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**LEE**(10) **Pub. No.: US 2021/0191507 A1**(43) **Pub. Date: Jun. 24, 2021**(54) **XR DEVICE AND METHOD FOR  
COTNROLLING THE SAME**(71) Applicant: **LG ELECTRONICS INC.**, Seoul  
(KR)(72) Inventor: **Daehwan LEE**, Seoul (KR)(73) Assignee: **LG ELECTRONICS INC.**, Seoul  
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(2013.01); **G06T 7/74** (2017.01); **B25J 19/023**  
(2013.01); **B25J 9/0003** (2013.01); **B25J**  
**11/0085** (2013.01); **B25J 9/1689** (2013.01)(57) **ABSTRACT**

The present disclosure relates to an XR device and a method for controlling the same, and more particularly, is applicable to a 5G communication technology field, a robot technology field, an autonomous technology field and an artificial intelligence (AI) technology field. The method for controlling an XR device comprises executing an augmented reality (AR) assistant application in the XR device by a user, displaying a real space, which includes a first real object, on a screen of the XR device, detecting a state of the first real object, displaying at least one virtual object for identifying the state of the first real object on the real space of the screen by overlapping the at least one virtual object on the real space, and controlling the state of the first real object by using one or more second real objects of the real space.

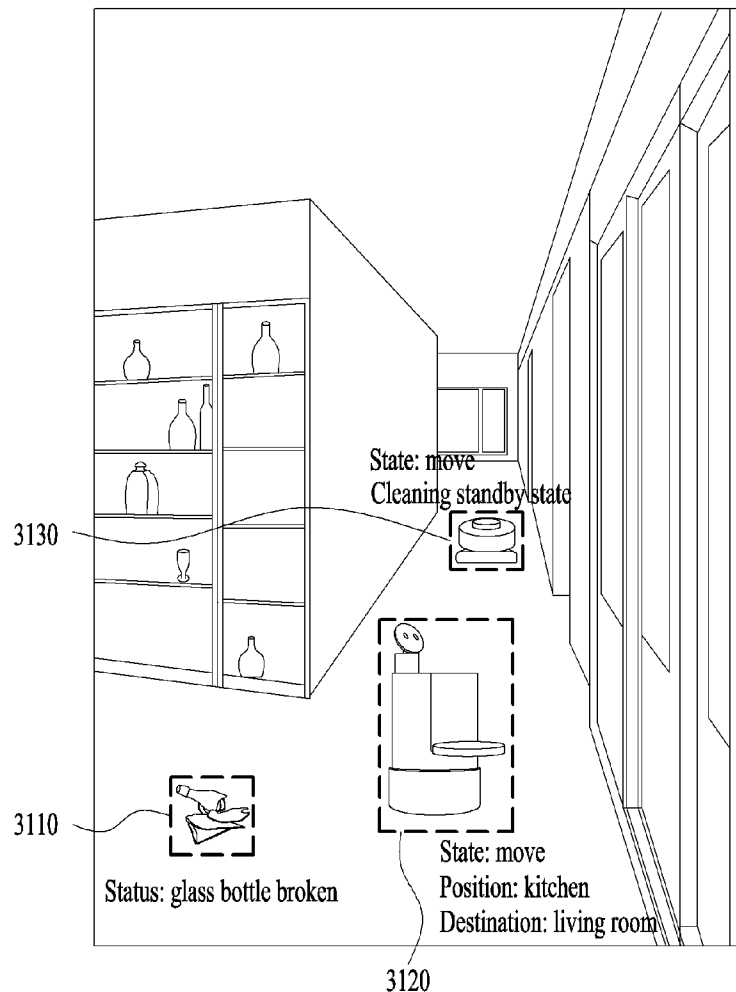


FIG. 1

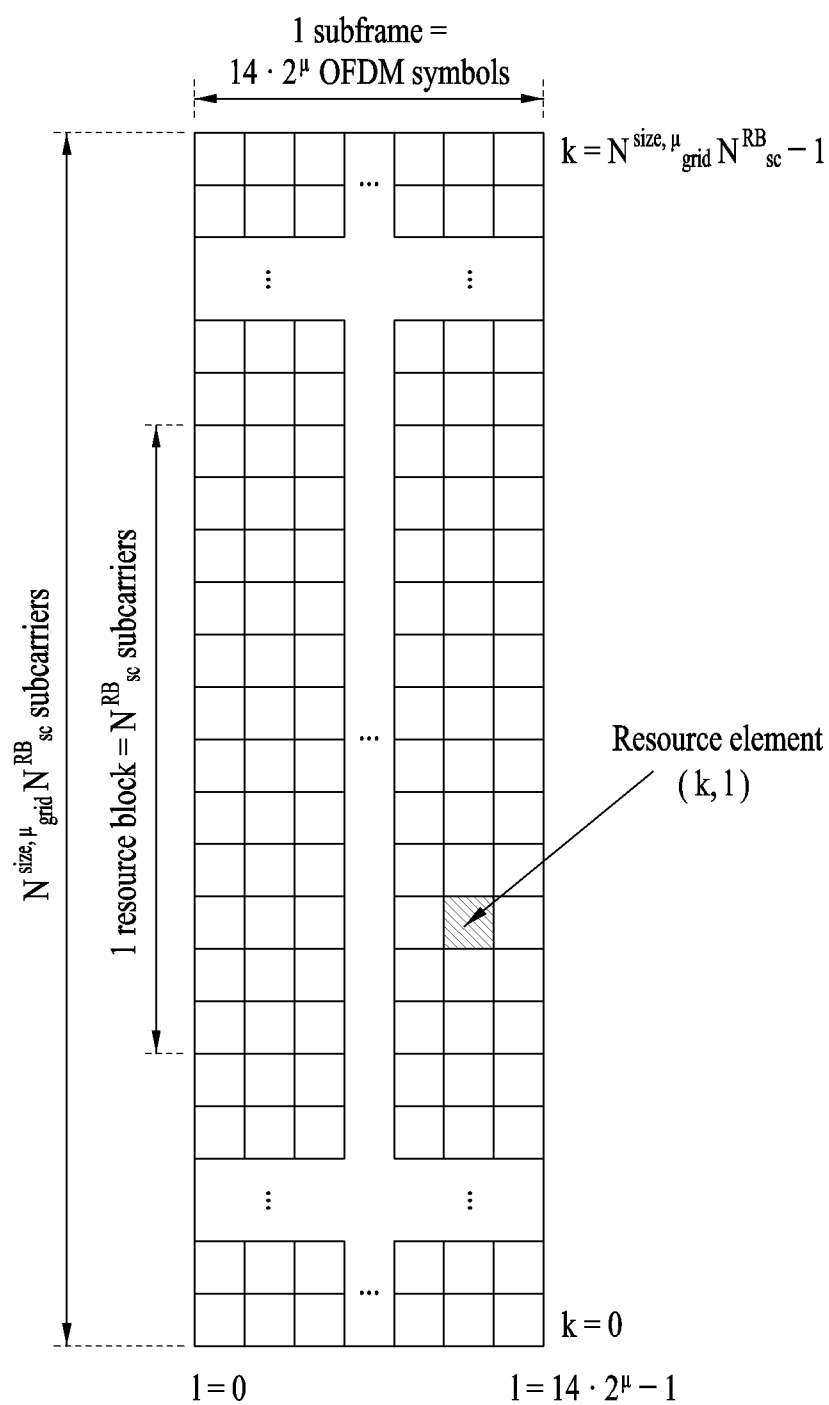


FIG. 2

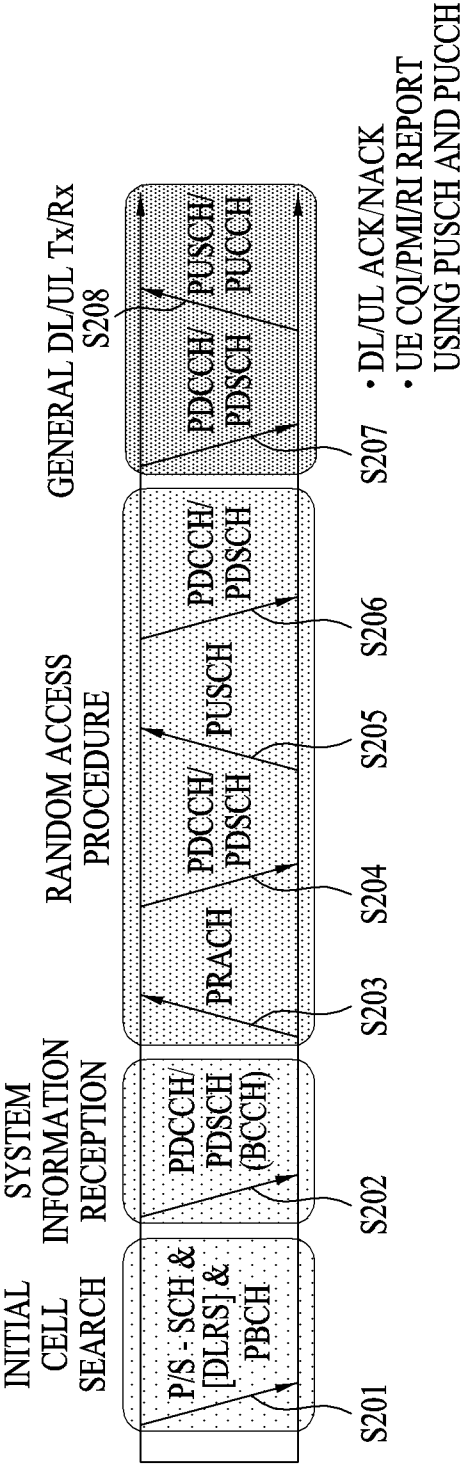


FIG. 3

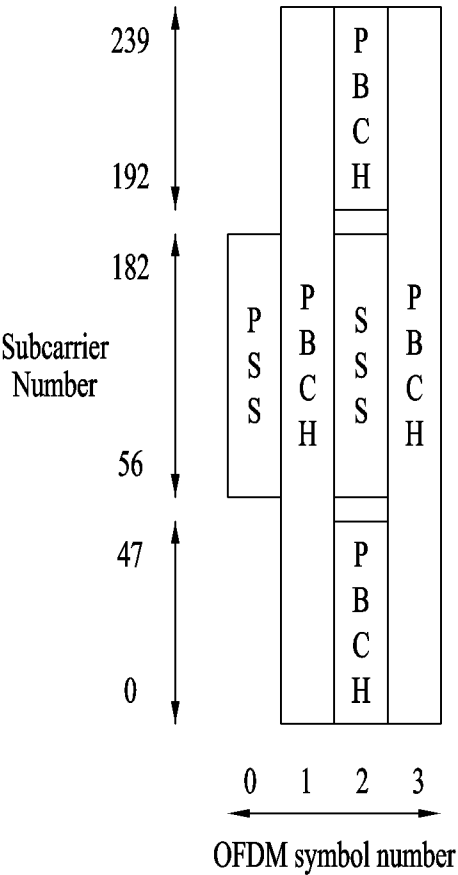


FIG. 4

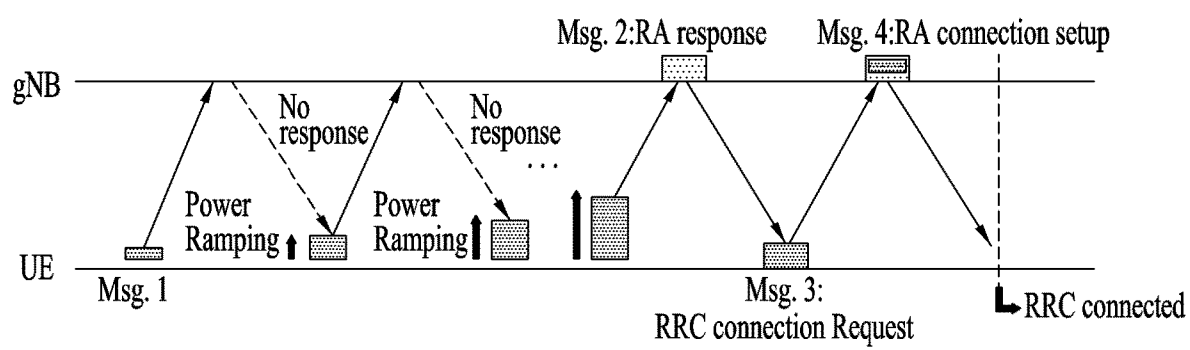


FIG. 5

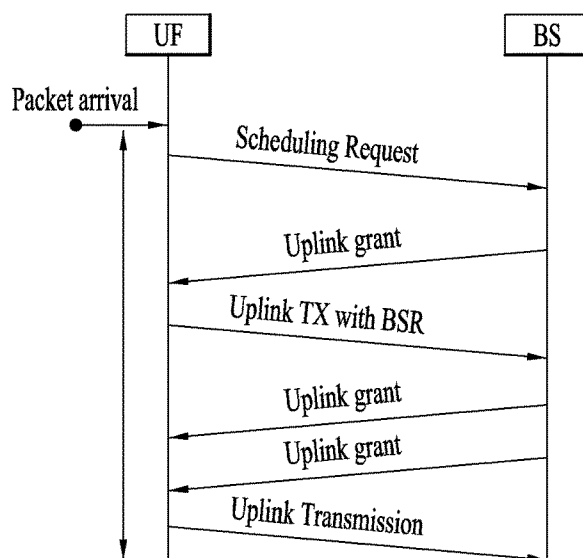


Fig. Uplink TX procedure with grant  
(a)

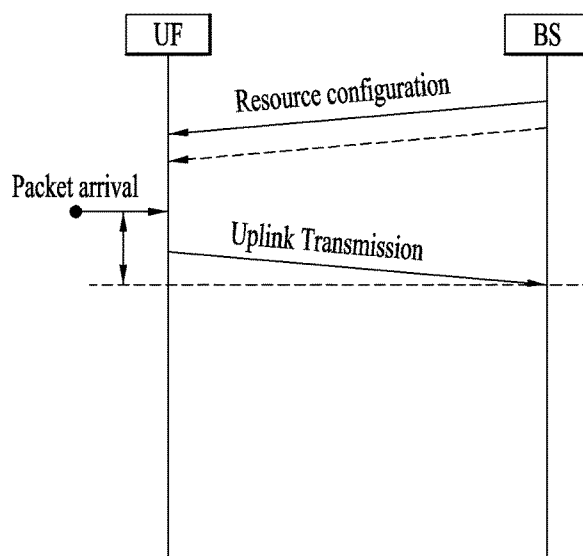


Fig. Uplink TX procedure without grant  
(b)

FIG. 6

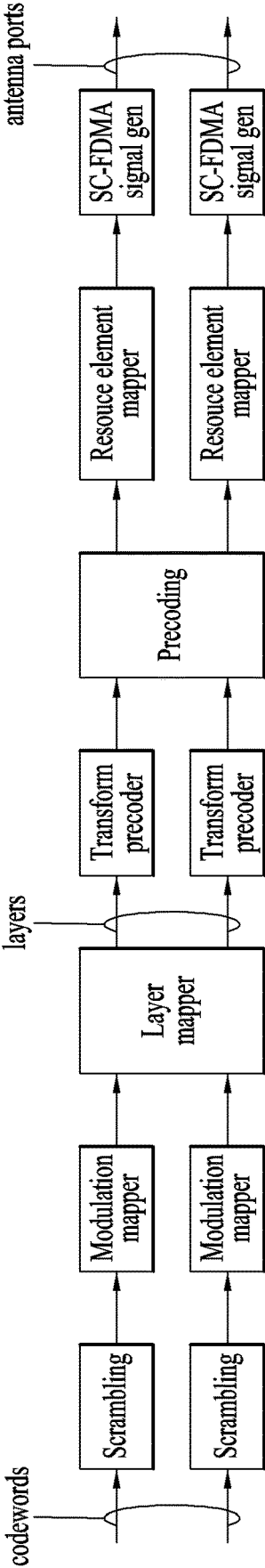
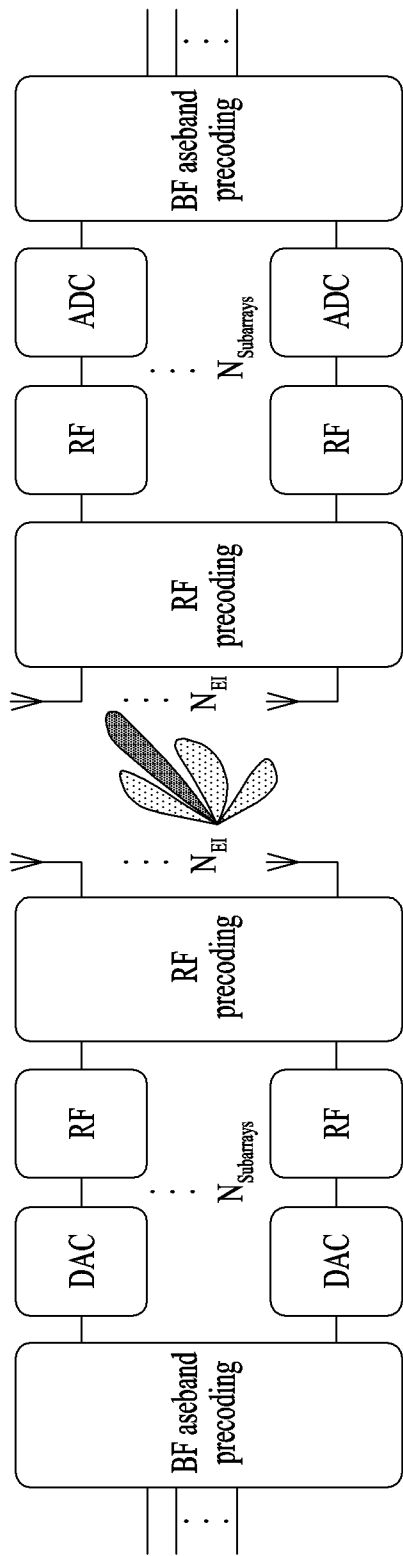


FIG. 7



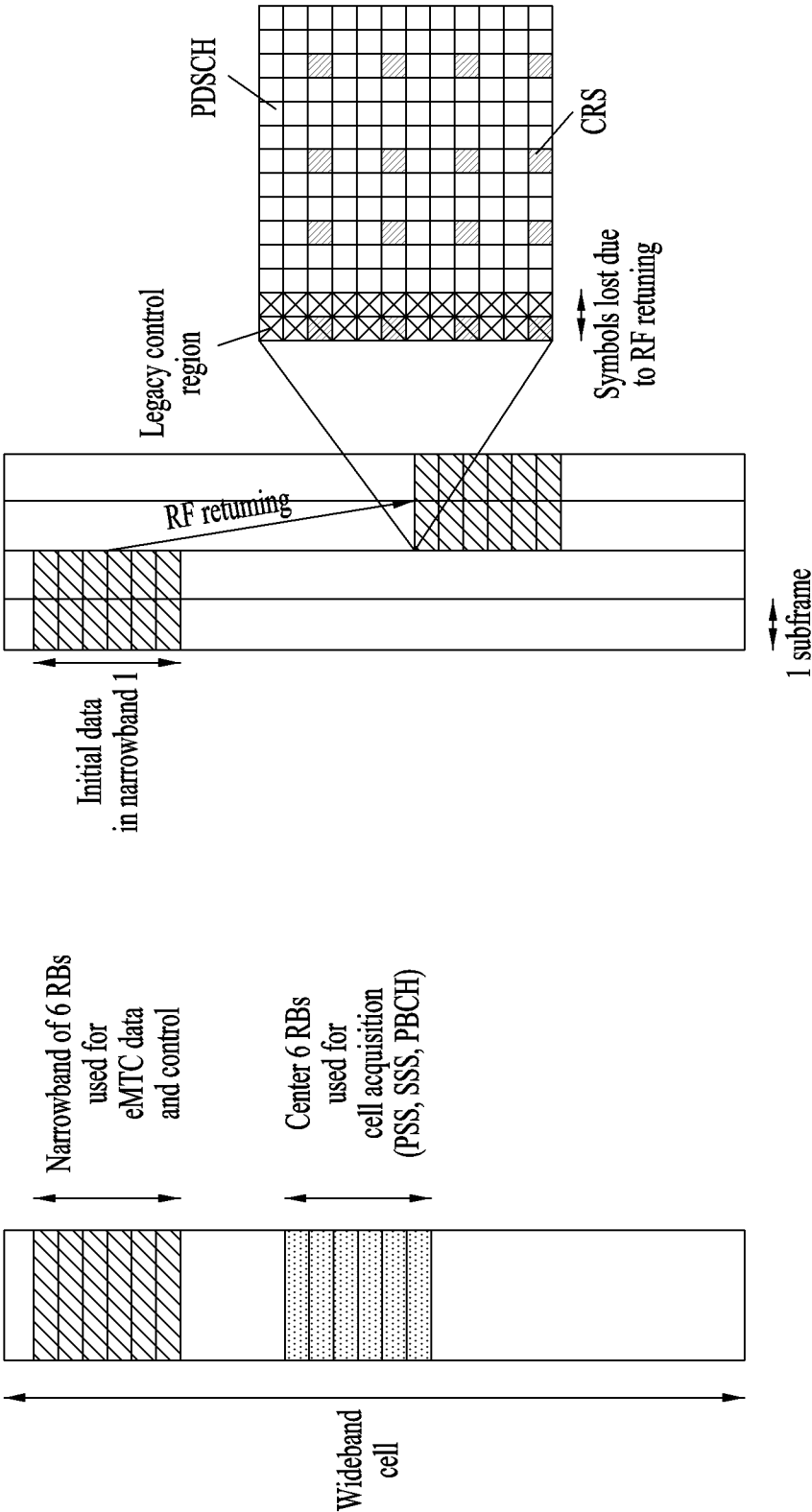


FIG. 8 (b)

FIG. 8(a)

FIG. 9

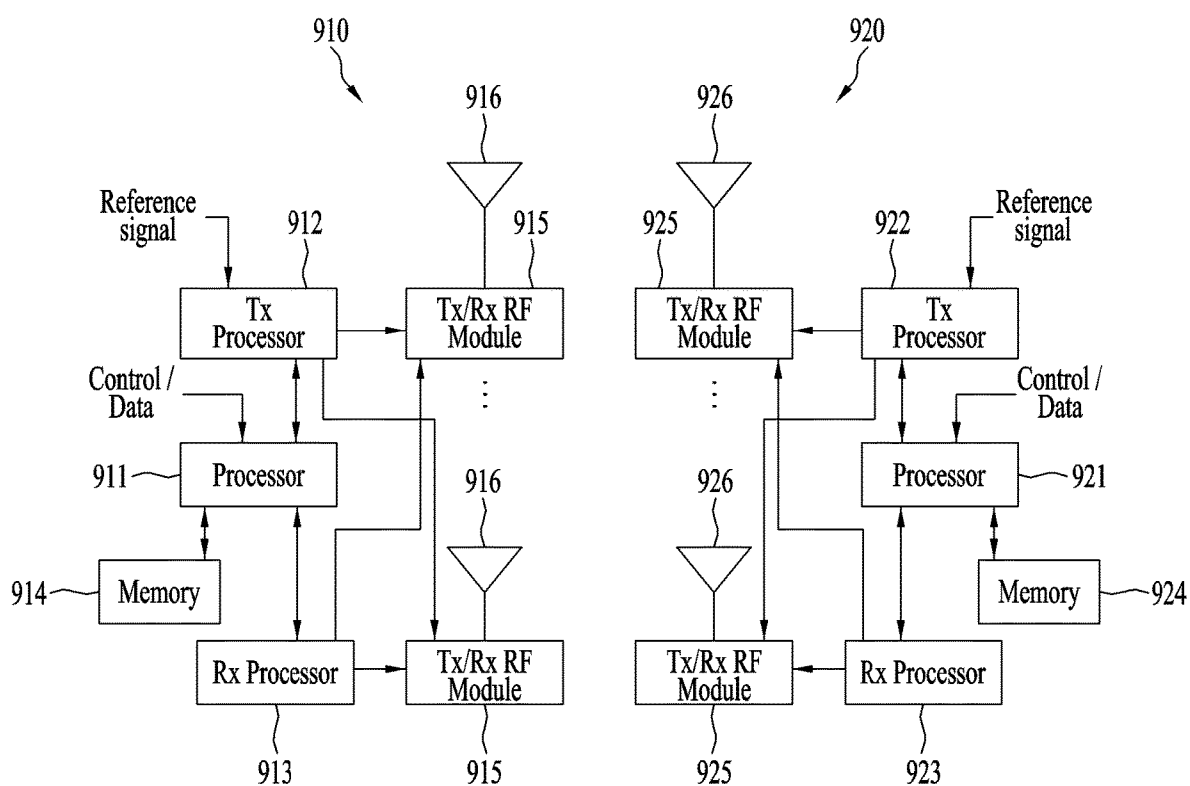


FIG. 10

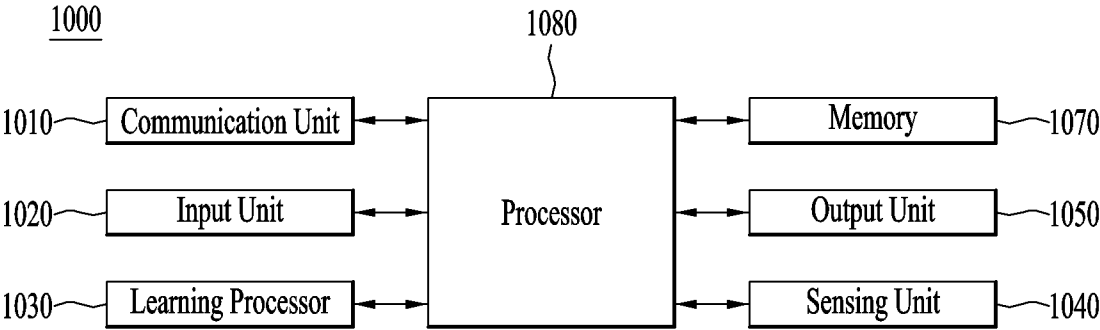


FIG. 11

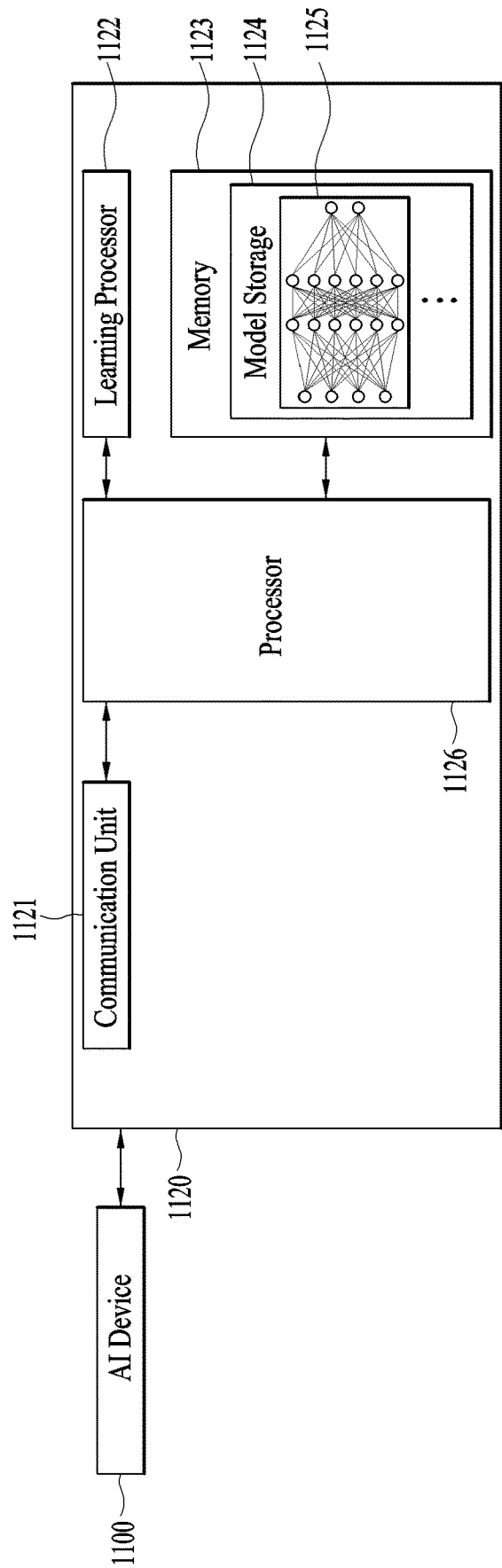


FIG. 12

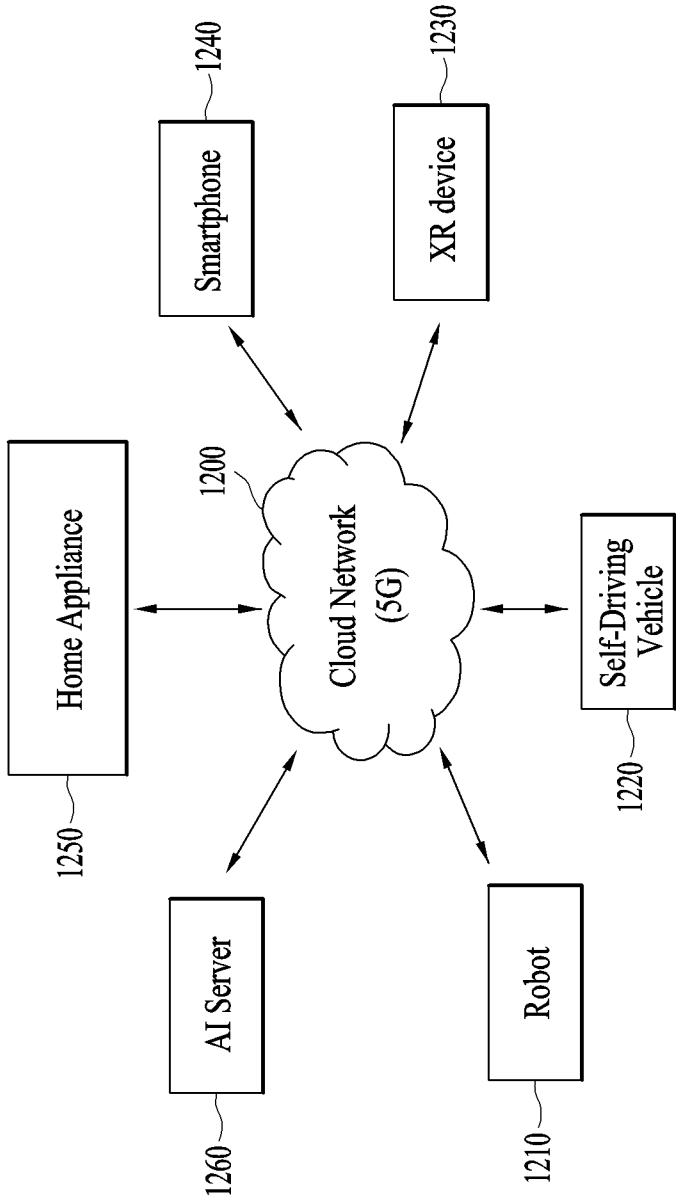


FIG. 13

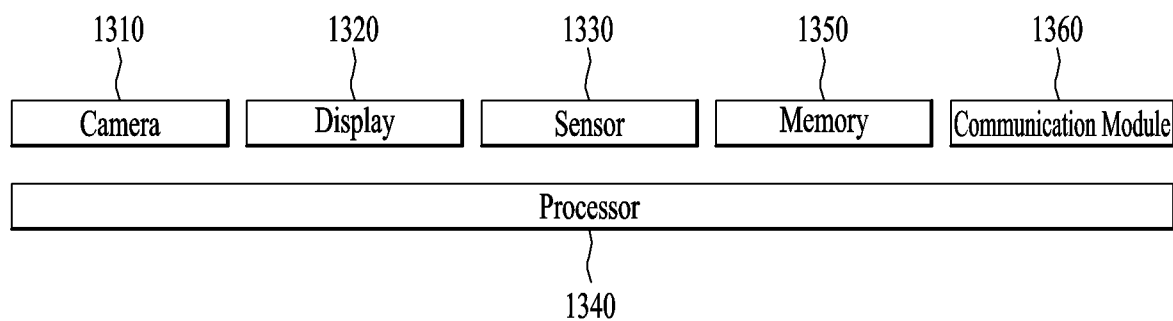


FIG. 14

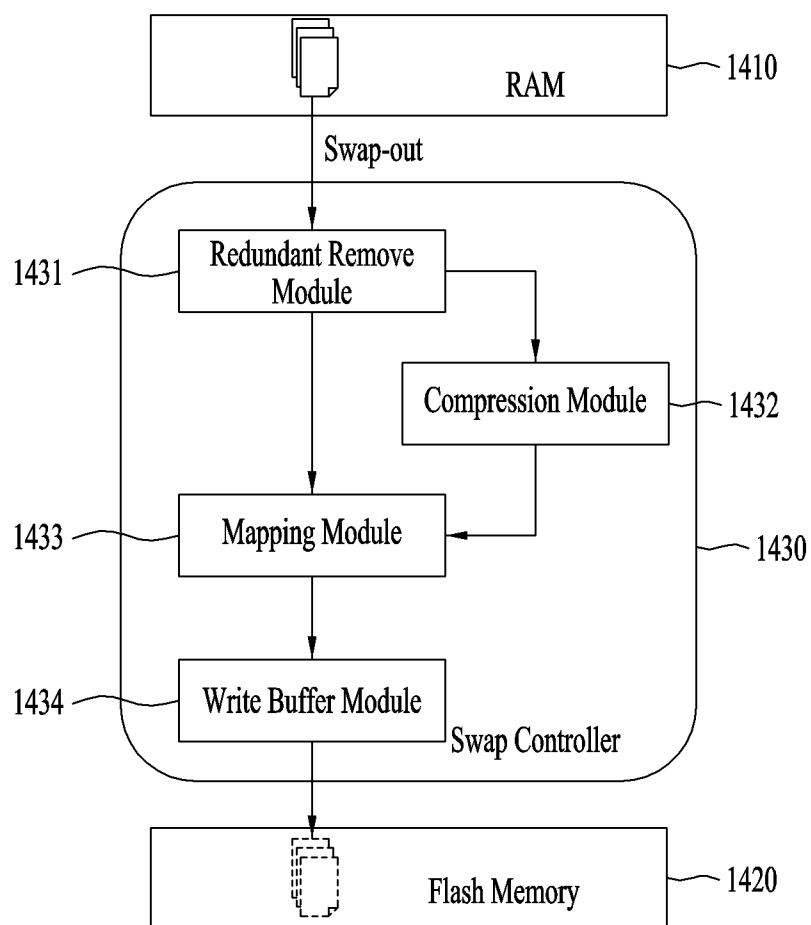


FIG. 15

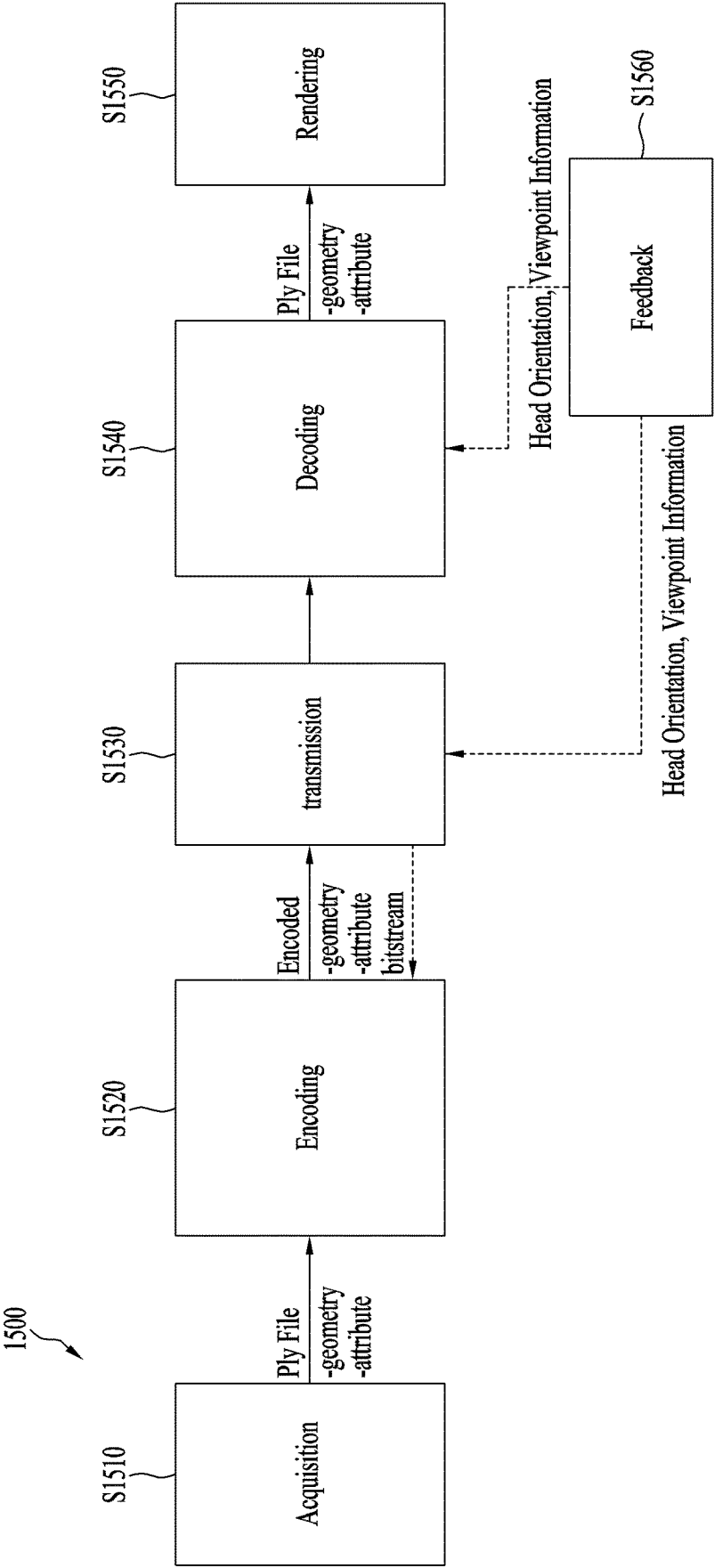


FIG. 16

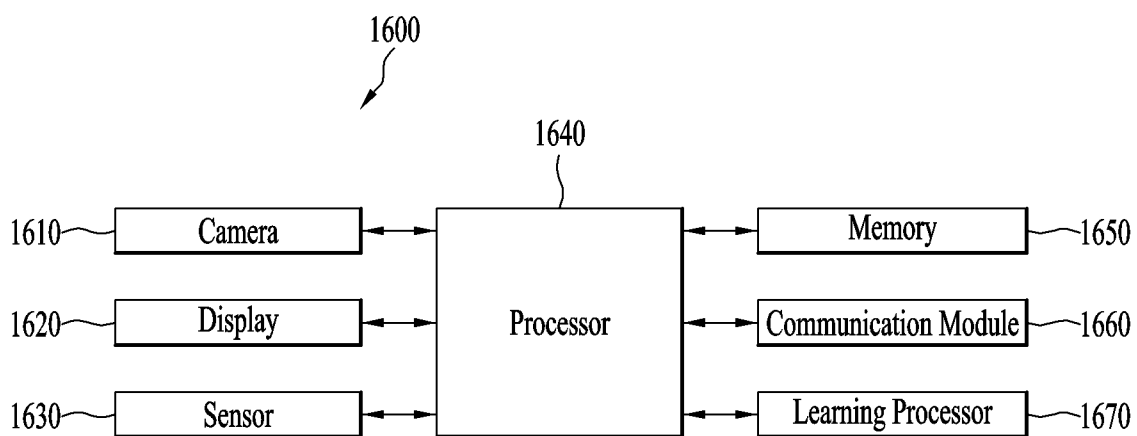


FIG. 17

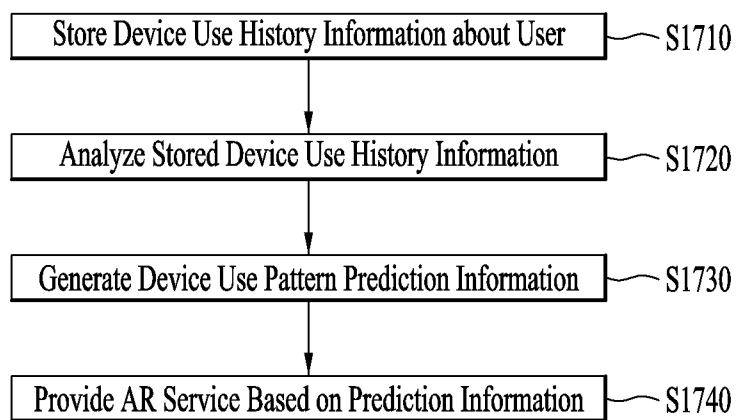


FIG. 18

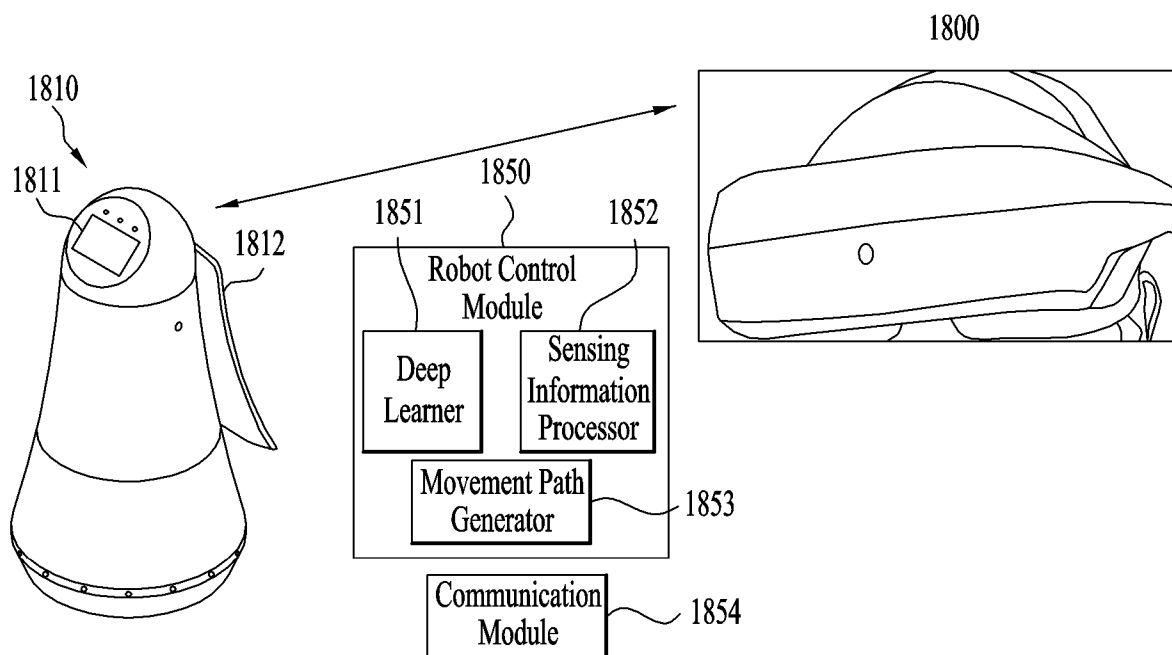


FIG. 19

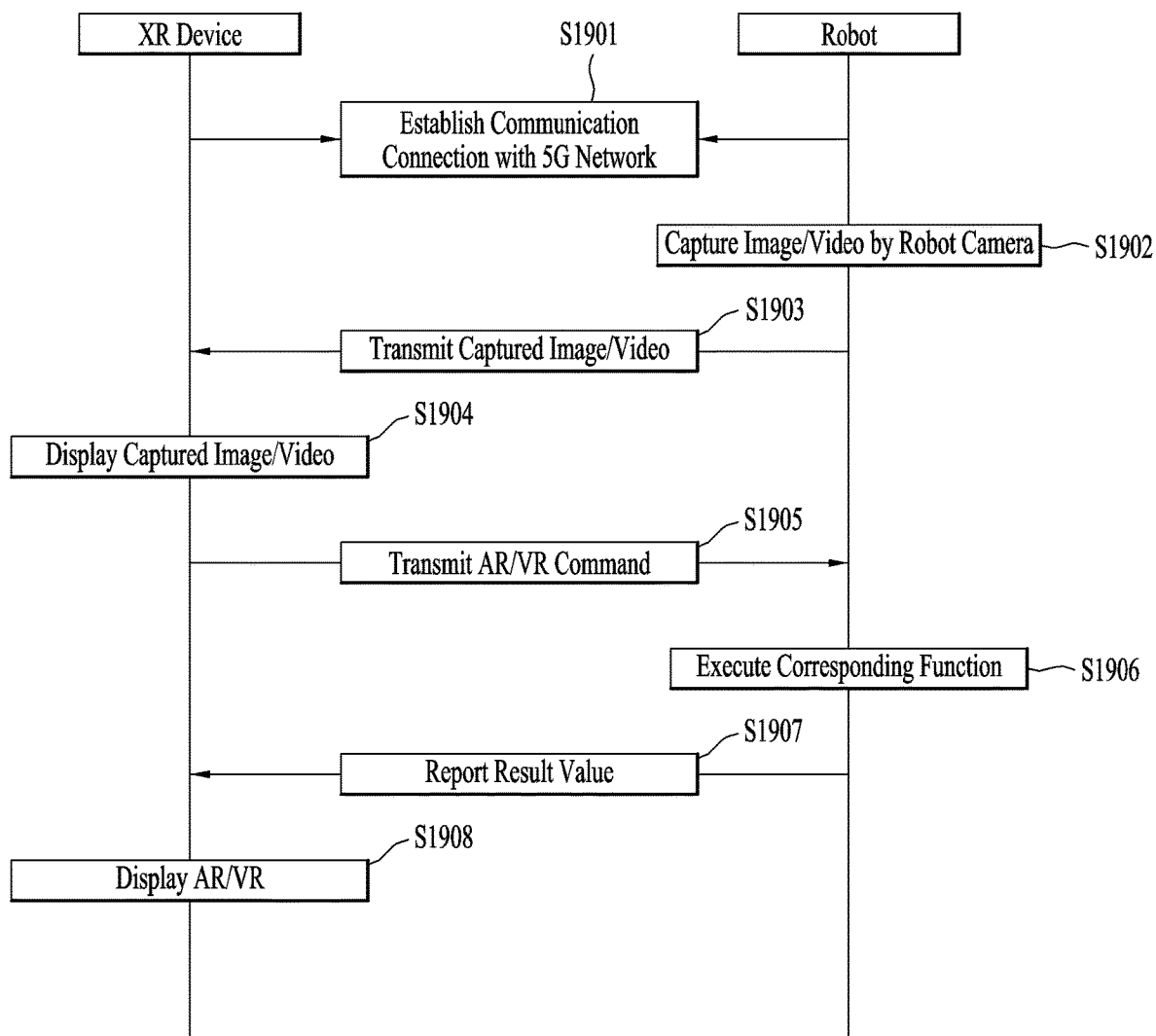


FIG. 20

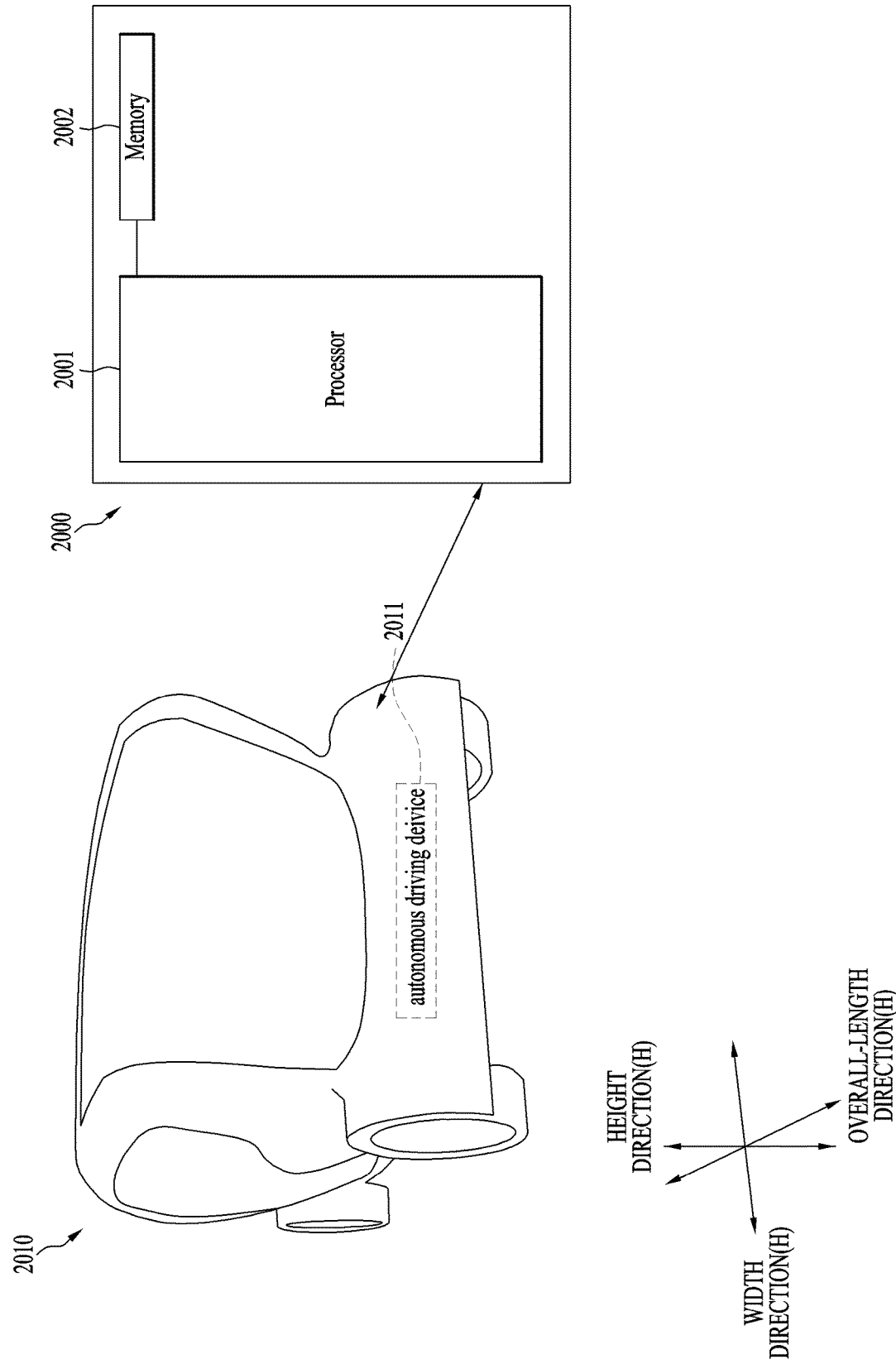


FIG. 21

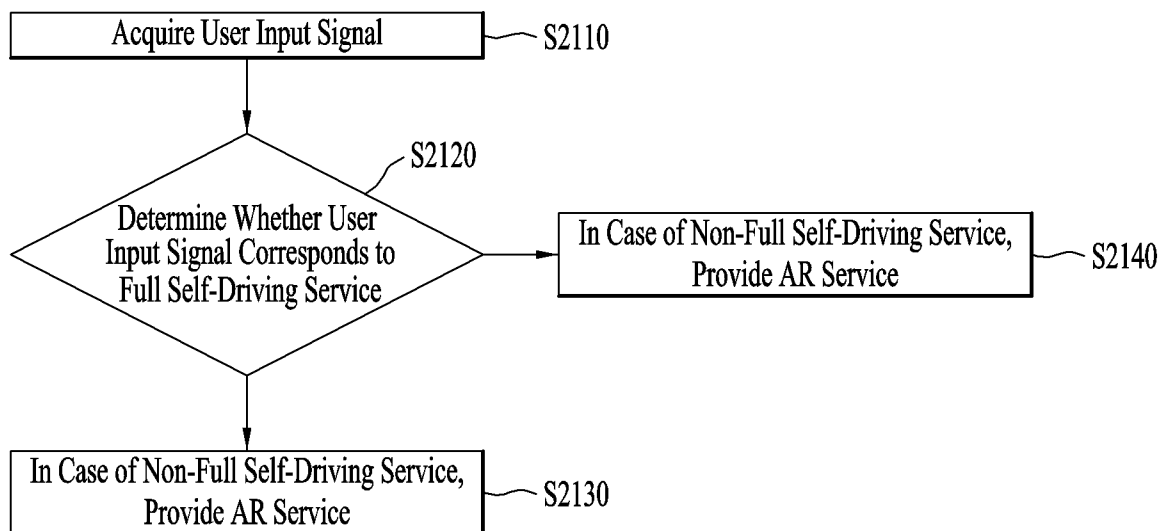


FIG. 22

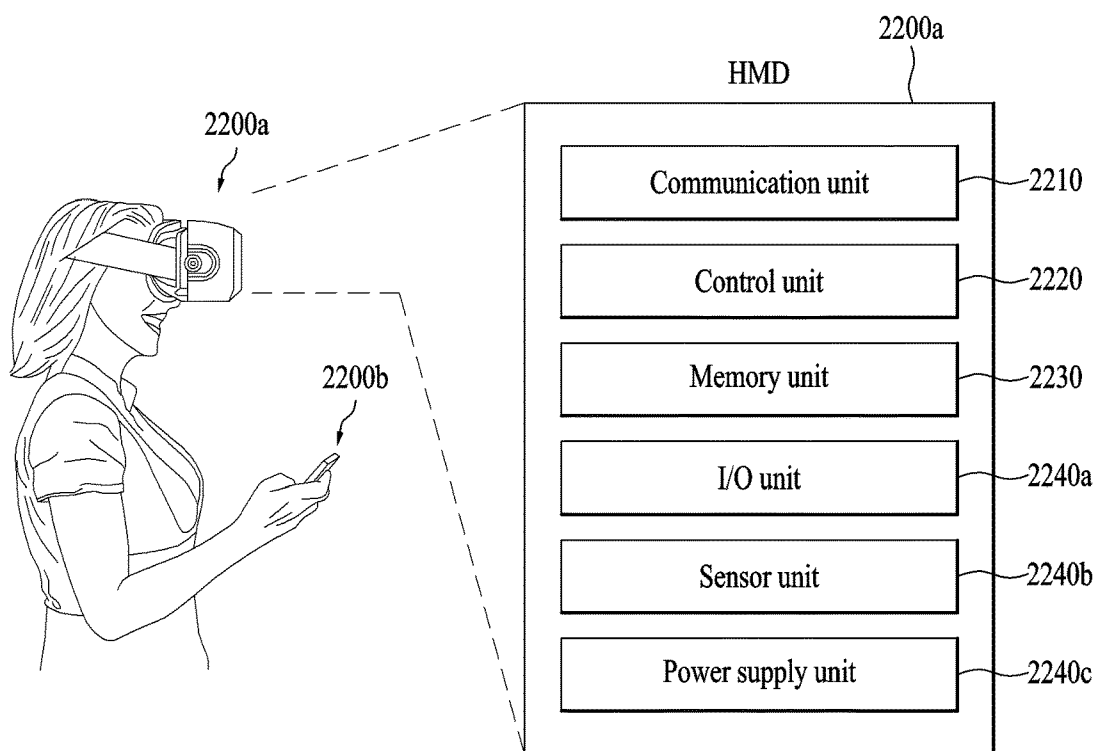


FIG. 23

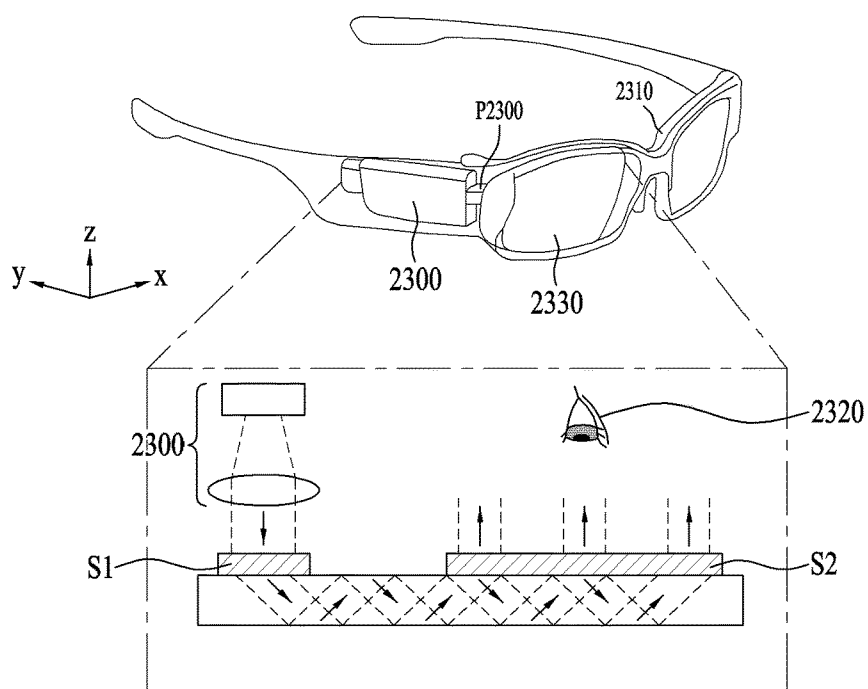


FIG. 24

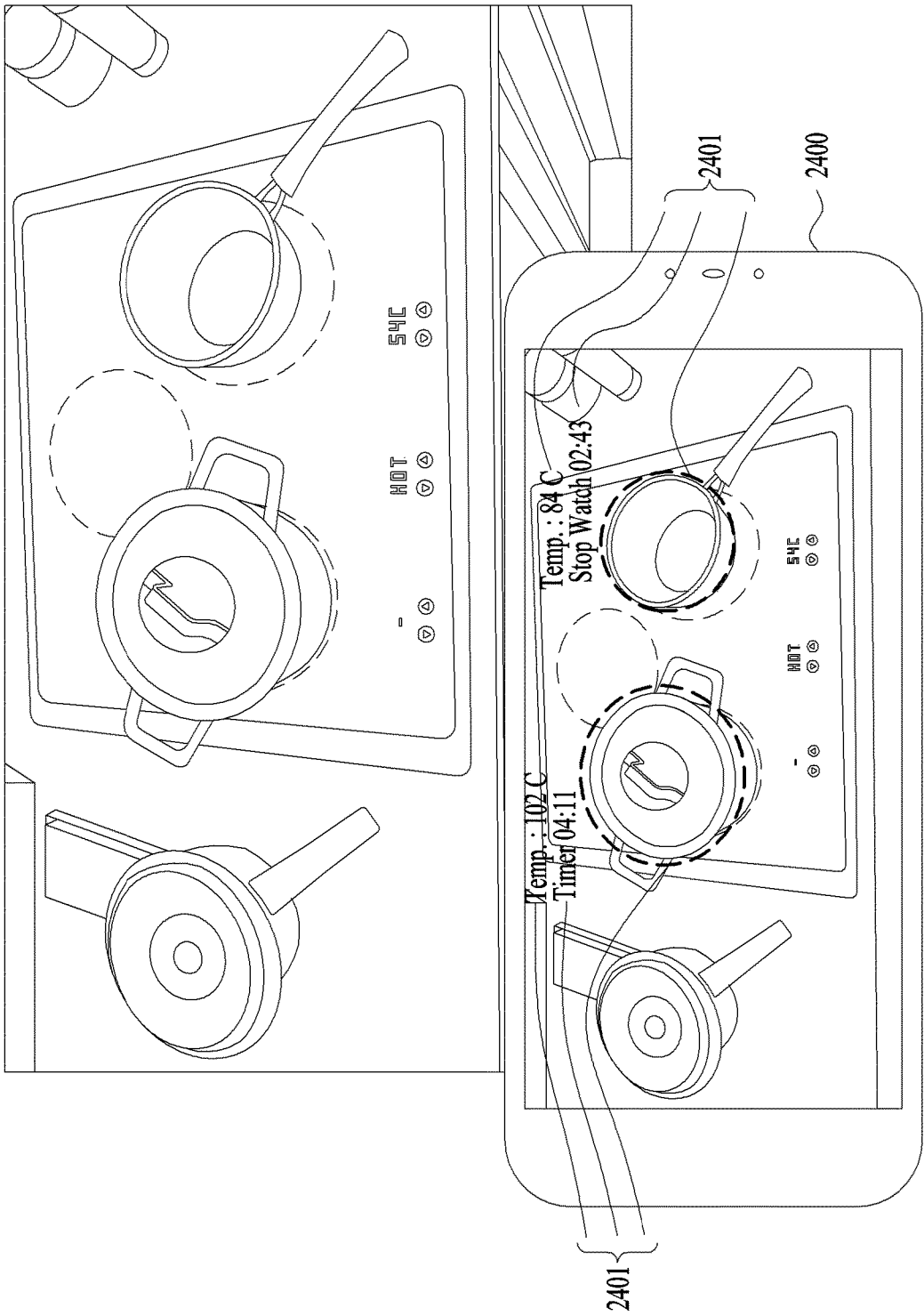


FIG. 25

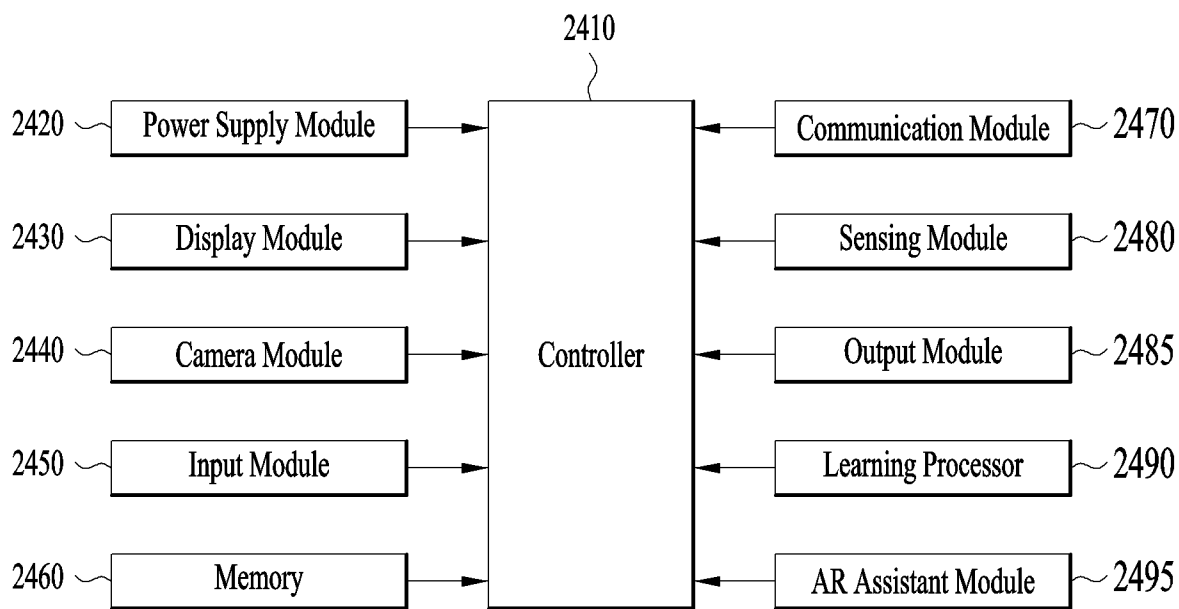


FIG. 26

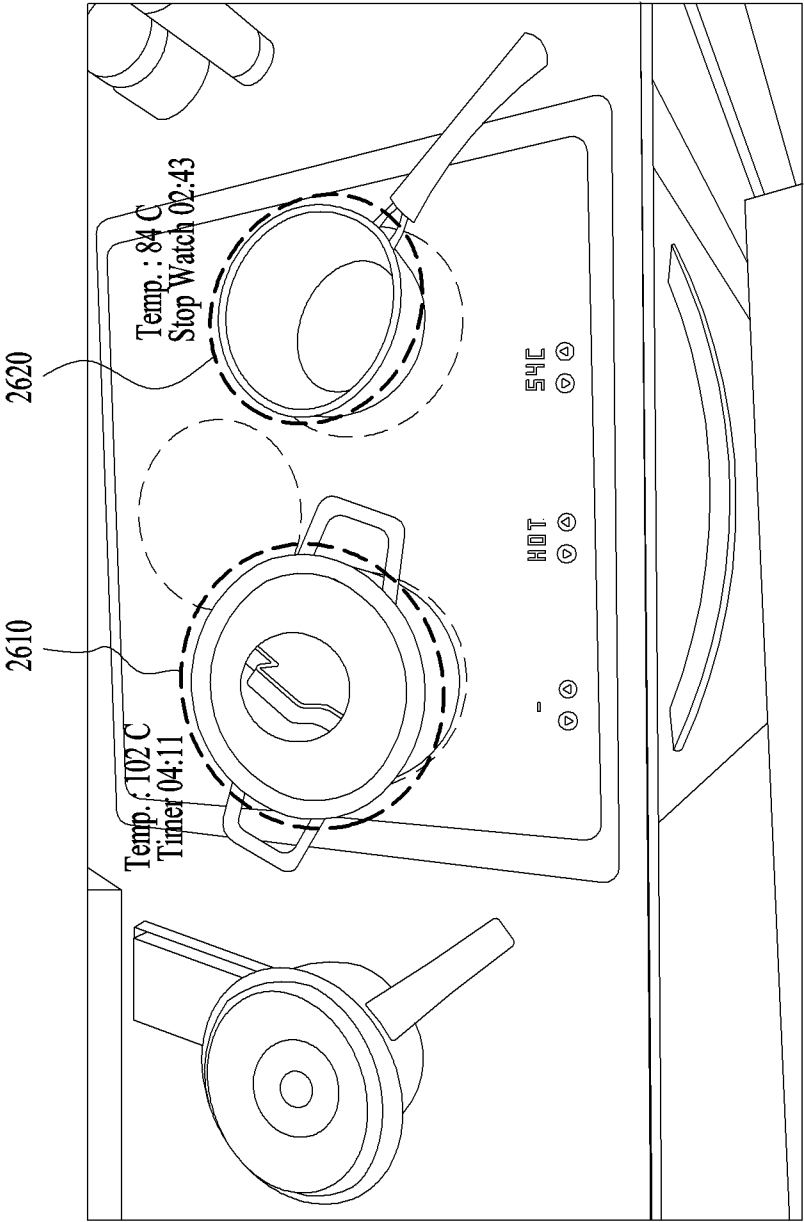


FIG. 27

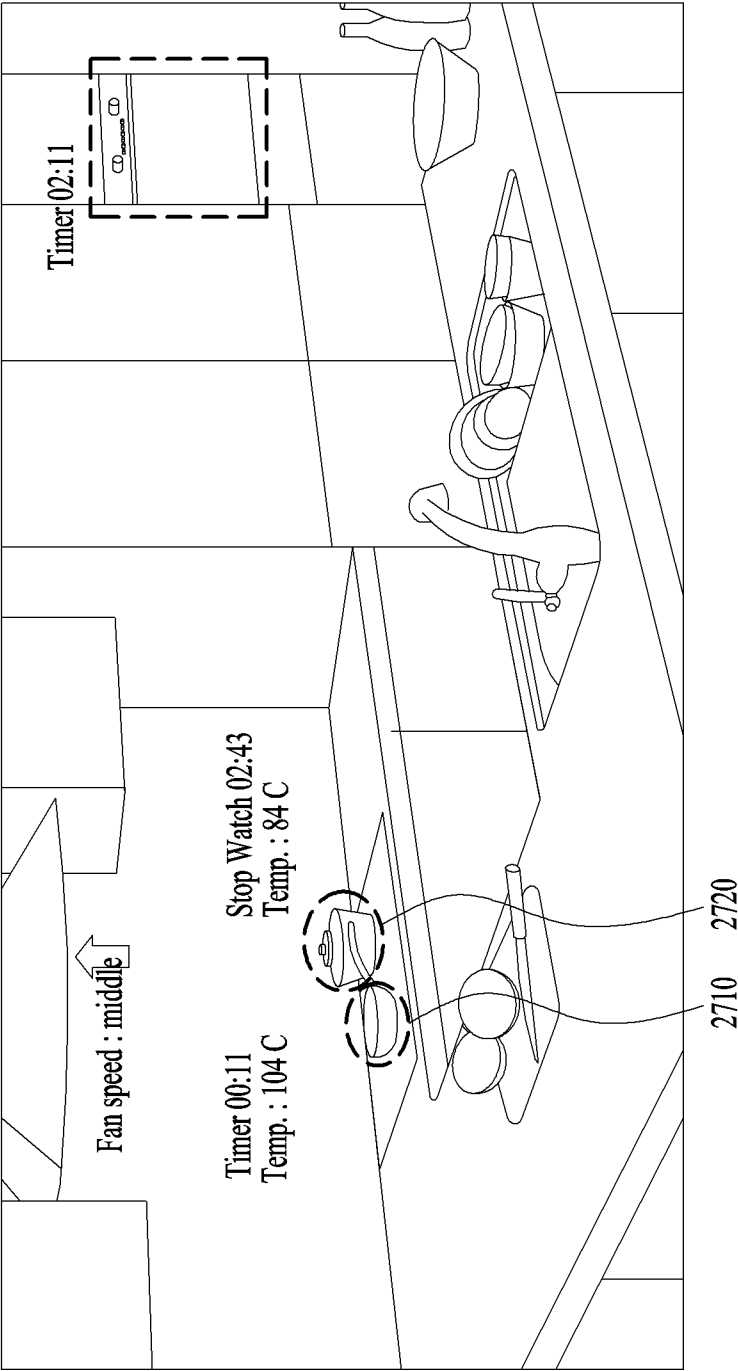


FIG. 28

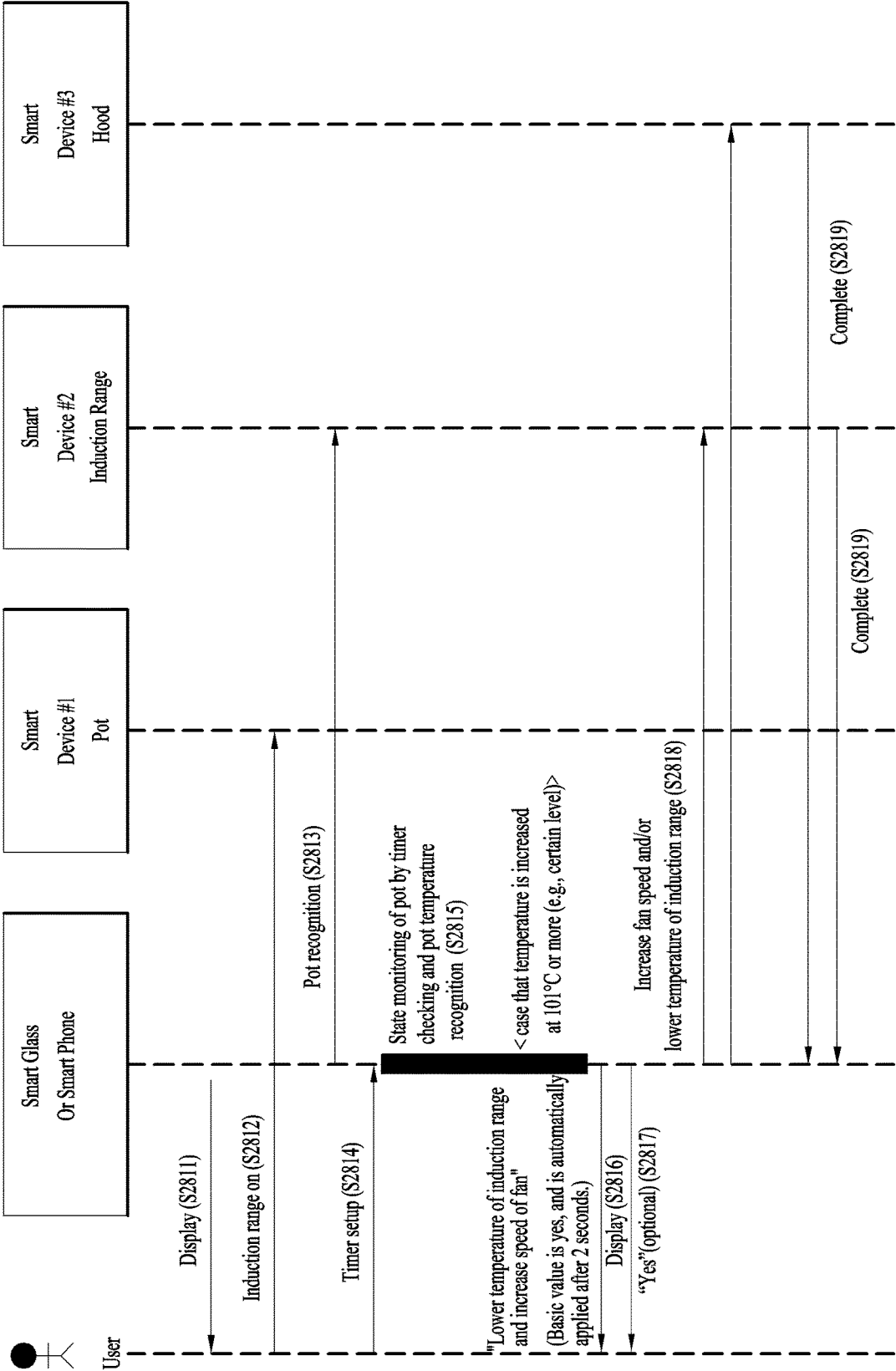


FIG. 29

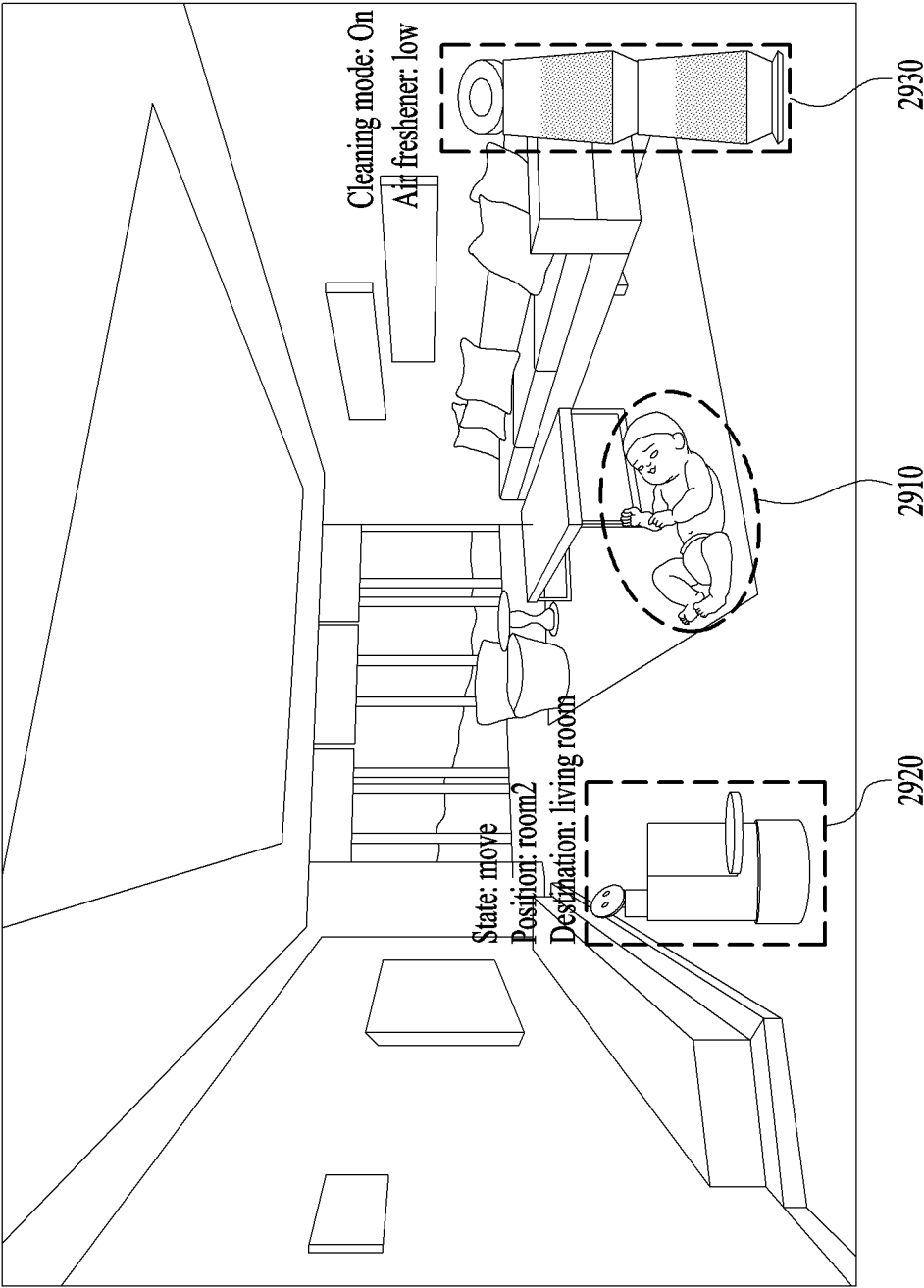


FIG. 30

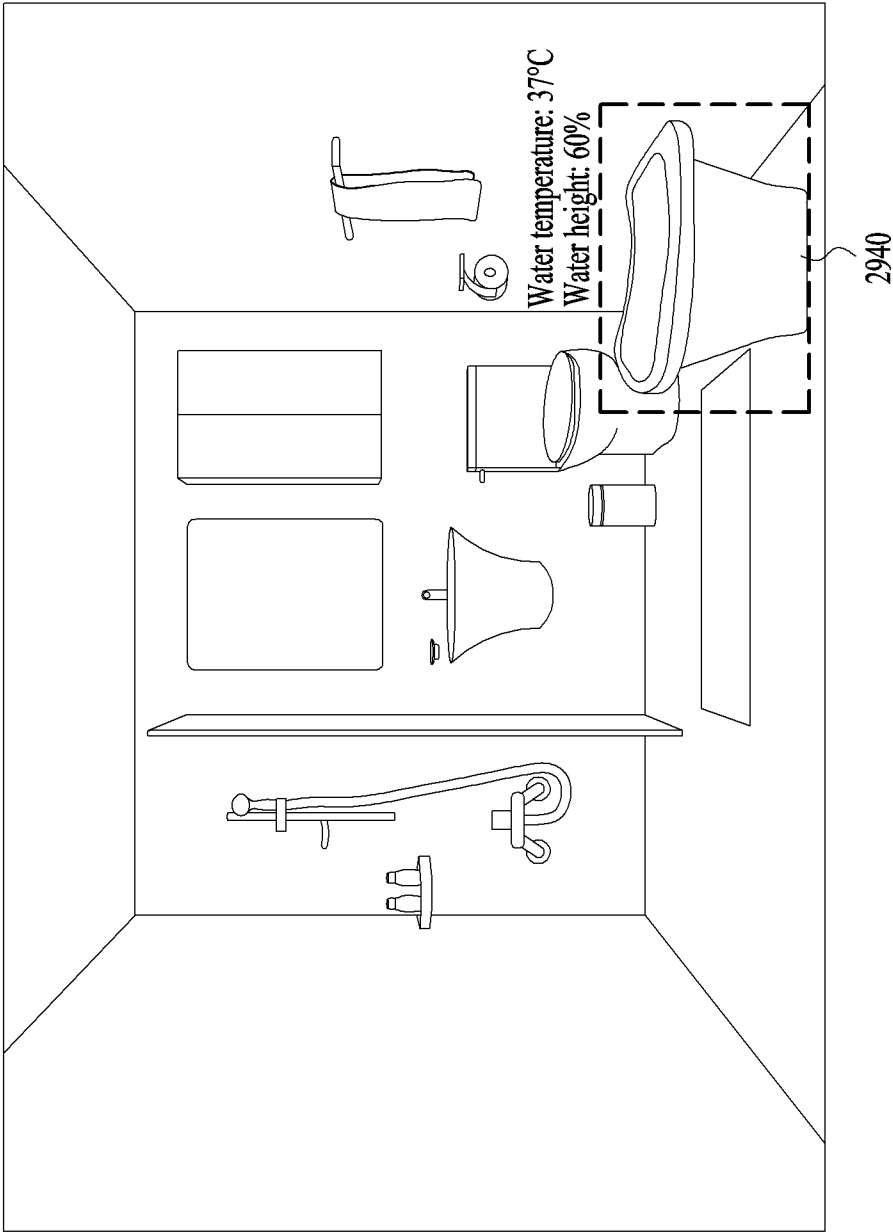
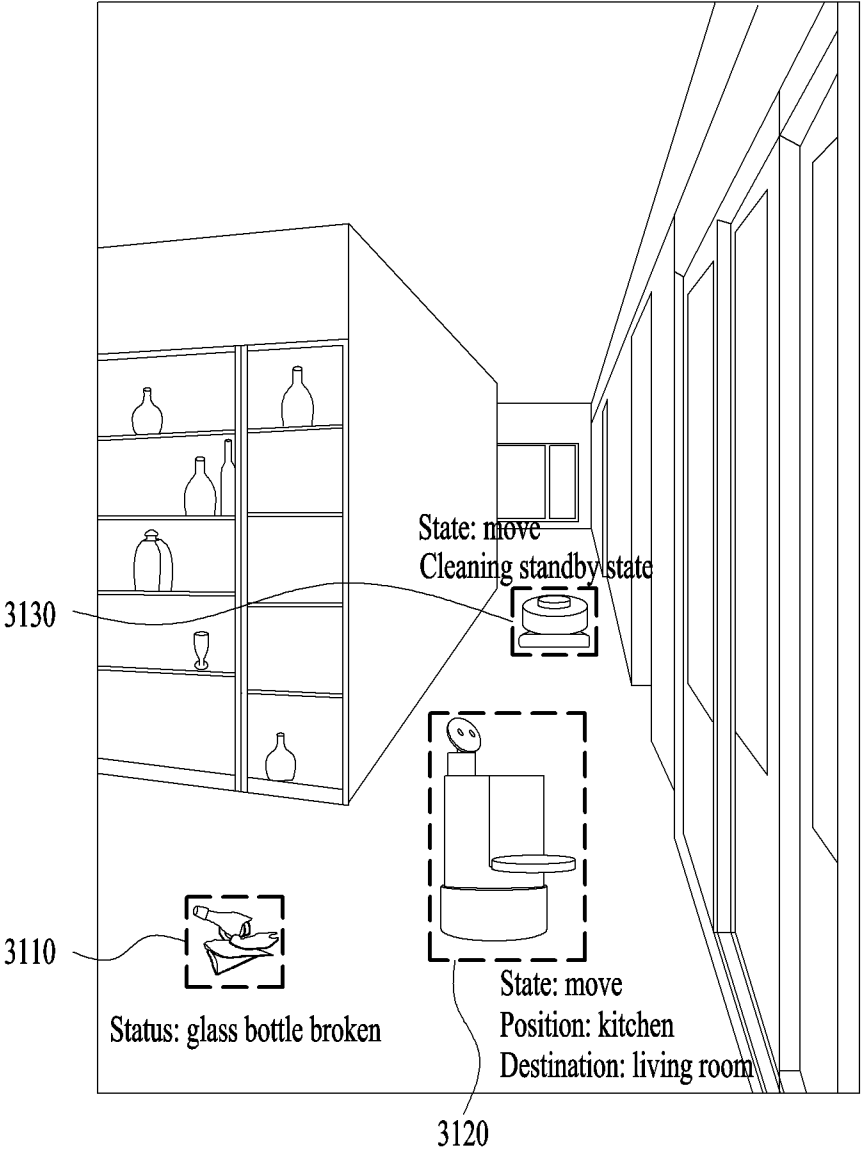


FIG. 31



## XR DEVICE AND METHOD FOR CONTROLLING THE SAME

[0001] This application claims the benefit of the Korean Patent Application No. 10-2019-0174506, filed on Dec. 24, 2019, which is hereby incorporated by reference as if fully set forth herein.

### BACKGROUND OF THE INVENTION

#### Field of the Invention

[0002] The present disclosure relates to an extended reality (XR) device for providing augmented reality (AR) mode and virtual reality (VR) mode and a method of controlling the same. More particularly, the present disclosure is applicable to all of the technical fields of 5th generation (5G) communication, robots, self-driving, and artificial intelligence (AI).

#### Discussion of the Related Art

[0003] Virtual reality (VR) simulates objects or a background in the real world only in computer graphic (CG) images. Augmented reality (AR) is an overlay of virtual CG images on images of objects in the real world. Mixed reality (MR) is a CG technology of merging the real world with virtual objects. All of VR, AR and MR are collectively referred to shortly as extended reality (XR).

[0004] Meanwhile, for convenience and concentration, a user desires to control a state of a specific real object of a real space viewed by an XR device by using another real object instead of directly controlling the state of the specific real object. However, although the XR device of the related art may display real objects of a real space on a screen, a problem occurs in that the XR device fails to control a specific real object of the real space by using another real object.

### SUMMARY OF THE INVENTION

[0005] Accordingly, the present disclosure is directed to an XR device and a method for controlling the same, which substantially obviate one or more problems due to limitations and disadvantages of the related art.

[0006] An object of the present disclosure is to provide an XR device and a method for controlling the same, in which a state of a specific object of a real space displayed in the XR device is able to be controlled using another real object.

[0007] Another object of the present disclosure is to provide an XR device and a method for controlling the same, in which a state of a specific object of a real space displayed in the XR device is guided using a virtual object and therefore controlled by another real object.

[0008] In addition to the objects of the present disclosure as mentioned above, additional objects and features of the present disclosure will be clearly understood by those skilled in the art from the following description of the present disclosure.

[0009] To achieve these objects and other advantages and in accordance with the purpose of the disclosure, as embodied and broadly described herein, a method of controlling an extended reality (XR) device according to one aspect of the present disclosure comprises executing an augmented reality (AR) assistant application in the XR device by a user, displaying a real space, which includes a first real object, on a screen of the XR device, detecting a state of the first real

object, displaying at least one virtual object for identifying the state of the first real object on the real space of the screen by overlapping the at least one virtual object on the real space, and controlling the state of the first real object by using one or more second real objects of the real space.

[0010] In one embodiment, the method further comprises displaying at least one virtual object on the real space of the screen by overlapping the at least one virtual object on the real space, so as to provide a guide for controlling the state of the first real object.

[0011] In one embodiment, if the first real object is a pot which is cooking, the one or more second real objects include at least one of an induction range of the pot and a fan provided in a hood.

[0012] In one embodiment, the controlling the first real object includes controlling a temperature of the pot by using at least one of a temperature control of the induction range and a speed control of the fan.

[0013] In one embodiment, if the temperature of the pot exceeds 100° C., the temperature of the pot is controlled by lowering a temperature of the induction range or increasing a speed of the fan.

[0014] In one embodiment, if the first real object is a diaper containing a poop, the one or more second real objects include at least one of a robot and an air cleaner.

[0015] In one embodiment, the controlling the first real object includes transmitting a current position of a real space where the diaper containing the poop exists and a command to bring poop disposable goods to the current position to the robot, and transmitting a command to power on an air cleaning function to the air cleaner.

[0016] In one embodiment, the one or more second real objects further include a bathtub, and the controlling the first real object includes transmitting a command to fill water in the bathtub, the command including a temperature of the water to be filled in the bathtub and height information of the water.

[0017] In one embodiment, if the first real object corresponds to broken glass pieces existing in a specific position of a real space, the one or more second real objects include at least one of a robot and a robot cleaner.

[0018] In one embodiment, the controlling the first real object includes transmitting a current position of a real space where the broken glass pieces exist and a command to bring cleaning tools to the current position to the robot, and transmitting a command to clean the broken glass pieces to the robot cleaner.

[0019] In another aspect of the present disclosure, an XR device comprises an AR assistant module executing an augmented reality (AR) assistant application if the AR assistant application is selected by a user, a camera module acquiring a real space that includes a first real object, and a display module displaying the real space that includes the first real object, wherein the AR assistant module detects a state of the first real object, displays at least one virtual object for identifying the state of the first real object on the real space of the display module by overlapping the at least one virtual object on the real space, and controls the state of the first real object by using one or more second real objects of the real space.

[0020] In one embodiment, the AR assistant module displays at least one virtual object on the real space of the

display module by overlapping the at least one virtual object on the real space, so as to provide a guide for controlling the state of the first real object.

**[0021]** In one embodiment, if the first real object is a pot which is cooking, the one or more second real objects include at least one of an induction range of the pot and a fan provided in a hood.

**[0022]** In one embodiment, the AR assistant module controls a temperature of the pot by using at least one of a temperature control of the induction range and a speed control of the fan.

**[0023]** In one embodiment, if the temperature of the pot exceeds 100° C., the AR assistant module controls the temperature of the pot by lowering a temperature of the induction range or increasing a speed of the fan.

**[0024]** In one embodiment, if the first real object is a diaper containing a poop, the one or more second real objects include at least one of a robot and an air cleaner.

**[0025]** In one embodiment, the AR assistant module transmits a current position of a real space where the diaper containing the poop exists and a command to bring poop disposable goods to the current position to the robot, and transmits a command to power on an air cleaning function to the air cleaner.

**[0026]** In one embodiment, the one or more second real objects further include a bathtub, and the AR assistant module transmits a command to fill water in the bathtub, the command including a temperature of the water to be filled in the bathtub and height information of the water.

**[0027]** In one embodiment, if the first real object corresponds to broken glass pieces existing in a specific position of a real space, the one or more second real objects include at least one of a robot and a robot cleaner.

**[0028]** In one embodiment, the AR assistant module transmits a current position of a real space where the broken glass pieces exists and a command to bring cleaning tools to the current position to the robot, and transmits a command to clean the broken glass pieces to the robot cleaner.

**[0029]** In the XR device and the method for controlling the same according to the embodiments of the present disclosure, a state of a specific real object of a real space displayed in the XR device is able to be controlled using another real object, whereby a user's desire to control the state of the specific real object of the real space viewed by the XR device by using another real object may be fulfilled.

**[0030]** Also, the state of the specific real object of the real space displayed in the XR device may be controlled using another real object, whereby a user may control another state of the specific real object, which is not controlled by the XR device. Therefore, concentration of a task and a processing speed of the task may be enhanced, and the amount of the task processed at the same time may be increased.

#### BRIEF DESCRIPTION OF THE DRAWINGS

**[0031]** The accompanying drawings, which are included to provide a further understanding of the disclosure and are incorporated in and constitute a part of this application, illustrate embodiment(s) of the disclosure and together with the description serve to explain the principle of the disclosure. In the drawings:

**[0032]** FIG. 1 is a diagram illustrating an exemplary resource grid to which physical signals/channels are mapped in a 3rd generation partnership project (3GPP) system;

**[0033]** FIG. 2 is a diagram illustrating an exemplary method of transmitting and receiving 3GPP signals;

**[0034]** FIG. 3 is a diagram illustrating an exemplary structure of a synchronization signal block (SSB);

**[0035]** FIG. 4 is a diagram illustrating an exemplary random access procedure;

**[0036]** FIG. 5 is a diagram illustrating exemplary uplink (UL) transmission based on a UL grant;

**[0037]** FIG. 6 is a conceptual diagram illustrating exemplary physical channel processing;

**[0038]** FIG. 7 is a block diagram illustrating an exemplary transmitter and receiver for hybrid beamforming;

**[0039]** FIG. 8(a) is a diagram illustrating an exemplary narrowband operation, and FIG. 8(b) is a diagram illustrating exemplary machine type communication (MTC) channel repetition with radio frequency (RF) retuning;

**[0040]** FIG. 9 is a block diagram illustrating an exemplary wireless communication system to which proposed methods according to the present disclosure are applicable;

**[0041]** FIG. 10 is a block diagram illustrating an artificial intelligence (AI) device 100 according to an embodiment of the present disclosure;

**[0042]** FIG. 11 is a block diagram illustrating an AI server 200 according to an embodiment of the present disclosure;

**[0043]** FIG. 12 is a diagram illustrating an AI system 1 according to an embodiment of the present disclosure;

**[0044]** FIG. 13 is a block diagram illustrating an extended reality (XR) device according to embodiments of the present disclosure;

**[0045]** FIG. 14 is a detailed block diagram illustrating a memory illustrated in FIG. 13;

**[0046]** FIG. 15 is a block diagram illustrating a point cloud data processing system;

**[0047]** FIG. 16 is a block diagram illustrating a device including a learning processor;

**[0048]** FIG. 17 is a flowchart illustrating a process of providing an XR service by an XR device 1600 of the present disclosure, illustrated in FIG. 16;

**[0049]** FIG. 18 is a diagram illustrating the outer appearances of an XR device and a robot;

**[0050]** FIG. 19 is a flowchart illustrating a process of controlling a robot by using an XR device;

**[0051]** FIG. 20 is a diagram illustrating a vehicle that provides a self-driving service;

**[0052]** FIG. 21 is a flowchart illustrating a process of providing an augmented reality/virtual reality (AR/VR) service during a self-driving service in progress;

**[0053]** FIG. 22 is a view showing an embodiment of an XR device of an HMD type according to the present disclosure;

**[0054]** FIG. 23 is a view showing an embodiment of an XR device of XR glasses type according to the present disclosure;

**[0055]** FIG. 24 illustrates an XR device of a mobile terminal type according to one embodiment of the present disclosure;

**[0056]** FIG. 25 is a schematic block diagram illustrating one embodiment of an XR device according to the present disclosure;

**[0057]** FIG. 26 illustrates one embodiment for controlling a state of a specific real object of a real space displayed on an XR device according to the present disclosure;

**[0058]** FIG. 27 illustrates another embodiment for controlling a state of a specific real object of a real space displayed on an XR device according to the present disclosure;

**[0059]** FIG. 28 is a flow chart illustrating one embodiment for controlling a state of a specific real object of a real space displayed on an XR device according to the present disclosure;

**[0060]** FIG. 29 illustrates still another embodiment for controlling a state of a specific real object of a real space displayed on an XR device according to the present disclosure;

**[0061]** FIG. 30 illustrates further still another embodiment for controlling a state of a specific real object of a real space displayed on an XR device according to the present disclosure; and

**[0062]** FIG. 31 illustrates further still another embodiment for controlling a state of a specific real object of a real space displayed on an XR device according to the present disclosure.

#### DETAILED DESCRIPTION OF THE INVENTION

**[0063]** Reference will now be made in detail to embodiments of the present disclosure, examples of which are illustrated in the accompanying drawings. Wherever possible, the same reference numbers will be used throughout the drawings to refer to the same or like parts, and a redundant description will be avoided. The terms “module” and “unit” are interchangeably used only for easiness of description and thus they should not be considered as having distinctive meanings or roles. Further, a detailed description of well-known technology will not be given in describing embodiments of the present disclosure lest it should obscure the subject matter of the embodiments. The attached drawings are provided to help the understanding of the embodiments of the present disclosure, not limiting the scope of the present disclosure. It is to be understood that the present disclosure covers various modifications, equivalents, and/or alternatives falling within the scope and spirit of the present disclosure.

**[0064]** The following embodiments of the present disclosure are intended to embody the present disclosure, not limiting the scope of the present disclosure. What could easily be derived from the detailed description of the present disclosure and the embodiments by a person skilled in the art is interpreted as falling within the scope of the present disclosure.

**[0065]** The above embodiments are therefore to be construed in all aspects as illustrative and not restrictive. The scope of the disclosure should be determined by the appended claims and their legal equivalents, not by the above description, and all changes coming within the meaning and equivalency range of the appended claims are intended to be embraced therein.

**[0066]** Introduction

**[0067]** In the disclosure, downlink (DL) refers to communication from a base station (BS) to a user equipment (UE), and uplink (UL) refers to communication from the UE to the BS. On DL, a transmitter may be a part of the BS and a receiver may be a part of the UE, whereas on UL, a transmitter may be a part of the UE and a receiver may be a part of the BS. A UE may be referred to as a first communication device, and a BS may be referred to as a

second communication device in the present disclosure. The term BS may be replaced with fixed station, Node B, evolved Node B (eNB), next generation Node B (gNB), base transceiver system (BTS), access point (AP), network or 5th generation (5G) network node, artificial intelligence (AI) system, road side unit (RSU), robot, augmented reality/virtual reality (AR/VR) system, and so on. The term UE may be replaced with terminal, mobile station (MS), user terminal (UT), mobile subscriber station (MSS), subscriber station (SS), advanced mobile station (AMS), wireless terminal (WT), device-to-device (D2D) device, vehicle, robot, AI device (or module), AR/VR device (or module), and so on.

**[0068]** The following technology may be used in various wireless access systems including code division multiple access (CDMA), frequency division multiple access (FDMA), time division multiple access (TDMA), orthogonal frequency division multiple access (OFDMA), and single carrier FDMA (SC-FDMA).

**[0069]** For the convenience of description, the present disclosure is described in the context of a 3<sup>rd</sup> generation partnership project (3GPP) communication system (e.g., long term evolution-advanced (LTE-A) and new radio or new radio access technology (NR)), which should not be construed as limiting the present disclosure. For reference, 3GPP LTE is part of evolved universal mobile telecommunications system (E-UMTS) using evolved UMTS terrestrial radio access (E-UTRA), and LTE-A/LTE-A pro is an evolution of 3GPP LTE. 3GPP NR is an evolution of 3GPP/LTE-A/LTE-A pro.

**[0070]** In the present disclosure, a node refers to a fixed point capable of transmitting/receiving wireless signals by communicating with a UE. Various types of BSs may be used as nodes irrespective of their names. For example, any of a BS, an NB, an eNB, a pico-cell eNB (PeNB), a home eNB (HeNB), a relay, and a repeater may be a node. At least one antenna is installed in one node. The antenna may refer to a physical antenna, an antenna port, a virtual antenna, or an antenna group. A node is also referred to as a point.

**[0071]** In the present disclosure, a cell may refer to a certain geographical area or radio resources, in which one or more nodes provide a communication service. A “cell” as a geographical area may be understood as coverage in which a service may be provided in a carrier, while a “cell” as radio resources is associated with the size of a frequency configured in the carrier, that is, a bandwidth (BW). Because a range in which a node may transmit a valid signal, that is, DL coverage and a range in which the node may receive a valid signal from a UE, that is, UL coverage depend on a carrier carrying the signals, and thus the coverage of the node is associated with the “cell” coverage of radio resources used by the node. Accordingly, the term “cell” may mean the service coverage of a node, radio resources, or a range in which a signal reaches with a valid strength in the radio resources, under circumstances.

**[0072]** In the present disclosure, communication with a specific cell may amount to communication with a BS or node that provides a communication service to the specific cell. Further, a DL/UL signal of a specific cell means a DL/UL signal from/to a BS or node that provides a communication service to the specific cell. Particularly, a cell that provides a UL/DL communication service to a UE is called a serving cell for the UE. Further, the channel state/quality of a specific cell refers to the channel state/quality of a channel or a communication link established

between a UE and a BS or node that provides a communication service to the specific cell.

**[0073]** A “cell” associated with radio resources may be defined as a combination of DL resources and UL resources, that is, a combination of a DL component carrier (CC) and a UL CC. A cell may be configured with DL resources alone or both DL resources and UL resources in combination. When carrier aggregation (CA) is supported, linkage between the carrier frequency of DL resources (or a DL CC) and the carrier frequency of UL resources (or a UL CC) may be indicated by system information transmitted in a corresponding cell. A carrier frequency may be identical to or different from the center frequency of each cell or CC. Hereinbelow, a cell operating in a primary frequency is referred to as a primary cell (Pcell) or PCC, and a cell operating in a secondary frequency is referred to as a secondary cell (Scell) or SCC. The Scell may be configured after a UE and a BS perform a radio resource control (RRC) connection establishment procedure and thus an RRC connection is established between the UE and the BS, that is, the UE is RRC\_CONNECTED. The RRC connection may mean a path in which the RRC of the UE may exchange RRC messages with the RRC of the BS. The Scell may be configured to provide additional radio resources to the UE. The Scell and the Pcell may form a set of serving cells for the UE according to the capabilities of the UE. Only one serving cell configured with a Pcell exists for an RRC\_CONNECTED UE which is not configured with CA or does not support CA.

**[0074]** A cell supports a unique radio access technology (RAT). For example, LTE RAT-based transmission/reception is performed in an LTE cell, and 5G RAT-based transmission/reception is performed in a 5G cell.

**[0075]** CA aggregates a plurality of carriers each having a smaller system BW than a target BW to support broadband. CA differs from OFDMA in that DL or UL communication is conducted in a plurality of carrier frequencies each forming a system BW (or channel BW) in the former, and DL or UL communication is conducted by loading a basic frequency band divided into a plurality of orthogonal subcarriers in one carrier frequency in the latter. In OFDMA or orthogonal frequency division multiplexing (OFDM), for example, one frequency band having a certain system BW is divided into a plurality of subcarriers with a predetermined subcarrier spacing, information/data is mapped to the plurality of subcarriers, and the frequency band in which the information/data has been mapped is transmitted in a carrier frequency of the frequency band through frequency upconversion. In wireless CA, frequency bands each having a system BW and a carrier frequency may be used simultaneously for communication, and each frequency band used in CA may be divided into a plurality of subcarriers with a predetermined subcarrier spacing.

**[0076]** The 3GPP communication standards define DL physical channels corresponding to resource elements (REs) conveying information originated from upper layers of the physical layer (e.g., the medium access control (MAC) layer, the radio link control (RLC) layer, the packet data convergence protocol (PDCP) layer, the radio resource control (RRC) layer, the service data adaptation protocol (SDAP) layer, and the non-access stratum (NAS) layer), and DL physical signals corresponding to REs which are used in the physical layer but do not deliver information originated from the upper layers. For example, physical downlink shared

channel (PDSCH), physical broadcast channel (PBCH), physical multicast channel (PMCH), physical control format indicator channel (PCFICH), and physical downlink control channel (PDCCH) are defined as DL physical channels, and a reference signal (RS) and a synchronization signal are defined as DL physical signals. An RS, also called a pilot is a signal in a predefined special waveform known to both a BS and a UE. For example, cell specific RS (CRS), UE-specific RS (UE-RS), positioning RS (PRS), channel state information RS (CSI-RS), and demodulation RS (DMRS) are defined as DL RSs. The 3GPP communication standards also define UL physical channels corresponding to REs conveying information originated from upper layers, and UL physical signals corresponding to REs which are used in the physical layer but do not carry information originated from the upper layers. For example, physical uplink shared channel (PUSCH), physical uplink control channel (PUCCH), and physical random access channel (PRACH) are defined as UL physical channels, and DMRS for a UL control/data signal and sounding reference signal (SRS) used for UL channel measurement are defined.

**[0077]** In the present disclosure, physical shared channels (e.g., PUSCH and PDSCH) are used to deliver information originated from the upper layers of the physical layer (e.g., the MAC layer, the RLC layer, the PDCP layer, the RRC layer, the SDAP layer, and the NAS layer).

**[0078]** In the present disclosure, an RS is a signal in a predefined special waveform known to both a BS and a UE. In a 3GPP communication system, for example, the CRS being a cell common RS, the UE-RS for demodulation of a physical channel of a specific UE, the CSI-RS used to measure/estimate a DL channel state, and the DMRS used to demodulate a physical channel are defined as DL RSs, and the DMRS used for demodulation of a UL control/data signal and the SRS used for UL channel state measurement/estimation are defined as UL RSs.

**[0079]** In the present disclosure, a transport block (TB) is payload for the physical layer. For example, data provided to the physical layer by an upper layer or the MAC layer is basically referred to as a TB. A UE which is a device including an AR/VR module (i.e., an AR/VR device) may transmit a TB including AR/VR data to a wireless communication network (e.g., a 5G network) on a PUSCH. Further, the UE may receive a TB including AR/VR data of the 5G network or a TB including a response to AR/VR data transmitted by the UE from the wireless communication network.

**[0080]** In the present disclosure, hybrid automatic repeat and request (HARQ) is a kind of error control technique. An HARQ acknowledgement (HARQ-ACK) transmitted on DL is used for error control of UL data, and a HARQ-ACK transmitted on UL is used for error control of DL data. A transmitter performing an HARQ operation awaits reception of an ACK after transmitting data (e.g., a TB or a codeword). A receiver performing an HARQ operation transmits an ACK only when data has been successfully received, and a negative ACK (NACK) when the received data has an error. Upon receipt of the ACK, the transmitter may transmit (new) data, and upon receipt of the NACK, the transmitter may retransmit the data.

**[0081]** In the present disclosure, CSI generically refers to information representing the quality of a radio channel (or link) established between a UE and an antenna port. The CSI may include at least one of a channel quality indicator

(CQI), a precoding matrix indicator (PMI), a CSI-RS resource indicator (CRI), a synchronization signal block resource indicator (SSBRI), a layer indicator (LI), a rank indicator (RI), or a reference signal received power (RSRP).

**[0082]** In the present disclosure, frequency division multiplexing (FDM) is transmission/reception of signals/channels/users in different frequency resources, and time division multiplexing (TDM) is transmission/reception of signals/channels/users in different time resources.

**[0083]** In the present disclosure, frequency division duplex (FDD) is a communication scheme in which UL communication is performed in a UL carrier, and DL communication is performed in a DL carrier linked to the UL carrier, whereas time division duplex (TDD) is a communication scheme in which UL communication and DL communication are performed in time division in the same carrier. In the present disclosure, half-duplex is a scheme in which a communication device operates on UL or UL only in one frequency at one time point, and on DL or UL in another frequency at another time point. For example, when the communication device operates in half-duplex, the communication device communicates in UL and DL frequencies, wherein the communication device performs a UL transmission in the UL frequency for a predetermined time, and retunes to the DL frequency and performs a DL reception in the DL frequency for another predetermined time, in time division, without simultaneously using the UL and DL frequencies.

**[0084]** FIG. 1 is a diagram illustrating an exemplary resource grid to which physical signals/channels are mapped in a 3GPP system.

**[0085]** Referring to FIG. 1, for each subcarrier spacing configuration and carrier, a resource grid of  $N_{grid}^{size,\mu} * N_{sc}^{RB}$  subcarriers by  $14 \cdot 2^\mu$  OFDM symbols is defined. Herein,  $N_{grid}^{size,\mu}$  is indicated by RRC signaling from a BS, and  $\mu$  represents a subcarrier spacing  $\Delta f$  given by  $\Delta f = 2^\mu \cdot 15$  [kHz] where  $\mu \in \{0, 1, 2, 3, 4\}$  in a 5G system.

**[0086]**  $N_{grid}^{size,\mu}$  may be different between UL and DL as well as a subcarrier spacing configuration  $\mu$ . For the subcarrier spacing configuration  $\mu$ , an antenna port  $p$ , and a transmission direction (UL or DL), there is one resource grid. Each element of a resource grid for the subcarrier spacing configuration  $\mu$  and the antenna port  $p$  is referred to as an RE, uniquely identified by an index pair  $(k, l)$  where  $k$  is a frequency-domain index and  $l$  is the position of a symbol in a relative time domain with respect to a reference point. A frequency unit used for mapping physical channels to REs, resource block (RB) is defined by 12 consecutive subcarriers ( $N_{sc}^{RB} = 12$ ) in the frequency domain. Considering that a UE may not support a wide BW supported by the 5G system at one time, the UE may be configured to operate in a part (referred to as a bandwidth part (BWP)) of the frequency BW of a cell.

**[0087]** For the background technology, terminology, and abbreviations used in the present disclosure, standard specifications published before the present disclosure may be referred to. For example, the following documents may be referred to.

**[0088]** 3GPP LTE

**[0089]** 3GPP TS 36.211: Physical channels and modulation

**[0090]** 3GPP TS 36.212: Multiplexing and channel coding

**[0091]** 3GPP TS 36.213: Physical layer procedures

**[0092]** 3GPP TS 36.214: Physical layer: Measurements

**[0093]** 3GPP TS 36.300: Overall description

**[0094]** 3GPP TS 36.304: User Equipment (UE) procedures in idle mode

**[0095]** 3GPP TS 36.314: Layer 2—Measurements

**[0096]** 3GPP TS 36.321: Medium Access Control (MAC) protocol

**[0097]** 3GPP TS 36.322: Radio Link Control (RLC) protocol

**[0098]** 3GPP TS 36.323: Packet Data Convergence Protocol (PDCP)

**[0099]** 3GPP TS 36.331: Radio Resource Control (RRC) protocol

**[0100]** 3GPP TS 23.303: Proximity-based services (ProSe); Stage 2

**[0101]** 3GPP TS 23.285: Architecture enhancements for V2X services

**[0102]** 3GPP TS 23.401: General Packet Radio Service (GPRS) enhancements for Evolved Universal Terrestrial Radio Access Network (E-UTRAN) access

**[0103]** 3GPP TS 23.402: Architecture enhancements for non-3GPP accesses

**[0104]** 3GPP TS 23.286: Application layer support for V2X services; Functional architecture and information flows

**[0105]** 3GPP TS 24.301: Non-Access-Stratum (NAS) protocol for Evolved Packet System (EPS); Stage 3

**[0106]** 3GPP TS 24.302: Access to the 3GPP Evolved Packet Core (EPC) via non-3GPP access networks; Stage 3

**[0107]** 3GPP TS 24.334: Proximity-services (ProSe) User Equipment (UE) to ProSe function protocol aspects; Stage 3

**[0108]** 3GPP TS 24.386: User Equipment (UE) to V2X control function; protocol aspects; Stage 3

**[0109]** 3GPP NR (e.g. 5G)

**[0110]** 3GPP TS 38.211: Physical channels and modulation

**[0111]** 3GPP TS 38.212: Multiplexing and channel coding

**[0112]** 3GPP TS 38.213: Physical layer procedures for control

**[0113]** 3GPP TS 38.214: Physical layer procedures for data

**[0114]** 3GPP TS 38.215: Physical layer measurements

**[0115]** 3GPP TS 38.300: NR and NG-RAN Overall Description

**[0116]** 3GPP TS 38.304: User Equipment (UE) procedures in idle mode and in RRC inactive state

**[0117]** 3GPP TS 38.321: Medium Access Control (MAC) protocol

**[0118]** 3GPP TS 38.322: Radio Link Control (RLC) protocol

**[0119]** 3GPP TS 38.323: Packet Data Convergence Protocol (PDCP)

**[0120]** 3GPP TS 38.331: Radio Resource Control (RRC) protocol

**[0121]** 3GPP TS 37.324: Service Data Adaptation Protocol (SDAP)

**[0122]** 3GPP TS 37.340: Multi-connectivity; Overall description

**[0123]** 3GPP TS 23.287: Application layer support for V2X services; Functional architecture and information flows

[0124] 3GPP TS 23.501: System Architecture for the 5G System

[0125] 3GPP TS 23.502: Procedures for the 5G System

[0126] 3GPP TS 23.503: Policy and Charging Control Framework for the 5G System; Stage 2

[0127] 3GPP TS 24.501: Non-Access-Stratum (NAS) protocol for 5G System (5GS); Stage 3

[0128] 3GPP TS 24.502: Access to the 3GPP 5G Core Network (SGCN) via non-3GPP access networks

[0129] 3GPP TS 24.526: User Equipment (UE) policies for 5G System (5GS); Stage 3

[0130] FIG. 2 is a diagram illustrating an exemplary method of transmitting/receiving 3GPP signals.

[0131] Referring to FIG. 2, when a UE is powered on or enters a new cell, the UE performs an initial cell search involving acquisition of synchronization with a BS (S201). For the initial cell search, the UE receives a primary synchronization channel (P-SCH) and a secondary synchronization channel (S-SCH), acquires synchronization with the BS, and obtains information such as a cell identifier (ID) from the P-SCH and the S-SCH. In the LTE system and the NR system, the P-SCH and the S-SCH are referred to as a primary synchronization signal (PSS) and a secondary synchronization signal (SSS), respectively. The initial cell search procedure will be described below in greater detail.

[0132] After the initial cell search, the UE may receive a PBCH from the BS and acquire broadcast information within a cell from the PBCH. During the initial cell search, the UE may check a DL channel state by receiving a DL RS.

[0133] Upon completion of the initial cell search, the UE may acquire more specific system information by receiving a PDCCH and receiving a PDSCH according to information carried on the PDCCH (S202).

[0134] When the UE initially accesses the BS or has no radio resources for signal transmission, the UE may perform a random access procedure with the BS (S203 to S206). For this purpose, the UE may transmit a predetermined sequence as a preamble on a PRACH (S203 and S205) and receive a PDCCH, and a random access response (RAR) message in response to the preamble on a PDSCH corresponding to the PDCCH (S204 and S206). If the random access procedure is contention-based, the UE may additionally perform a contention resolution procedure. The random access procedure will be described below in greater detail.

[0135] After the above procedure, the UE may then perform PDCCH/PDSCH reception (S207) and PUSCH/PUCCH transmission (S208) in a general UL/DL signal transmission procedure. Particularly, the UE receives DCI on a PDCCH.

[0136] The UE monitors a set of PDCCH candidates in monitoring occasions configured for one or more control element sets (CORESETs) in a serving cell according to a corresponding search space configuration. The set of PDCCH candidates to be monitored by the UE is defined from the perspective of search space sets. A search space set may be a common search space set or a UE-specific search space set. A CORESET includes a set of (physical) RBs that last for a time duration of one to three OFDM symbols. The network may configure a plurality of CORESETs for the UE. The UE monitors PDCCH candidates in one or more search space sets. Herein, monitoring is attempting to decode PDCCH candidate(s) in a search space. When the UE succeeds in decoding one of the PDCCH candidates in the search space, the UE determines that a PDCCH has been

detected from among the PDCCH candidates and performs PDSCH reception or PUSCH transmission based on DCI included in the detected PDCCH.

[0137] The PDCCH may be used to schedule DL transmissions on a PDSCH and UL transmissions on a PUSCH. DCI in the PDCCH includes a DL assignment (i.e., a DL grant) including at least a modulation and coding format and resource allocation information for a DL shared channel, and a UL grant including a modulation and coding format and resource allocation information for a UL shared channel.

[0138] Initial Access (IA) Procedure

[0139] Synchronization Signal Block (SSB) Transmission and Related Operation

[0140] FIG. 3 is a diagram illustrating an exemplary SSB structure. The UE may perform cell search, system information acquisition, beam alignment for initial access, DL measurement, and so on, based on an SSB. The term SSB is interchangeably used with synchronization signal/physical broadcast channel (SS/PBCH).

[0141] Referring to FIG. 3, an SSB includes a PSS, an SSS, and a PBCH. The SSB includes four consecutive OFDM symbols, and the PSS, the PBCH, the SSS/PBCH, or the PBCH is transmitted in each of the OFDM symbols. The PBCH is encoded/decoded based on a polar code and modulated/demodulated in quadrature phase shift keying (QPSK). The PBCH in an OFDM symbol includes data REs to which a complex modulated value of the PBCH is mapped and DMRS REs to which a DMRS for the PBCH is mapped. There are three DMRS REs per RB in an OFDM symbol and three data REs between every two of the DMRS REs.

[0142] Cell Search

[0143] Cell search is a process of acquiring the time/frequency synchronization of a cell and detecting the cell ID (e.g., physical cell ID (PCI)) of the cell by a UE. The PSS is used to detect a cell ID in a cell ID group, and the SSS is used to detect the cell ID group. The PBCH is used for SSB (time) index detection and half-frame detection.

[0144] In the 5G system, there are 336 cell ID groups each including 3 cell IDs. Therefore, a total of 1008 cell IDs are available. Information about a cell ID group to which the cell ID of a cell belongs is provided/acquired by/from the SSS of the cell, and information about the cell ID among 336 cells within the cell ID is provided/acquired by/from the PSS.

[0145] The SSB is periodically transmitted with an SSB periodicity. The UE assumes a default SSB periodicity of 20 ms during initial cell search. After cell access, the SSB periodicity may be set to one of {5 ms, 10 ms, 20 ms, 40 ms, 80 ms, 160 ms} by the network (e.g., a BS). An SSB burst set is configured at the start of an SSB period. The SSB burst set is composed of a 5-ms time window (i.e., half-frame), and the SSB may be transmitted up to L times within the SSB burst set. The maximum number L of SSB transmissions may be given as follows according to the frequency band of a carrier.

[0146] For frequency range up to 3 GHz, L=4

[0147] For frequency range from 3 GHz to 6 GHz, L=8

[0148] For frequency range from 6 GHz to 52.6 GHz, L=64

[0149] The possible time positions of SSBs in a half-frame are determined by a subcarrier spacing, and the periodicity of half-frames carrying SSBs is configured by the network. The time positions of SSB candidates are indexed as 0 to L-1 (SSB indexes) in a time order in an SSB burst set (i.e.,

half-frame). Other SSBs may be transmitted in different spatial directions (by different beams spanning the coverage area of the cell) during the duration of a half-frame. Accordingly, an SSB index (SSBI) may be associated with a BS transmission (Tx) beam in the 5G system.

**[0150]** The UE may acquire DL synchronization by detecting an SSB. The UE may identify the structure of an SSB burst set based on a detected (time) SSBI and hence a symbol/slot/half-frame boundary. The number of a frame/half-frame to which the detected SSB belongs may be identified by using system frame number (SFN) information and half-frame indication information.

**[0151]** Specifically, the UE may acquire the 10-bit SFN of a frame carrying the PBCH from the PBCH. Subsequently, the UE may acquire 1-bit half-frame indication information. For example, when the UE detects a PBCH with a half-frame indication bit set to 0, the UE may determine that an SSB to which the PBCH belongs is in the first half-frame of the frame. When the UE detects a PBCH with a half-frame indication bit set to 1, the UE may determine that an SSB to which the PBCH belongs is in the second half-frame of the frame. Finally, the UE may acquire the SSBI of the SSB to which the PBCH belongs based on a DMRS sequence and PBCH payload delivered on the PBCH.

**[0152]** System Information (SI) Acquisition

**[0153]** SI is divided into a master information block (MIB) and a plurality of system information blocks (SIBs). The SI except for the MIB may be referred to as remaining minimum system information (RMSI). For details, the following may be referred to.

**[0154]** The MIB includes information/parameters for monitoring a PDCCH that schedules a PDSCH carrying systemInformationBlock1 (SIB1), and transmitted on a PBCH of an SSB by a BS. For example, a UE may determine from the MIB whether there is any CORESET for a Type0-PDCCH common search space. The Type0-PDCCH common search space is a kind of PDCCH search space and used to transmit a PDCCH that schedules an SI message. In the presence of a Type0-PDCCH common search space, the UE may determine (i) a plurality of contiguous RBs and one or more consecutive symbols included in a CORESET, and (ii) a PDCCH occasion (e.g., a time-domain position at which a PDCCH is to be received), based on information (e.g., pdcch-ConfigSIB1) included in the MIB.

**[0155]** SIB1 includes information related to availability and scheduling (e.g., a transmission period and an SI-window size) of the remaining SIBs (hereinafter, referred to SIBx where x is an integer equal to or larger than 2). For example, SIB1 may indicate whether SIBx is broadcast periodically or in an on-demand manner upon user request. If SIBx is provided in the on-demand manner, SIB1 may include information required for the UE to transmit an SI request. A PDCCH that schedules SIB1 is transmitted in the Type0-PDCCH common search space, and SIB1 is transmitted on a PDSCH indicated by the PDCCH.

**[0156]** SIBx is included in an SI message and transmitted on a PDSCH. Each SI message is transmitted within a periodic time window (i.e., SI-window).

**[0157]** Random Access Procedure

**[0158]** The random access procedure serves various purposes. For example, the random access procedure may be

used for network initial access, handover, and UE-triggered UL data transmission. The UE may acquire UL synchronization and UL transmission resources in the random access procedure. The random access procedure may be contention-based or contention-free.

**[0159]** FIG. 4 is a diagram illustrating an exemplary random access procedure. Particularly, FIG. 4 illustrates a contention-based random access procedure.

**[0160]** First, a UE may transmit a random access preamble as a first message (Msg1) of the random access procedure on a PRACH. In the present disclosure, a random access procedure and a random access preamble are also referred to as a RACH procedure and a RACH preamble, respectively.

**[0161]** A plurality of preamble formats are defined by one or more RACH OFDM symbols and different cyclic prefixes (CPs) (and/or guard times). A RACH configuration for a cell is included in system information of the cell and provided to the UE. The RACH configuration includes information about a subcarrier spacing, available preambles, a preamble format, and so on for a PRACH. The RACH configuration includes association information between SSBs and RACH (time-frequency) resources, that is, association information between SSBI and RACH (time-frequency) resources. The SSBI are associated with Tx beams of a BS, respectively. The UE transmits a RACH preamble in RACH time-frequency resources associated with a detected or selected SSB. The BS may identify a preferred BS Tx beam of the UE based on time-frequency resources in which the RACH preamble has been detected.

**[0162]** An SSB threshold for RACH resource association may be configured by the network, and a RACH preamble transmission (i.e., PRACH transmission) or retransmission is performed based on an SSB in which an RSRP satisfying the threshold has been measured. For example, the UE may select one of SSB(s) satisfying the threshold and transmit or retransmit the RACH preamble in RACH resources associated with the selected SSB.

**[0163]** Upon receipt of the RACH preamble from the UE, the BS transmits an RAR message (a second message (Msg2)) to the UE. A PDCCH that schedules a PDSCH carrying the RAR message is cyclic redundancy check (CRC)-masked by an RA radio network temporary identifier (RNTI) (RA-RNTI) and transmitted. When the UE detects the PDCCH masked by the RA-RNTI, the UE may receive the RAR message on the PDSCH scheduled by DCI delivered on the PDCCH. The UE determines whether RAR information for the transmitted preamble, that is, Msg1 is included in the RAR message. The UE may determine whether random access information for the transmitted Msg1 is included by checking the presence or absence of the RACH preamble ID of the transmitted preamble. If the UE fails to receive a response to Msg1, the UE may transmit the RACH preamble a predetermined number of or fewer times, while performing power ramping. The UE calculates the PRACH transmission power of a preamble retransmission based on the latest pathloss and a power ramping counter.

**[0164]** Upon receipt of the RAR information for the UE on the PDSCH, the UE may acquire timing advance information for UL synchronization, an initial UL grant, and a UE temporary cell RNTI (C-RNTI). The timing advance information is used to control a UL signal transmission timing. To enable better alignment between PUSCH/PUCCH transmission of the UE and a subframe timing at a network end, the network (e.g., BS) may measure the time difference between

PUSCH/PUCCH/SRS reception and a subframe and transmit the timing advance information based on the measured time difference. The UE may perform a UL transmission as a third message (Msg3) of the RACH procedure on a PUSCH. Msg3 may include an RRC connection request and a UE ID. The network may transmit a fourth message (Msg4) in response to Msg3, and Msg4 may be treated as a contention solution message on DL. As the UE receives Msg4, the UE may enter an RRC\_CONNECTED state.

**[0165]** The contention-free RACH procedure may be used for handover of the UE to another cell or BS or performed when requested by a BS command. The contention-free RACH procedure is basically similar to the contention-based RACH procedure. However, compared to the contention-based RACH procedure in which a preamble to be used is randomly selected among a plurality of RACH preambles, a preamble to be used by the UE (referred to as a dedicated RACH preamble) is allocated to the UE by the BS in the contention-free RACH procedure. Information about the dedicated RACH preamble may be included in an RRC message (e.g., a handover command) or provided to the UE by a PDCCH order. When the RACH procedure starts, the UE transmits the dedicated RACH preamble to the BS. When the UE receives the RACH procedure from the BS, the RACH procedure is completed.

**[0166]** DL and UL Transmission/Reception Operations

**[0167]** DL Transmission/Reception Operation

**[0168]** DL grants (also called DL assignments) may be classified into (1) dynamic grant and (2) configured grant. A dynamic grant is a data transmission/reception method based on dynamic scheduling of a BS, aiming to maximize resource utilization.

**[0169]** The BS schedules a DL transmission by DCI. The UE receives the DCI for DL scheduling (i.e., including scheduling information for a PDSCH) (referred to as DL grant DCI) from the BS. The DCI for DL scheduling may include, for example, the following information: a BWP indicator, a frequency-domain resource assignment, a time-domain resource assignment, and a modulation and coding scheme (MCS).

**[0170]** The UE may determine a modulation order, a target code rate, and a TB size (TBS) for the PDSCH based on an MCS field in the DCI. The UE may receive the PDSCH in time-frequency resources according to the frequency-domain resource assignment and the time-domain resource assignment.

**[0171]** The DL configured grant is also called semi-persistent scheduling (SPS). The UE may receive an RRC message including a resource configuration for DL data transmission from the BS. In the case of DL SPS, an actual DL configured grant is provided by a PDCCH, and the DL SPS is activated or deactivated by the PDCCH. When DL SPS is configured, the BS provides the UE with at least the following parameters by RRC signaling: a configured scheduling RNTI (CS-RNTI) for activation, deactivation, and retransmission; and a periodicity. An actual DL grant (e.g., a frequency resource assignment) for DL SPS is provided to the UE by DCI in a PDCCH addressed to the CS-RNTI. If a specific field in the DCI of the PDCCH addressed to the CS-RNTI is set to a specific value for scheduling activation, SPS associated with the CS-RNTI is activated. The DCI of the PDCCH addressed to the CS-RNTI includes actual

frequency resource allocation information, an MCS index, and so on. The UE may receive DL data on a PDSCH based on the SPS.

**[0172]** UL Transmission/Reception Operation

**[0173]** UL grants may be classified into (1) dynamic grant that schedules a PUSCH dynamically by UL grant DCI and (2) configured grant that schedules a PUSCH semi-statically by RRC signaling.

**[0174]** FIG. 5 is a diagram illustrating exemplary UL transmissions according to UL grants. Particularly, FIG. 5(a) illustrates a UL transmission procedure based on a dynamic grant, and FIG. 5(b) illustrates a UL transmission procedure based on a configured grant.

**[0175]** In the case of a UL dynamic grant, the BS transmits DCI including UL scheduling information to the UE. The UE receives DCI for UL scheduling (i.e., including scheduling information for a PUSCH) (referred to as UL grant DCI) on a PDCCH. The DCI for UL scheduling may include, for example, the following information: a BWP indicator, a frequency-domain resource assignment, a time-domain resource assignment, and an MCS. For efficient allocation of UL radio resources by the BS, the UE may transmit information about UL data to be transmitted to the BS, and the BS may allocate UL resources to the UE based on the information. The information about the UL data to be transmitted is referred to as a buffer status report (BSR), and the BSR is related to the amount of UL data stored in a buffer of the UE.

**[0176]** Referring to FIG. 5(a), the illustrated UL transmission procedure is for a UE which does not have UL radio resources available for BSR transmission. In the absence of a UL grant available for UL data transmission, the UE is not capable of transmitting a BSR on a PUSCH. Therefore, the UE should request resources for UL data, starting with transmission of an SR on a PUCCH. In this case, a 5-step UL resource allocation procedure is used.

**[0177]** Referring to FIG. 5(a), in the absence of PUSCH resources for BSR transmission, the UE first transmits an SR to the BS, for PUSCH resource allocation. The SR is used for the UE to request PUSCH resources for UL transmission to the BS, when no PUSCH resources are available to the UE in spite of occurrence of a buffer status reporting event. In the presence of valid PUCCH resources for the SR, the UE transmits the SR on a PUCCH, whereas in the absence of valid PUCCH resources for the SR, the UE starts the afore-described (contention-based) RACH procedure. Upon receipt of a UL grant in UL grant DCI from the BS, the UE transmits a BSR to the BS in PUSCH resources allocated by the UL grant. The BS checks the amount of UL data to be transmitted by the UE based on the BSR and transmits a UL grant in UL grant DCI to the UE. Upon detection of a PDCCH including the UL grant DCI, the UE transmits actual UL data to the BS on a PUSCH based on the UL grant included in the UL grant DCI.

**[0178]** Referring to FIG. 5(b), in the case of a configured grant, the UE receives an RRC message including a resource configuration for UL data transmission from the BS. In the NR system, two types of UL configured grants are defined: type 1 and type 2. In the case of UL configured grant type 1, an actual UL grant (e.g., time resources and frequency resources) is provided by RRC signaling, whereas in the case of UL configured grant type 2, an actual UL grant is provided by a PDCCH, and activated or deactivated by the PDCCH. If configured grant type 1 is configured, the BS

provides the UE with at least the following parameters by RRC signaling: a CS-RNTI for retransmission; a periodicity of configured grant type 1; information about a starting symbol index  $S$  and the number  $L$  of symbols for a PUSCH in a slot; a time-domain offset representing a resource offset with respect to SFN=0 in the time domain; and an MCS index representing a modulation order, a target code rate, and a TB size. If configured grant type 2 is configured, the BS provides the UE with at least the following parameters by RRC signaling: a CS-RNTI for activation, deactivation, and retransmission; and a periodicity of configured grant type 2. An actual UL grant of configured grant type 2 is provided to the UE by DCI of a PDCCH addressed to a CS-RNTI. If a specific field in the DCI of the PDCCH addressed to the CS-RNTI is set to a specific value for scheduling activation, configured grant type 2 associated with the CS-RNTI is activated. The DCI set to a specific value for scheduling activation in the PDCCH includes actual frequency resource allocation information, an MCS index, and so on. The UE may perform a UL transmission on a PUSCH based on a configured grant of type 1 or type 2.

**[0179]** FIG. 6 is a conceptual diagram illustrating exemplary physical channel processing.

**[0180]** Each of the blocks illustrated in FIG. 6 may be performed in a corresponding module of a physical layer block in a transmission device. More specifically, the signal processing depicted in FIG. 6 may be performed for UL transmission by a processor of a UE described in the present disclosure. Signal processing of FIG. 6 except for transform precoding, with CP-OFDM signal generation instead of SC-FDMA signal generation may be performed for DL transmission in a processor of a BS described in the present disclosure. Referring to FIG. 6, UL physical channel processing may include scrambling, modulation mapping, layer mapping, transform precoding, precoding, RE mapping, and SC-FDMA signal generation. The above processes may be performed separately or together in the modules of the transmission device. The transform precoding, a kind of discrete Fourier transform (DFT), is to spread UL data in a special manner that reduces the peak-to-average power ratio (PAPR) of a waveform. OFDM which uses a CP together with transform precoding for DFT spreading is referred to as DFT-s-OFDM, and OFDM using a CP without DFT spreading is referred to as CP-OFDM. An SC-FDMA signal is generated by DFT-s-OFDM. In the NR system, if transform precoding is enabled for UL, transform precoding may be applied optionally. That is, the NR system supports two options for a UL waveform: one is CP-OFDM and the other is DFT-s-OFDM. The BS provides RRC parameters to the UE such that the UE determines whether to use CP-OFDM or DFT-s-OFDM for a UL transmission waveform. FIG. 6 is a conceptual view illustrating UL physical channel processing for DFT-s-OFDM. For CP-OFDM, transform precoding is omitted from the processes of FIG. 6. For DL transmission, CP-OFDM is used for DL waveform transmission.

**[0181]** Each of the above processes will be described in greater detail. For one codeword, the transmission device may scramble coded bits of the codeword by a scrambler and then transmit the scrambled bits on a physical channel. The codeword is obtained by encoding a TB. The scrambled bits are modulated to complex-valued modulation symbols by a modulation mapper. The modulation mapper may modulate the scrambled bits in a predetermined modulation scheme and arrange the modulated bits as complex-valued modulation symbols representing positions on a signal constellation.

Pi/2-binay phase shift keying (pi/2-BPSK), m-phase shift keying (m-PSK), m-quadrature amplitude modulation (m-QAM), or the like is available for modulation of the coded data. The complex-valued modulation symbols may be mapped to one or more transmission layers by a layer mapper. A complexed-value modulation symbol on each layer may be precoded by a precoder, for transmission through an antenna port. If transform precoding is possible for UL transmission, the precoder may perform precoding after the complex-valued modulation symbols are subjected to transform precoding, as illustrated in FIG. 6. The precoder may output antenna-specific symbols by processing the complex-valued modulation symbols in a multiple input multiple output (MIMO) scheme according to multiple Tx antennas, and distribute the antenna-specific symbols to corresponding RE mappers. An output  $z$  of the precoder may be obtained by multiplying an output  $y$  of the layer mapper by an  $N \times M$  precoding matrix,  $W$  where  $N$  is the number of antenna ports and  $M$  is the number of layers. The RE mappers map the complex-valued modulation symbols for the respective antenna ports to appropriate REs in an RB allocated for transmission. The RE mappers may map the complex-valued modulation symbols to appropriate subcarriers, and multiplex the mapped symbols according to users. SC-FDMA signal generators (CP-OFDM signal generators, when transform precoding is disabled in DL transmission or UL transmission) may generate complex-valued time domain OFDM symbol signals by modulating the complex-valued modulation symbols in a specific modulations scheme, for example, in OFDM. The SC-FDMA signal generators may perform inverse fast Fourier transform (IFFT) on the antenna-specific symbols and insert CPs into the time-domain IFFT-processed symbols. The OFDM symbols are subjected to digital-to-analog conversion, frequency upconversion, and so on, and then transmitted to a reception device through the respective Tx antennas. Each of the SC-FDMA signal generators may include an IFFT module, a CP inserter, a digital-to-analog converter (DAC), a frequency upconverter, and so on.

**[0182]** A signal processing procedure of the reception device is performed in a reverse order of the signal processing procedure of the transmission device. For details, refer to the above description and FIG. 6.

**[0183]** Now, a description will be given of the PUCCH.

**[0184]** The PUCCH is used for UCI transmission. UCI includes an SR requesting UL transmission resources, CSI representing a UE-measured DL channel state based on a DL RS, and/or an HARQ-ACK indicating whether a UE has successfully received DL data.

**[0185]** The PUCCH supports multiple formats, and the PUCCH formats are classified according to symbol durations, payload sizes, and multiplexing or non-multiplexing. [Table 1] below lists exemplary PUCCH formats.

TABLE 1

Format	PUCCH length in OFDM symbols	Number of bits	Etc.
0	1-2	$\leq 2$	Sequence selection
1	4-14	$\leq 2$	Sequence modulation
2	1-2	$> 2$	CP-OFDM
3	4-14	$> 2$	DFT-s-OFDM (no UE multiplexing)

TABLE 1-continued

Format	PUCCH length in OFDM symbols	Number of bits	Etc.
4	4-14	>2	DFT-s-OFDM (Pre DFT orthogonal cover code (OCC))

**[0186]** The BS configures PUCCH resources for the UE by RRC signaling. For example, to allocate PUCCH resources, the BS may configure a plurality of PUCCH resource sets for the UE, and the UE may select a specific PUCCH resource set corresponding to a UCI (payload) size (e.g., the number of UCI bits). For example, the UE may select one of the following PUCCH resource sets according to the number of UCI bits,  $N_{UCI}$ .

**[0187]** PUCCH resource set #0, if the number of UCI bits  $\leq 2$

**[0188]** PUCCH resource set #1, if  $2 < \text{the number of UCI bits} \leq N_1$

**[0189]** ...

**[0190]** PUCCH resource set #(K-1), if  $NK-2 < \text{the number of UCI bits} \leq N_{K-1}$

**[0191]** Herein, K represents the number of PUCCH resource sets ( $K > 1$ ), and  $N_i$  represents the maximum number of UCI bits supported by PUCCH resource set #i. For example, PUCCH resource set #1 may include resources of PUCCH format 0 to PUCCH format 1, and the other PUCCH resource sets may include resources of PUCCH format 2 to PUCCH format 4.

**[0192]** Subsequently, the BS may transmit DCI to the UE on a PDCCH, indicating a PUCCH resource to be used for UCI transmission among the PUCCH resources of a specific PUCCH resource set by an ACK/NACK resource indicator (ARI) in the DCI. The ARI may be used to indicate a PUCCH resource for HARQ-ACK transmission, also called a PUCCH resource indicator (PRI).

**[0193]** Enhanced Mobile Broadband Communication (eMBB)

**[0194]** In the NR system, a massive MIMO environment in which the number of Tx/Rx antennas is significantly increased is under consideration. On the other hand, in an NR system operating at or above 6 GHz, beamforming is considered, in which a signal is transmitted with concentrated energy in a specific direction, not omni-directionally, to compensate for rapid propagation attenuation. Accordingly, there is a need for hybrid beamforming with analog beamforming and digital beamforming in combination according to a position to which a beamforming weight vector/precoding vector is applied, for the purpose of increased performance, flexible resource allocation, and easiness of frequency-wise beam control.

**[0195]** Hybrid Beamforming

**[0196]** FIG. 7 is a block diagram illustrating an exemplary transmitter and receiver for hybrid beamforming.

**[0197]** In hybrid beamforming, a BS or a UE may form a narrow beam by transmitting the same signal through multiple antennas, using an appropriate phase difference and thus increasing energy only in a specific direction.

**[0198]** Beam Management (BM)

**[0199]** BM is a series of processes for acquiring and maintaining a set of BS (or transmission and reception point

(TRP)) beams and/or UE beams available for DL and UL transmissions/receptions. BM may include the following processes and terminology.

**[0200]** Beam measurement: the BS or the UE measures the characteristics of a received beamformed signal.

**[0201]** Beam determination: the BS or the UE selects its Tx beam/Rx beam.

**[0202]** Beam sweeping: a spatial domain is covered by using a Tx beam and/or an Rx beam in a predetermined method for a predetermined time interval.

**[0203]** Beam report: the UE reports information about a signal beamformed based on a beam measurement.

**[0204]** The BM procedure may be divided into (1) a DL BM procedure using an SSB or CSI-RS and (2) a UL BM procedure using an SRS. Further, each BM procedure may include Tx beam sweeping for determining a Tx beam and Rx beam sweeping for determining an Rx beam. The following description will focus on the DL BM procedure using an SSB.

**[0205]** The DL BM procedure using an SSB may include (1) transmission of a beamformed SSB from the BS and (2) beam reporting of the UE. An SSB may be used for both of Tx beam sweeping and Rx beam sweeping. SSB-based Rx beam sweeping may be performed by attempting SSB reception while changing Rx beams at the UE.

**[0206]** SSB-based beam reporting may be configured, when CSI/beam is configured in the RRC\_CONNECTED state.

**[0207]** The UE receives information about an SSB resource set used for BM from the BS. The SSB resource set may be configured with one or more SSBIs. For each SSB resource set, SSBI 0 to SSBI 63 may be defined.

**[0208]** The UE receives signals in SSB resources from the BS based on the information about the SSB resource set.

**[0209]** When the BS configures the UE with an SSBRI and RSRP reporting, the UE reports a (best) SSBRI and an RSRP corresponding to the SSBRI to the BS.

**[0210]** The BS may determine a BS Tx beam for use in DL transmission to the UE based on a beam report received from the UE.

**[0211]** Beam Failure Recovery (BFR) Procedure

**[0212]** In a beamforming system, radio link failure (RLF) may often occur due to rotation or movement of a UE or beamforming blockage. Therefore, BFR is supported to prevent frequent occurrence of RLF in NR.

**[0213]** For beam failure detection, the BS configures beam failure detection RSs for the UE. If the number of beam failure indications from the physical layer of the UE reaches a threshold configured by RRC signaling within a period configured by RRC signaling of the BS, the UE declares beam failure.

**[0214]** After the beam failure is detected, the UE triggers BFR by initiating a RACH procedure on a Pcell, and performs BFR by selecting a suitable beam (if the BS provides dedicated RACH resources for certain beams, the UE performs the RACH procedure for BFR by using the dedicated RACH resources first of all). Upon completion of the RACH procedure, the UE considers that the BFR has been completed.

**[0215]** Ultra-Reliable and Low Latency Communication (URLLC)

**[0216]** A URLLC transmission defined in NR may mean a transmission with (1) a relatively small traffic size, (2) a relatively low arrival rate, (3) an extremely low latency

requirement (e.g., 0.5 ms or lms), (4) a relatively short transmission duration (e.g., 2 OFDM symbols), and (5) an emergency service/message.

**[0217] Pre-Emption Indication**

**[0218]** Although eMBB and URLLC services may be scheduled in non-overlapped time/frequency resources, a URLLC transmission may take place in resources scheduled for on-going eMBB traffic. To enable a UE receiving a PDSCH to determine that the PDSCH has been partially punctured due to URLLC transmission of another UE, a preemption indication may be used. The preemption indication may also be referred to as an interrupted transmission indication.

**[0219]** In relation to a preemption indication, the UE receives DL preemption RRC information (e.g., a DownlinkPreemption IE) from the BS by RRC signaling.

**[0220]** The UE receives DCI format 2\_1 based on the DL preemption RRC information from the BS. For example, the UE attempts to detect a PDCCH conveying preemption indication-related DCI, DCI format 2\_1 by using an INT-RNTI configured by the DL preemption RRC information.

**[0221]** Upon detection of DCI format 2\_1 for serving cell(s) configured by the DL preemption RRC information, the UE may assume that there is no transmission directed to the UE in RBs and symbols indicated by DCI format 2\_1 in a set of RBs and a set of symbols during a monitoring interval shortly previous to a monitoring interval to which DCI format 2\_1 belongs. For example, the UE decodes data based on signals received in the remaining resource areas, considering that a signal in a time-frequency resource indicated by a preemption indication is not a DL transmission scheduled for the UE.

**[0222] Massive MTC (mMTC)**

**[0223]** mMTC is one of 5G scenarios for supporting a hyper-connectivity service in which communication is conducted with multiple UEs at the same time. In this environment, a UE intermittently communicates at a very low transmission rate with low mobility. Accordingly, mMTC mainly seeks long operation of a UE with low cost. In this regard, MTC and narrow band-Internet of things (NB-IoT) handled in the 3GPP will be described below.

**[0224]** The following description is given with the appreciation that a transmission time interval (TTI) of a physical channel is a subframe. For example, a minimum time interval between the start of transmission of a physical channel and the start of transmission of the next physical channel is one subframe. However, a subframe may be replaced with a slot, a mini-slot, or multiple slots in the following description.

**[0225] Machine Type Communication (MTC)**

**[0226]** MTC is an application that does not require high throughput, applicable to machine-to-machine (M2M) or IoT. MTC is a communication technology which the 3GPP has adopted to satisfy the requirements of the IoT service.

**[0227]** While the following description is given mainly of features related to enhanced MTC (eMTC), the same thing is applicable to MTC, eMTC, and MTC to be applied to 5G (or NR), unless otherwise mentioned. The term MTC as used herein may be interchangeable with eMTC, LTE-M1/M2, bandwidth reduced low complexity (BL)/coverage enhanced (CE), non-BL UE (in enhanced coverage), NR MTC, enhanced BL/CE, and so on.

**[0228] MTC General**

**[0229]** (1) MTC operates only in a specific system BW (or channel BW).

**[0230]** MTC may use a predetermined number of RBs among the RBs of a system band in the legacy LTE system or the NR system. The operating frequency BW of MTC may be defined in consideration of a frequency range and a subcarrier spacing in NR. A specific system or frequency BW in which MTC operates is referred to as an MTC narrowband (NB) or MTC subband. In NR, MTC may operate in at least one BWP or a specific band of a BWP.

**[0231]** While MTC is supported by a cell having a much larger BW (e.g., 10 MHz) than 1.08 MHz, a physical channel and signal transmitted/received in MTC is always limited to 1.08 MHz or 6 (LTE) RBs. For example, a narrowband is defined as 6 non-overlapped consecutive physical resource blocks (PRBs) in the frequency domain in the LTE system.

**[0232]** In MTC, some DL and UL channels are allocated restrictively within a narrowband, and one channel does not occupy a plurality of narrowbands in one time unit. FIG. 8(a) is a diagram illustrating an exemplary narrowband operation, and FIG. 8(b) is a diagram illustrating exemplary MTC channel repetition with RF retuning.

**[0233]** An MTC narrowband may be configured for a UE by system information or DCI transmitted by a BS.

**[0234]** (2) MTC does not use a channel (defined in legacy LTE or NR) which is to be distributed across the total system BW of the legacy LTE or NR. For example, because a legacy LTE PDCCH is distributed across the total system BW, the legacy PDCCH is not used in MTC. Instead, a new control channel, MTC PDCCH (MPDCCH) is used in MTC. The MPDCCH is transmitted/received in up to 6 RBs in the frequency domain. In the time domain, the MPDCCH may be transmitted in one or more OFDM symbols starting with an OFDM symbol of a starting OFDM symbol index indicated by an RRC parameter from the BS among the OFDM symbols of a subframe.

**[0235]** (3) In MTC, PBCH, PRACH, MPDCCH, PDSCH, PUCCH, and PUSCH may be transmitted repeatedly. The MTC repeated transmissions may make these channels decodable even when signal quality or power is very poor as in a harsh condition like basement, thereby leading to the effect of an increased cell radius and signal penetration.

**[0236] MTC Operation Modes and Levels**

**[0237]** For CE, two operation modes, CE Mode A and CE Mode B and four different CE levels are used in MTC, as listed in [Table 2] below.

TABLE 2

Mode	Level	Description
Mode A	Level 1	No repetition for PRACH
	Level 2	Small Number of Repetition for PRACH
Mode B	Level 3	Medium Number of Repetition for PRACH
	Level 4	Large Number of Repetition for PRACH

**[0238]** An MTC operation mode is determined by a BS and a CE level is determined by an MTC UE.

**[0239] MTC Guard Period**

**[0240]** The position of a narrowband used for MTC may change in each specific time unit (e.g., subframe or slot). An MTC UE may tune to different frequencies in different time units. A certain time may be required for frequency retuning and thus used as a guard period for MTC. No transmission and reception take place during the guard period.

**[0241] MTC Signal Transmission/Reception Method**

**[0242]** Apart from features inherent to MTC, an MTC signal transmission/reception procedure is similar to the procedure illustrated in FIG. 2. The operation of S201 in FIG. 2 may also be performed for MTC. A PSS/SSS used in an initial cell search operation in MTC may be the legacy LTE PSS/SSS.

**[0243]** After acquiring synchronization with a BS by using the PSS/SSS, an MTC UE may acquire broadcast information within a cell by receiving a PBCH signal from the BS. The broadcast information transmitted on the PBCH is an MIB. In MTC, reserved bits among the bits of the legacy LTE MIB are used to transmit scheduling information for a new system information block 1 bandwidth reduced (SIB1-BR). The scheduling information for the SIB1-BR may include information about a repetition number and a TBS for a PDSCH conveying SIB1-BR. A frequency resource assignment for the PDSCH conveying SIB1-BR may be a set of 6 consecutive RBs within a narrowband. The SIB1-BR is transmitted directly on the PDSCH without a control channel (e.g., PDSCH or MPDCCH) associated with SIB1-BR.

**[0244]** After completing the initial cell search, the MTC UE may acquire more specific system information by receiving an MPDCCH and a PDSCH based on information of the MPDCCH (S202).

**[0245]** Subsequently, the MTC UE may perform a RACH procedure to complete connection to the BS (S203 to S206). A basic configuration for the RACH procedure of the MTC UE may be transmitted in SIB2. Further, SIB2 includes paging-related parameters. In the 3GPP system, a paging occasion (PO) means a time unit in which a UE may attempt to receive paging. Paging refers to the network's indication of the presence of data to be transmitted to the UE. The MTC UE attempts to receive an MPDCCH based on a P-RNTI in a time unit corresponding to its PO in a narrowband configured for paging, paging narrowband (PNB). When the UE succeeds in decoding the MPDCCH based on the P-RNTI, the UE may check its paging message by receiving a PDSCH scheduled by the MPDCCH. In the presence of its paging message, the UE accesses the network by performing the RACH procedure.

**[0246]** In MTC, signals and/or messages (Msg1, Msg2, Msg3, and Msg4) may be transmitted repeatedly in the RACH procedure, and a different repetition pattern may be set according to a CE level.

**[0247]** For random access, PRACH resources for different CE levels are signaled by the BS. Different PRACH resources for up to 4 respective CE levels may be signaled to the MTC UE. The MTC UE measures an RSRP using a DL RS (e.g., CRS, CSI-RS, or TRS) and determines one of the CE levels signaled by the BS based on the measurement. The UE selects one of different PRACH resources (e.g., frequency, time, and preamble resources for a PARCH) for random access based on the determined CE level and transmits a PRACH. The BS may determine the CE level of the UE based on the PRACH resources that the UE has used for the PRACH transmission. The BS may determine a CE mode for the UE based on the CE level that the UE indicates by the PRACH transmission. The BS may transmit DCI to the UE in the CE mode.

**[0248]** Search spaces for an RAR for the PRACH and contention resolution messages are signaled in system information by the BS.

**[0249]** After the above procedure, the MTC UE may receive an MPDCCH signal and/or a PDSCH signal (S207) and transmit a PUSCH signal and/or a PUCCH signal (S208) in a general UL/DL signal transmission procedure. The MTC UE may transmit UCI on a PUCCH or a PUSCH to the BS.

**[0250]** Once an RRC connection for the MTC UE is established, the MTC UE attempts to receive an MDCCCH by monitoring an MPDCCH in a configured search space in order to acquire UL and DL data allocations.

**[0251]** In legacy LTE, a PDSCH is scheduled by a PDCCH. Specifically, the PDCCH may be transmitted in the first N (N=1, 2 or 3) OFDM symbols of a subframe, and the PDSCH scheduled by the PDCCH is transmitted in the same subframe.

**[0252]** Compared to legacy LTE, an MPDCCH and a PDSCH scheduled by the MPDCCH are transmitted/received in different subframes in MTC. For example, an MPDCCH with a last repetition in subframe #n schedules a PDSCH starting in subframe #n+2. The MPDCCH may be transmitted only once or repeatedly. A maximum repetition number of the MPDCCH is configured for the UE by RRC signaling from the BS. DCI carried on the MPDCCH provides information on how many times the MPDCCH is repeated so that the UE may determine when the PDSCH transmission starts. For example, if DCI in an MPDCCH starting in subframe #n includes information indicating that the MPDCCH is repeated 10 times, the MPDCCH may end in subframe #n+9 and the PDSCH may start in subframe #n+11. The DCI carried on the MPDCCH may include information about a repetition number for a physical data channel (e.g., PUSCH or PDSCH) scheduled by the DCI. The UE may transmit/receive the physical data channel repeatedly in the time domain according to the information about the repetition number of the physical data channel scheduled by the DCI. The PDSCH may be scheduled in the same or different narrowband as or from a narrowband in which the MPDCCH scheduling the PDSCH is transmitted. When the MPDCCH and the PDSCH are in different narrowbands, the MTC UE needs to retune to the frequency of the narrowband carrying the PDSCH before decoding the PDSCH. For UL scheduling, the same timing as in legacy LTE may be followed. For example, an MPDCCH ending in subframe #n may schedule a PUSCH transmission starting in subframe #n+4. If a physical channel is repeatedly transmitted, frequency hopping is supported between different MTC subbands by RF retuning. For example, if a PDSCH is repeatedly transmitted in 32 subframes, the PDSCH is transmitted in the first 16 subframes in a first MTC subband, and in the remaining 16 subframes in a second MTC subband. MTC may operate in half-duplex mode.

**[0253]** Narrowband-Internet of Things (NB-IoT)

**[0254]** NB-IoT may refer to a system for supporting low complexity, low power consumption, and efficient use of frequency resources by a system BW corresponding to one RB of a wireless communication system (e.g., the LTE system or the NR system). NB-IoT may operate in half-duplex mode. NB-IoT may be used as a communication scheme for implementing IoT by supporting, for example, an MTC device (or UE) in a cellular system.

**[0255]** In NB-IoT, each UE perceives one RB as one carrier. Therefore, an RB and a carrier as mentioned in relation to NB-IoT may be interpreted as the same meaning.

[0256] While a frame structure, physical channels, multi-carrier operations, and general signal transmission/reception in relation to NB-IoT will be described below in the context of the legacy LTE system, the description is also applicable to the next generation system (e.g., the NR system). Further, the description of NB-IoT may also be applied to MTC serving similar technical purposes (e.g., low power, low cost, and coverage enhancement).

#### [0257] NB-IoT Frame Structure and Physical Resources

[0258] A different NB-IoT frame structure may be configured according to a subcarrier spacing. For example, for a subcarrier spacing of 15 kHz, the NB-IoT frame structure may be identical to that of a legacy system (e.g., the LTE system). For example, a 10-ms NB-IoT frame may include 10 1-ms NB-IoT subframes each including two 0.5-ms slots. Each 0.5-ms NB-IoT slot may include 7 OFDM symbols. In another example, for a BWP or cell/carrier having a subcarrier spacing of 3.75 kHz, a 10-ms NB-IoT frame may include five 2-ms NB-IoT subframes each including 7 OFDM symbols and one guard period (GP). Further, a 2-ms NB-IoT subframe may be represented in NB-IoT slots or NB-IoT resource units (RUs). The NB-IoT frame structures are not limited to the subcarrier spacings of 15 kHz and 3.75 kHz, and NB-IoT for other subcarrier spacings (e.g., 30 kHz) may also be considered by changing time/frequency units.

[0259] NB-IoT DL physical resources may be configured based on physical resources of other wireless communication systems (e.g., the LTE system or the NR system) except that a system BW is limited to a predetermined number of RBs (e.g., one RB, that is, 180 kHz). For example, if the NB-IoT DL supports only the 15-kHz subcarrier spacing as described before, the NB-IoT DL physical resources may be configured as a resource area in which the resource grid illustrated in FIG. 1 is limited to one RB in the frequency domain.

[0260] Like the NB-IoT DL physical resources, NB-IoT UL resources may also be configured by limiting a system BW to one RB. In NB-IoT, the number of UL subcarriers  $N_{sc}^{UL}$  and a slot duration  $T_{slot}$  may be given as illustrated in [Table 3] below. In NB-IoT of the LTE system, the duration of one slot,  $T_{slot}$  is defined by 7 SC-FDMA symbols in the time domain.

TABLE 3

Subcarrier spacing	$N_{sc}^{UL}$	$T_{slot}$
$\Delta f = 3.75$ kHz	48	$6144 \cdot T_s$
$\Delta f = 15$ kHz	12	$15360 \cdot T_s$

[0261] In NB-IoT, RUs are used for mapping to REs of a PUSCH for NB-IoT (referred to as an NPUSCH). An RU may be defined by  $N_{sc}^{UL} \cdot N_{slot}^{UL}$  SC-FDMA symbols in the time domain by  $N_{sc}^{UL}$  consecutive subcarriers in the frequency domain. For example,  $N_{sc}^{RU}$  and  $N_{slot}^{UL}$  are listed in [Table 4] for a cell/carrier having an FDD frame structure and in [Table 5] for a cell/carrier having a TDD frame structure.

TABLE 4

NPUSCH format	$\Delta f$	$N_{sc}^{RU}$	$N_{slot}^{UL}$	$N_{ymb}^{UL}$
1	3.75 kHz	1	16	7
	15 kHz	1	16	
		3	8	
		6	4	
		12	2	
2	3.75 kHz	1	4	
	15 kHz	1	4	

TABLE 5

NPUSCH format	$\Delta f$	Support uplink-downlink configurations	$N_{sc}^{RU}$	$N_{slot}^{UL}$	$N_{ymb}^{UL}$
1	3.75 kHz	1, 4	1	16	7
	15 kHz	1, 2, 3, 4, 5	1	16	
			3	8	
			6	4	
			12	2	
2	3.75 kHz	1, 4	1	4	
	15 kHz	1, 2, 3, 4, 5	1	4	

#### [0262] NB-IoT Physical Channels

[0263] OFDMA may be adopted for NB-IoT DL based on the 15-kHz subcarrier spacing. Because OFDMA provides orthogonality between subcarriers, co-existence with other systems (e.g., the LTE system or the NR system) may be supported efficiently. The names of DL physical channels/signals of the NB-IoT system may be prefixed with “N (narrowband)” to be distinguished from their counterparts in the legacy system. For example, DL physical channels may be named NPBCH, NPDCCH, NPDSCH, and so on, and DL physical signals may be named NPSS, NSSS, narrowband reference signal (NRS), narrowband positioning reference signal (NPRS), narrowband wake up signal (NWUS), and so on. The DL channels, NPBCH, NPDCCH, NPDSCH, and so on may be repeatedly transmitted to enhance coverage in the NB-IoT system. Further, new defined DCI formats may be used in NB-IoT, such as DCI format NO, DCI format N1, and DCI format N2.

[0264] SC-FDMA may be applied with the 15-kHz or 3.75-kHz subcarrier spacing to NB-IoT UL. As described in relation to DL, the names of physical channels of the NB-IoT system may be prefixed with “N (narrowband)” to be distinguished from their counterparts in the legacy system. For example, UL channels may be named NPRACH, NPUSCH, and so on, and UL physical signals may be named NDMRS and so on. NPUSCHs may be classified into NPUSCH format 1 and NPUSCH format 2. For example, NPUSCH format 1 may be used to transmit (or deliver) an uplink shared channel (UL-SCH), and NPUSCH format 2 may be used for UCI transmission such as HARQ ACK signaling. A UL channel, NPRACH in the NB-IoT system may be repeatedly transmitted to enhance coverage. In this case, the repeated transmissions may be subjected to frequency hopping.

#### [0265] Multi-Carrier Operation in NB-IoT

[0266] NB-IoT may be implemented in multi-carrier mode. A multi-carrier operation may refer to using multiple carriers configured for different usages (i.e., multiple carriers of different types) in transmitting/receiving channels and/or signals between a BS and a UE.

[0267] In the multi-carrier mode in NB-IoT, carriers may be divided into anchor type carrier (i.e., anchor carrier or anchor PRB) and non-anchor type carrier (i.e., non-anchor carrier or non-anchor PRB).

[0268] The anchor carrier may refer to a carrier carrying an NPSS, an NSSS, and an NPBCH for initial access, and an NPDSCH for a system information block, N-SIB from the perspective of a BS. That is, a carrier for initial access is referred to as an anchor carrier, and the other carrier(s) is referred to as a non-anchor carrier in NB-IoT.

[0269] NB-IoT Signal Transmission/Reception Process

[0270] In NB-IoT, a signal is transmitted/received in a similar manner to the procedure illustrated in FIG. 2, except for features inherent to NB-IoT. Referring to FIG. 2, when an NB-IoT UE is powered on or enters a new cell, the NB-IoT UE may perform an initial cell search (S201). For the initial cell search, the NB-IoT UE may acquire synchronization with a BS and obtain information such as a cell ID by receiving an NPSS and an NSSS from the BS. Further, the NB-IoT UE may acquire broadcast information within a cell by receiving an NPBCH from the BS.

[0271] Upon completion of the initial cell search, the NB-IoT UE may acquire more specific system information by receiving an NPDCCH and receiving an NPDSCH corresponding to the NPDCCH (S202). In other words, the BS may transmit more specific system information to the NB-IoT UE which has completed the initial cell search by transmitting an NPDCCH and an NPDSCH corresponding to the NPDCCH.

[0272] The NB-IoT UE may then perform a RACH procedure to complete a connection setup with the BS (S203 to S206). For this purpose, the NB-IoT UE may transmit a preamble on an NPRACH to the BS (S203). As described before, it may be configured that the NPRACH is repeatedly transmitted based on frequency hopping, for coverage enhancement. In other words, the BS may (repeatedly) receive the preamble on the NPRACH from the NB-IoT UE. The NB-IoT UE may then receive an NPDCCH, and a RAR in response to the preamble on an NPDSCH corresponding to the NPDCCH from the BS (S204). In other words, the BS may transmit the NPDCCH, and the RAR in response to the preamble on the NPDSCH corresponding to the NPDCCH to the NB-IoT UE. Subsequently, the NB-IoT UE may transmit an NPUSCH to the BS, using scheduling information in the RAR (S205) and perform a contention resolution procedure by receiving an NPDCCH and an NPDSCH corresponding to the NPDCCH (S206).

[0273] After the above process, the NB-IoT UE may perform an NPDCCH/NPDSCH reception (S207) and an NPUSCH transmission (S208) in a general UL/DL signal transmission procedure. In other words, after the above process, the BS may perform an NPDCCH/NPDSCH transmission and an NPUSCH reception with the NB-IoT UE in the general UL/DL signal transmission procedure.

[0274] In NB-IoT, the NPBCH, the NPDCCH, and the NPDSCH may be transmitted repeatedly, for coverage enhancement. A UL-SCH (i.e., general UL data) and UCI may be delivered on the PUSCH in NB-IoT. It may be configured that the UL-SCH and the UCI are transmitted in different NPUSCH formats (e.g., NPUSCH format 1 and NPUSCH format 2).

[0275] In NB-IoT, UCI may generally be transmitted on an NPUSCH. Further, the UE may transmit the NPUSCH

periodically, aperiodically, or semi-persistently according to request/indication of the network (e.g., BS).

[0276] Wireless Communication Apparatus

[0277] FIG. 9 is a block diagram of an exemplary wireless communication system to which proposed methods of the present disclosure are applicable.

[0278] Referring to FIG. 9, the wireless communication system includes a first communication device 910 and/or a second communication device 920. The phrases “A and/or B” and “at least one of A or B” are may be interpreted as the same meaning. The first communication device 910 may be a BS, and the second communication device 920 may be a UE (or the first communication device 910 may be a UE, and the second communication device 920 may be a BS).

[0279] Each of the first communication device 910 and the second communication device 920 includes a processor 911 or 921, a memory 914 or 924, one or more Tx/Rx RF modules 915 or 925, a Tx processor 912 or 922, an Rx processor 913 or 923, and antennas 916 or 926. A Tx/Rx module may also be called a transceiver. The processor performs the afore-described functions, processes, and/or methods. More specifically, on DL (communication from the first communication device 910 to the second communication device 920), a higher-layer packet from a core network is provided to the processor 911. The processor 911 implements Layer 2 (i.e., L2) functionalities. On DL, the processor 911 is responsible for multiplexing between a logical channel and a transport channel, provisioning of a radio resource assignment to the second communication device 920, and signaling to the second communication device 920. The Tx processor 912 executes various signal processing functions of L1 (i.e., the physical layer). The signal processing functions facilitate forward error correction (FEC) of the second communication device 920, including coding and interleaving. An encoded and interleaved signal is modulated to complex-valued modulation symbols after scrambling and modulation. For the modulation, BPSK, QPSK, 16QAM, 64QAM, 256QAM, and so on are available according to channels. The complex-valued modulation symbols (hereinafter, referred to as modulation symbols) are divided into parallel streams. Each stream is mapped to OFDM subcarriers and multiplexed with an RS in the time and/or frequency domain. A physical channel is generated to carry a time-domain OFDM symbol stream by subjecting the mapped signals to IFFT. The OFDM symbol stream is spatially precoded to multiple spatial streams. Each spatial stream may be provided to a different antenna 916 through an individual Tx/Rx module (or transceiver) 915. Each Tx/Rx module 915 may upconvert the frequency of each spatial stream to an RF carrier, for transmission. In the second communication device 920, each Tx/Rx module (or transceiver) 925 receives a signal of the RF carrier through each antenna 926. Each Tx/Rx module 925 recovers the signal of the RF carrier to a baseband signal and provides the baseband signal to the Rx processor 923. The Rx processor 923 executes various signal processing functions of L1 (i.e., the physical layer). The Rx processor 923 may perform spatial processing on information to recover any spatial stream directed to the second communication device 920. If multiple spatial streams are directed to the second communication device 920, multiple Rx processors may combine the multiple spatial streams into a single OFDMA symbol stream. The Rx processor 923 converts an OFDM symbol stream being a time-domain signal to a frequency-domain

signal by FFT. The frequency-domain signal includes an individual OFDM symbol stream on each subcarrier of an OFDM signal. Modulation symbols and an RS on each subcarrier are recovered and demodulated by determining most likely signal constellation points transmitted by the first communication device 910. These soft decisions may be based on channel estimates. The soft decisions are decoded and deinterleaved to recover the original data and control signal transmitted on physical channels by the first communication device 910. The data and control signal are provided to the processor 921.

[0280] On UL (communication from the second communication device 920 to the first communication device 910), the first communication device 910 operates in a similar manner as described in relation to the receiver function of the second communication device 920. Each Tx/Rx module 925 receives a signal through an antenna 926. Each Tx/Rx module 925 provides an RF carrier and information to the Rx processor 923. The processor 921 may be related to the memory 924 storing a program code and data. The memory 924 may be referred to as a computer-readable medium.

[0281] Artificial Intelligence (AI)

[0282] Artificial intelligence is a field of studying AI or methodologies for creating AI, and machine learning is a field of defining various issues dealt with in the AI field and studying methodologies for addressing the various issues. Machine learning is defined as an algorithm that increases the performance of a certain operation through steady experiences for the operation.

[0283] An artificial neural network (ANN) is a model used in machine learning and may generically refer to a model having a problem-solving ability, which is composed of artificial neurons (nodes) forming a network via synaptic connections. The ANN may be defined by a connection pattern between neurons in different layers, a learning process for updating model parameters, and an activation function for generating an output value.

[0284] The ANN may include an input layer, an output layer, and optionally, one or more hidden layers. Each layer includes one or more neurons, and the ANN may include a synapse that links between neurons. In the ANN, each neuron may output the function value of the activation function, for the input of signals, weights, and deflections through the synapse.

[0285] Model parameters refer to parameters determined through learning and include a weight value of a synaptic connection and deflection of neurons. A hyperparameter means a parameter to be set in the machine learning algorithm before learning, and includes a learning rate, a repetition number, a mini batch size, and an initialization function.

[0286] The purpose of learning of the ANN may be to determine model parameters that minimize a loss function. The loss function may be used as an index to determine optimal model parameters in the learning process of the ANN.

[0287] Machine learning may be classified into supervised learning, unsupervised learning, and reinforcement learning according to learning methods.

[0288] Supervised learning may be a method of training an ANN in a state in which a label for training data is given, and the label may mean a correct answer (or result value) that the ANN should infer with respect to the input of training data to the ANN. Unsupervised learning may be a method of

training an ANN in a state in which a label for training data is not given. Reinforcement learning may be a learning method in which an agent defined in a certain environment is trained to select a behavior or a behavior sequence that maximizes cumulative compensation in each state.

[0289] Machine learning, which is implemented by a deep neural network (DNN) including a plurality of hidden layers among ANNs, is also referred to as deep learning, and deep learning is part of machine learning. The following description is given with the appreciation that machine learning includes deep learning.

[0290] <Robot>

[0291] A robot may refer to a machine that automatically processes or executes a given task by its own capabilities. Particularly, a robot equipped with a function of recognizing an environment and performing an operation based on its decision may be referred to as an intelligent robot.

[0292] Robots may be classified into industrial robots, medical robots, consumer robots, military robots, and so on according to their usages or application fields.

[0293] A robot may be provided with a driving unit including an actuator or a motor, and thus perform various physical operations such as moving robot joints. Further, a movable robot may include a wheel, a brake, a propeller, and the like in a driving unit, and thus travel on the ground or fly in the air through the driving unit.

[0294] <Self-Driving>

[0295] Self-driving refers to autonomous driving, and a self-driving vehicle refers to a vehicle that travels with no user manipulation or minimum user manipulation.

[0296] For example, self-driving may include a technology of maintaining a lane while driving, a technology of automatically adjusting a speed, such as adaptive cruise control, a technology of automatically traveling along a predetermined route, and a technology of automatically setting a route and traveling along the route when a destination is set.

[0297] Vehicles may include a vehicle having only an internal combustion engine, a hybrid vehicle having both an internal combustion engine and an electric motor, and an electric vehicle having only an electric motor, and may include not only an automobile but also a train, a motorcycle, and the like.

[0298] Herein, a self-driving vehicle may be regarded as a robot having a self-driving function.

[0299] <Extended Reality (XR)>

[0300] Extended reality is a generic term covering virtual reality (VR), augmented reality (AR), and mixed reality (MR). VR provides a real-world object and background only as a computer graphic (CG) image, AR provides a virtual CG image on a real object image, and MR is a computer graphic technology that mixes and combines virtual objects into the real world.

[0301] MR is similar to AR in that the real object and the virtual object are shown together. However, in AR, the virtual object is used as a complement to the real object, whereas in MR, the virtual object and the real object are handled equally.

[0302] XR may be applied to a head-mounted display (HMD), a head-up display (HUD), a portable phone, a tablet PC, a laptop computer, a desktop computer, a TV, a digital signage, and so on. A device to which XR is applied may be referred to as an XR device.

[0303] FIG. 10 illustrates an AI device 1000 according to an embodiment of the present disclosure.

[0304] The AI device 1000 illustrated in FIG. 10 may be configured as a stationary device or a mobile device, such as a TV, a projector, a portable phone, a smartphone, a desktop computer, a laptop computer, a digital broadcasting terminal, a personal digital assistant (PDA), a portable multimedia player (PMP), a navigation device, a tablet PC, a wearable device, a set-top box (STB), a digital multimedia broadcasting (DMB) receiver, a radio, a washing machine, a refrigerator, a digital signage, a robot, or a vehicle.

[0305] Referring to FIG. 10, the AI device 1000 may include a communication unit 1010, an input unit 1020, a learning processor 1030, a sensing unit 1040, an output unit 1050, a memory 1070, and a processor 1080.

[0306] The communication unit 1010 may transmit and receive data to and from an external device such as another AI device or an AI server by wired or wireless communication. For example, the communication unit 1010 may transmit and receive sensor information, a user input, a learning model, and a control signal to and from the external device.

[0307] Communication schemes used by the communication unit 1010 include global system for mobile communication (GSM), CDMA, LTE, 5G, wireless local area network (WLAN), wireless fidelity (Wi-Fi), Bluetooth™, radio frequency identification (RFID), infrared data association (IrDA), ZigBee, near field communication (NFC), and so on. Particularly, the 5G technology described before with reference to FIGS. 1 to 9 may also be applied.

[0308] The input unit 1020 may acquire various types of data. The input unit 1020 may include a camera for inputting a video signal, a microphone for receiving an audio signal, and a user input unit for receiving information from a user. The camera or the microphone may be treated as a sensor, and thus a signal acquired from the camera or the microphone may be referred to as sensing data or sensor information.

[0309] The input unit 1020 may acquire training data for model training and input data to be used to acquire an output by using a learning model. The input unit 1020 may acquire raw input data. In this case, the processor 1080 or the learning processor 1030 may extract an input feature by preprocessing the input data.

[0310] The learning processor 1030 may train a model composed of an ANN by using training data. The trained ANN may be referred to as a learning model. The learning model may be used to infer a result value for new input data, not training data, and the inferred value may be used as a basis for determination to perform a certain operation.

[0311] The learning processor 1030 may perform AI processing together with a learning processor of an AI server.

[0312] The learning processor 1030 may include a memory integrated or implemented in the AI device 1000. Alternatively, the learning processor 1030 may be implemented by using the memory 1070, an external memory directly connected to the AI device 1000, or a memory maintained in an external device.

[0313] The sensing unit 1040 may acquire at least one of internal information about the AI device 1000, ambient environment information about the AI device 1000, and user information by using various sensors.

[0314] The sensors included in the sensing unit 1040 may include a proximity sensor, an illumination sensor, an accel-

erator sensor, a magnetic sensor, a gyro sensor, an inertial sensor, a red, green, blue (RGB) sensor, an IR sensor, a fingerprint recognition sensor, an ultrasonic sensor, an optical sensor, a microphone, a light detection and ranging (LiDAR), and a radar.

[0315] The output unit 1050 may generate a visual, auditory, or haptic output.

[0316] Accordingly, the output unit 1050 may include a display unit for outputting visual information, a speaker for outputting auditory information, and a haptic module for outputting haptic information.

[0317] The memory 1070 may store data that supports various functions of the AI device 1000. For example, the memory 1070 may store input data acquired by the input unit 1020, training data, a learning model, a learning history, and so on.

[0318] The processor 1080 may determine at least one executable operation of the AI device 100 based on information determined or generated by a data analysis algorithm or a machine learning algorithm. The processor 1080 may control the components of the AI device 1000 to execute the determined operation.

[0319] To this end, the processor 1080 may request, search, receive, or utilize data of the learning processor 1030 or the memory 1070. The processor 1080 may control the components of the AI device 1000 to execute a predicted operation or an operation determined to be desirable among the at least one executable operation.

[0320] When the determined operation needs to be performed in conjunction with an external device, the processor 1080 may generate a control signal for controlling the external device and transmit the generated control signal to the external device.

[0321] The processor 1080 may acquire intention information with respect to a user input and determine the user's requirements based on the acquired intention information.

[0322] The processor 1080 may acquire the intention information corresponding to the user input by using at least one of a speech to text (STT) engine for converting a speech input into a text string or a natural language processing (NLP) engine for acquiring intention information of a natural language.

[0323] At least one of the STT engine or the NLP engine may be configured as an ANN, at least part of which is trained according to the machine learning algorithm. At least one of the STT engine or the NLP engine may be trained by the learning processor, a learning processor of the AI server, or distributed processing of the learning processors. For reference, specific components of the AI server are illustrated in FIG. 11.

[0324] The processor 1080 may collect history information including the operation contents of the AI device 1000 or the user's feedback on the operation and may store the collected history information in the memory 1070 or the learning processor 1030 or transmit the collected history information to the external device such as the AI server. The collected history information may be used to update the learning model.

[0325] The processor 1080 may control at least a part of the components of AI device 1000 so as to drive an application program stored in the memory 1070. Furthermore, the processor 1080 may operate two or more of the components included in the AI device 1000 in combination so as to drive the application program.

[0326] FIG. 11 illustrates an AI server 1120 according to an embodiment of the present disclosure.

[0327] Referring to FIG. 11, the AI server 1120 may refer to a device that trains an ANN by a machine learning algorithm or uses a trained ANN. The AI server 1120 may include a plurality of servers to perform distributed processing, or may be defined as a 5G network. The AI server 1120 may be included as part of the AI device 1100, and perform at least part of the AI processing.

[0328] The AI server 1120 may include a communication unit 1121, a memory 1123, a learning processor 1122, a processor 1126, and so on.

[0329] The communication unit 1121 may transmit and receive data to and from an external device such as the AI device 1100.

[0330] The memory 1123 may include a model storage 1124. The model storage 1124 may store a model (or an ANN 1125) which has been trained or is being trained through the learning processor 1122.

[0331] The learning processor 1122 may train the ANN 1125 by training data. The learning model may be used, while being loaded on the AI server 1120 of the ANN, or on an external device such as the AI device 1110.

[0332] The learning model may be implemented in hardware, software, or a combination of hardware and software. If all or part of the learning model is implemented in software, one or more instructions of the learning model may be stored in the memory 1123.

[0333] The processor 1126 may infer a result value for new input data by using the learning model and may generate a response or a control command based on the inferred result value.

[0334] FIG. 12 illustrates an AI system according to an embodiment of the present disclosure.

[0335] Referring to FIG. 12, in the AI system, at least one of an AI server 1260, a robot 1210, a self-driving vehicle 1220, an XR device 1230, a smartphone 1240, or a home appliance 1250 is connected to a cloud network 1200. The robot 1210, the self-driving vehicle 1220, the XR device 1230, the smartphone 1240, or the home appliance 1250, to which AI is applied, may be referred to as an AI device.

[0336] The cloud network 1200 may refer to a network that forms part of cloud computing infrastructure or exists in the cloud computing infrastructure. The cloud network 1200 may be configured by using a 3G network, a 4G or LTE network, or a 5G network.

[0337] That is, the devices 1210 to 1260 included in the AI system may be interconnected via the cloud network 1200. In particular, each of the devices 1210 to 1260 may communicate with each other directly or through a BS.

[0338] The AI server 1260 may include a server that performs AI processing and a server that performs computation on big data.

[0339] The AI server 1260 may be connected to at least one of the AI devices included in the AI system, that is, at least one of the robot 1210, the self-driving vehicle 1220, the XR device 1230, the smartphone 1240, or the home appliance 1250 via the cloud network 1200, and may assist at least part of AI processing of the connected AI devices 1210 to 1250.

[0340] The AI server 1260 may train the ANN according to the machine learning algorithm on behalf of the AI

devices 1210 to 1250, and may directly store the learning model or transmit the learning model to the AI devices 1210 to 1250.

[0341] The AI server 1260 may receive input data from the AI devices 1210 to 1250, infer a result value for received input data by using the learning model, generate a response or a control command based on the inferred result value, and transmit the response or the control command to the AI devices 1210 to 1250.

[0342] Alternatively, the AI devices 1210 to 1250 may infer the result value for the input data by directly using the learning model, and generate the response or the control command based on the inference result.

[0343] Hereinafter, various embodiments of the AI devices 1210 to 1250 to which the above-described technology is applied will be described. The AI devices 1210 to 1250 illustrated in FIG. 12 may be regarded as a specific embodiment of the AI device 1000 illustrated in FIG. 10.

[0344] <AI+XR>

[0345] The XR device 1230, to which AI is applied, may be configured as a HMD, a HUD provided in a vehicle, a TV, a portable phone, a smartphone, a computer, a wearable device, a home appliance, a digital signage, a vehicle, a fixed robot, a mobile robot, or the like.

[0346] The XR device 1230 may acquire information about a surrounding space or a real object by analyzing 3D point cloud data or image data acquired from various sensors or an external device and thus generating position data and attribute data for the 3D points, and may render an XR object to be output. For example, the XR device 1230 may output an XR object including additional information about a recognized object in correspondence with the recognized object.

[0347] The XR device 1230 may perform the above-described operations by using the learning model composed of at least one ANN. For example, the XR device 1230 may recognize a real object from 3D point cloud data or image data by using the learning model, and may provide information corresponding to the recognized real object. The learning model may be trained directly by the XR device 1230 or by the external device such as the AI server 1260.

[0348] While the XR device 1230 may operate by generating a result by directly using the learning model, the XR device 1230 may operate by transmitting sensor information to the external device such as the AI server 1260 and receiving the result.

[0349] <AI+Robot+XR>

[0350] The robot 1210, to which AI and XR are applied, may be implemented as a guide robot, a delivery robot, a cleaning robot, a wearable robot, an entertainment robot, a pet robot, an unmanned flying robot, a drone, or the like.

[0351] The robot 1210, to which XR is applied, may refer to a robot to be controlled/interact within an XR image. In this case, the robot 1210 may be distinguished from the XR device 1230 and interwork with the XR device 1230.

[0352] When the robot 1210 to be controlled/interact within an XR image acquires sensor information from sensors each including a camera, the robot 1210 or the XR device 1230 may generate an XR image based on the sensor information, and the XR device 1230 may output the generated XR image. The robot 1210 may operate based on the control signal received through the XR device 1230 or based on the user's interaction.

[0353] For example, the user may check an XR image corresponding to a view of the robot 1210 interworking remotely through an external device such as the XR device 1210, adjust a self-driving route of the robot 1210 through interaction, control the operation or driving of the robot 1210, or check information about an ambient object around the robot 1210.

[0354] <AI+Self-Driving+XR>

[0355] The self-driving vehicle 1220, to which AI and XR are applied, may be implemented as a mobile robot, a vehicle, an unmanned flying vehicle, or the like.

[0356] The self-driving driving vehicle 1220, to which XR is applied, may refer to a self-driving vehicle provided with a means for providing an XR image or a self-driving vehicle to be controlled/interact within an XR image. Particularly, the self-driving vehicle 1220 to be controlled/interact within an XR image may be distinguished from the XR device 1230 and interwork with the XR device 1230.

[0357] The self-driving vehicle 1220 provided with the means for providing an XR image may acquire sensor information from the sensors each including a camera and output the generated XR image based on the acquired sensor information. For example, the self-driving vehicle 1220 may include an HUD to output an XR image, thereby providing a passenger with an XR object corresponding to a real object or an object on the screen.

[0358] When the XR object is output to the HUD, at least part of the XR object may be output to be overlaid on an actual object to which the passenger's gaze is directed. When the XR object is output to a display provided in the self-driving vehicle 1220, at least part of the XR object may be output to be overlaid on the object within the screen. For example, the self-driving vehicle 1220 may output XR objects corresponding to objects such as a lane, another vehicle, a traffic light, a traffic sign, a two-wheeled vehicle, a pedestrian, a building, and so on.

[0359] When the self-driving vehicle 1220 to be controlled/interact within an XR image acquires sensor information from the sensors each including a camera, the self-driving vehicle 1220 or the XR device 1230 may generate the XR image based on the sensor information, and the XR device 1230 may output the generated XR image. The self-driving vehicle 1220 may operate based on a control signal received through an external device such as the XR device 1230 or based on the user's interaction.

[0360] VR, AR, and MR technologies of the present disclosure are applicable to various devices, particularly, for example, a HMD, a HUD attached to a vehicle, a portable phone, a tablet PC, a laptop computer, a desktop computer, a TV, and a signage. The VR, AR, and MR technologies may also be applicable to a device equipped with a flexible or rollable display.

[0361] The above-described VR, AR, and MR technologies may be implemented based on CG and distinguished by the ratios of a CG image in an image viewed by the user.

[0362] That is, VR provides a real object or background only in a CG image, whereas AR overlays a virtual CG image on an image of a real object.

[0363] MR is similar to AR in that virtual objects are mixed and combined with a real world. However, a real object and a virtual object created as a CG image are distinctive from each other and the virtual object is used to complement the real object in AR, whereas a virtual object

and a real object are handled equally in MR. More specifically, for example, a hologram service is an MR representation.

[0364] These days, VR, AR, and MR are collectively called XR without distinction among them. Therefore, embodiments of the present disclosure are applicable to all of VR, AR, MR, and XR.

[0365] For example, wired/wireless communication, input interfacing, output interfacing, and computing devices are available as hardware (HW)-related element techniques applied to VR, AR, MR, and XR. Further, tracking and matching, speech recognition, interaction and user interfacing, location-based service, search, and AI are available as software (SW)-related element techniques.

[0366] Particularly, the embodiments of the present disclosure are intended to address at least one of the issues of communication with another device, efficient memory use, data throughput decrease caused by inconvenient user experience/user interface (UX/UI), video, sound, motion sickness, or other issues.

[0367] FIG. 13 is a block diagram illustrating an XR device according to embodiments of the present disclosure. The XR device 1300 includes a camera 1310, a display 1320, a sensor 1330, a processor 1340, a memory 1350, and a communication module 1360. Obviously, one or more of the modules may be deleted or modified, and one or more modules may be added to the modules, when needed, without departing from the scope and spirit of the present disclosure.

[0368] The communication module 1360 may communicate with an external device or a server, wiredly or wirelessly. The communication module 1360 may use, for example, Wi-Fi, Bluetooth, or the like, for short-range wireless communication, and for example, a 3GPP communication standard for long-range wireless communication. LTE is a technology beyond 3GPP TS 36.xxx Release 8. Specifically, LTE beyond 3GPP TS 36.xxx Release 10 is referred to as LTE-A, and LTE beyond 3GPP TS 36.xxx Release 13 is referred to as LTE-A pro. 3GPP 5G refers to a technology beyond TS 36.xxx Release 15 and a technology beyond TS 38.XXX Release 15. Specifically, the technology beyond TS 38.xxx Release 15 is referred to as 3GPP NR, and the technology beyond TS 36.xxx Release 15 is referred to as enhanced LTE. "xxx" represents the number of a technical specification. LTE/NR may be collectively referred to as a 3GPP system.

[0369] The camera 1310 may capture an ambient environment of the XR device 1300 and convert the captured image to an electric signal. The image, which has been captured and converted to an electric signal by the camera 1310, may be stored in the memory 1350 and then displayed on the display 1320 through the processor 1340. Further, the image may be displayed on the display 1320 by the processor 1340, without being stored in the memory 1350. Further, the camera 110 may have a field of view (FoV). The FoV is, for example, an area in which a real object around the camera 1310 may be detected. The camera 1310 may detect only a real object within the FoV. When a real object is located within the FoV of the camera 1310, the XR device 1300 may display an AR object corresponding to the real object. Further, the camera 1310 may detect an angle between the camera 1310 and the real object.

[0370] The sensor 1330 may include at least one sensor. For example, the sensor 1330 includes a sensing means such

as a gravity sensor, a geomagnetic sensor, a motion sensor, a gyro sensor, an accelerator sensor, an inclination sensor, a brightness sensor, an altitude sensor, an olfactory sensor, a temperature sensor, a depth sensor, a pressure sensor, a bending sensor, an audio sensor, a video sensor, a global positioning system (GPS) sensor, and a touch sensor. Further, although the display **1320** may be of a fixed type, the display **1320** may be configured as a liquid crystal display (LCD), an organic light emitting diode (OLED) display, an electroluminescent display (ELD), or a micro LED (M-LED) display, to have flexibility. Herein, the sensor **1330** is designed to detect a bending degree of the display **1320** configured as the afore-described LCD, OLED display, ELD, or M-LED display.

[0371] The memory **1350** is equipped with a function of storing all or a part of result values obtained by wired/wireless communication with an external device or a service as well as a function of storing an image captured by the camera **1310**. Particularly, considering the trend toward increased communication data traffic (e.g., in a 5G communication environment), efficient memory management is required. In this regard, a description will be given below with reference to FIG. **14**.

[0372] FIG. **14** is a detailed block diagram of the memory **1350** illustrated in FIG. **13**. With reference to FIG. **14**, a swap-out process between a random access memory (RAM) and a flash memory according to an embodiment of the present disclosure will be described.

[0373] When swapping out AR/VR page data from a RAM **1410** to a flash memory **1420**, a controller **1430** may swap out only one of two or more AR/VR page data of the same contents among AR/VR page data to be swapped out to the flash memory **1420**.

[0374] That is, the controller **1430** may calculate an identifier (e.g., a hash function) that identifies each of the contents of the AR/VR page data to be swapped out, and determine that two or more AR/VR page data having the same identifier among the calculated identifiers contain the same contents. Accordingly, the problem that the lifetime of an ARNR device including the flash memory **1420** as well as the lifetime of the flash memory **1420** is reduced because unnecessary AR/VR page data is stored in the flash memory **1420** may be overcome.

[0375] The operations of the controller **1430** may be implemented in software or hardware without departing from the scope of the present disclosure. More specifically, the memory illustrated in FIG. **14** is included in a HMD, a vehicle, a portable phone, a tablet PC, a laptop computer, a desktop computer, a TV, a signage, or the like, and executes a swap function.

[0376] A device according to embodiments of the present disclosure may process 3D point cloud data to provide various services such as VR, AR, MR, XR, and self-driving to a user.

[0377] A sensor collecting 3D point cloud data may be any of, for example, a LiDAR, a red, green, blue depth (RGB-D), and a 3D laser scanner. The sensor may be mounted inside or outside of a HMD, a vehicle, a portable phone, a tablet PC, a laptop computer, a desktop computer, a TV, a signage, or the like.

[0378] FIG. **15** illustrates a point cloud data processing system.

[0379] Referring to FIG. **15**, a point cloud processing system **1500** includes a transmission device which acquires,

encodes, and transmits point cloud data, and a reception device which acquires point cloud data by receiving and decoding video data. As illustrated in FIG. **15**, point cloud data according to embodiments of the present disclosure may be acquired by capturing, synthesizing, or generating the point cloud data (**S1510**). During the acquisition, data (e.g., a polygon file format or standard triangle format (PLY) file) of 3D positions (x, y, z)/attributes (color, reflectance, transparency, and so on) of points may be generated. For a video of multiple frames, one or more files may be acquired. Point cloud data-related metadata (e.g., metadata related to capturing) may be generated during the capturing. The transmission device or encoder according to embodiments of the present disclosure may encode the point cloud data by video-based point cloud compression (V-PCC) or geometry-based point cloud compression (G-PCC), and output one or more video streams (**S1520**). V-PCC is a scheme of compressing point cloud data based on a 2D video codec such as high efficiency video coding (HEVC) or versatile video coding (VVC), G-PCC is a scheme of encoding point cloud data separately into two streams: geometry and attribute. The geometry stream may be generated by reconstructing and encoding position information about points, and the attribute stream may be generated by reconstructing and encoding attribute information (e.g., color) related to each point. In V-PCC, despite compatibility with a 2D video, much data is required to recover V-PCC-processed data (e.g., geometry video, attribute video, occupancy map video, and auxiliary information), compared to G-PCC, thereby causing a long latency in providing a service. One or more output bit streams may be encapsulated along with related metadata in the form of a file (e.g., a file format such as ISOBMFF) and transmitted over a network or through a digital storage medium (**S1530**).

[0380] The device or processor according to embodiments of the present disclosure may acquire one or more bit streams and related metadata by decapsulating the received video data, and recover 3D point cloud data by decoding the acquired bit streams in V-PCC or G-PCC (**S1540**). A renderer may render the decoded point cloud data and provide content suitable for VR/AR/MR/service to the user on a display (**S1550**).

[0381] As illustrated in FIG. **15**, the device or processor according to embodiments of the present disclosure may perform a feedback process of transmitting various pieces of feedback information acquired during the rendering/display to the transmission device or to the decoding process (**S1560**). The feedback information according to embodiments of the present disclosure may include head orientation information, viewport information indicating an area that the user is viewing, and so on. Because the user interacts with a service (or content) provider through the feedback process, the device according to embodiments of the present disclosure may provide a higher data processing speed by using the afore-described V-PCC or G-PCC scheme or may enable clear video construction as well as provide various services in consideration of high user convenience.

[0382] FIG. **16** is a block diagram of an XR device **1600** including a learning processor. Compared to FIG. **13**, only a learning processor **1670** is added, and thus a redundant description is avoided because FIG. **13** may be referred to for the other components.

[0383] Referring to FIG. **16**, the XR device **1600** may be loaded with a learning model. The learning model may be

implemented in hardware, software, or a combination of hardware and software. If the whole or part of the learning model is implemented in software, one or more instructions that form the learning model may be stored in a memory **1650**.

[0384] According to embodiments of the present disclosure, a learning processor **1670** may be coupled communicably to a processor **1640**, and repeatedly train a model including ANNs by using training data. An ANN is an information processing system in which multiple neurons are linked in layers, modeling an operation principle of biological neurons and links between neurons. An ANN is a statistical learning algorithm inspired by a neural network (particularly the brain in the central nervous system of an animal) in machine learning and cognitive science. Machine learning is one field of AI, in which the ability of learning without an explicit program is granted to a computer. Machine learning is a technology of studying and constructing a system for learning, predicting, and improving its capability based on empirical data, and an algorithm for the system. Therefore, according to embodiments of the present disclosure, the learning processor **1670** may infer a result value from new input data by determining optimized model parameters of an ANN. Therefore, the learning processor **1670** may analyze a device use pattern of a user based on device use history information about the user. Further, the learning processor **1670** may be configured to receive, classify, store, and output information to be used for data mining, data analysis, intelligent decision, and a machine learning algorithm and technique.

[0385] According to embodiments of the present disclosure, the processor **1640** may determine or predict at least one executable operation of the device based on data analyzed or generated by the learning processor **1670**. Further, the processor **1640** may request, search, receive, or use data of the learning processor **1670**, and control the XR device **1600** to perform a predicted operation or an operation determined to be desirable among the at least one executable operation. According to embodiments of the present disclosure, the processor **1640** may execute various functions of realizing intelligent emulation (i.e., knowledge-based system, reasoning system, and knowledge acquisition system). The various functions may be applied to an adaptation system, a machine learning system, and various types of systems including an ANN (e.g., a fuzzy logic system). That is, the processor **1640** may predict a user's device use pattern based on data of a use pattern analyzed by the learning processor **1670**, and control the XR device **1600** to provide a more suitable XR service to the UE. Herein, the XR service includes at least one of the AR service, the VR service, or the MR service.

[0386] FIG. 17 illustrates a process of providing an XR service by the XR service **1600** of the present disclosure illustrated in FIG. 16.

[0387] According to embodiments of the present disclosure, the processor **1670** may store device use history information about a user in the memory **1650** (S1710). The device use history information may include information about the name, category, and contents of content provided to the user, information about a time at which a device has been used, information about a place in which the device has been used, time information, and information about use of an application installed in the device.

[0388] According to embodiments of the present disclosure, the learning processor **1670** may acquire device use pattern information about the user by analyzing the device use history information (S1720). For example, when the XR device **1600** provides specific content A to the user, the learning processor **1670** may learn information about a pattern of the device used by the user using the corresponding terminal by combining specific information about content A (e.g., information about the ages of users that generally use content A, information about the contents of content A, and content information similar to content A), and information about the time points, places, and number of times in which the user using the corresponding terminal has consumed content A.

[0389] According to embodiments of the present disclosure, the processor **1640** may acquire the user device pattern information generated based on the information learned by the learning processor **1670**, and generate device use pattern prediction information (S1730). Further, when the user is not using the device **1600**, if the processor **1640** determines that the user is located in a place where the user has frequently used the device **1600**, or it is almost time for the user to usually use the device **1600**, the processor **1640** may indicate the device **1600** to operate. In this case, the device according to embodiments of the present disclosure may provide AR content based on the user pattern prediction information (S1740).

[0390] When the user is using the device **1600**, the processor **1640** may check information about content currently provided to the user, and generate device use pattern prediction information about the user in relation to the content (e.g., when the user requests other related content or additional data related to the current content). Further, the processor **1640** may provide AR content based on the device use pattern prediction information by indicating the device **1600** to operate (S1740). The AR content according to embodiments of the present disclosure may include an advertisement, navigation information, danger information, and so on.

[0391] FIG. 18 illustrates the outer appearances of an XR device and a robot.

[0392] Component modules of an XR device **1800** according to an embodiment of the present disclosure have been described before with reference to the previous drawings, and thus a redundant description is not provided herein.

[0393] The outer appearance of a robot **1810** illustrated in FIG. 18 is merely an example, and the robot **1810** may be implemented to have various outer appearances according to the present disclosure. For example, the robot **1810** illustrated in FIG. 18 may be a drone, a cleaner, a cook robot, a wearable robot, or the like. Particularly, each component of the robot **1810** may be disposed at a different position such as up, down, left, right, back, or forth according to the shape of the robot **1810**.

[0394] The robot **1810** may be provided, on the exterior thereof, with various sensors to identify ambient objects. Further, to provide specific information to a user, the robot **1810** may be provided with an interface unit **1811** on top or the rear surface **1812** thereof.

[0395] To sense movement of the robot **1810** and an ambient object, and control the robot **1810**, a robot control module **1850** is mounted inside the robot **1810**. The robot control module **1850** may be implemented as a software module or a hardware chip with the software module imple-

mented therein. The robot control module **1850** may include a deep learner **1851**, a sensing information processor **1852**, a movement path generator **1853**, and a communication module **1854**.

[0396] The sensing information processor **1852** collects and processes information sensed by various types of sensors (e.g., a LiDAR sensor, an IR sensor, an ultrasonic sensor, a depth sensor, an image sensor, and a microphone) arranged in the robot **1810**.

[0397] The deep learner **1851** may receive information processed by the sensing information processor **1851** or accumulative information stored during movement of the robot **1810**, and output a result required for the robot **1810** to determine an ambient situation, process information, or generate a moving path.

[0398] The moving path generator **1852** may calculate a moving path of the robot **1810** by using the data calculated by the deep learner **1851** or the data processed by the sensing information processor **1852**.

[0399] Because each of the XR device **1800** and the robot **1810** is provided with a communication module, the XR device **1800** and the robot **1810** may transmit and receive data by short-range wireless communication such as Wi-Fi or Bluetooth, or 5G long-range wireless communication. A technique of controlling the robot **1810** by using the XR device **1800** will be described below with reference to FIG. 19.

[0400] FIG. 19 is a flowchart illustrating a process of controlling a robot by using an XR device.

[0401] The XR device and the robot are connected communicably to a 5G network (**S1901**). Obviously, the XR device and the robot may transmit and receive data by any other short-range or long-range communication technology without departing from the scope of the present disclosure.

[0402] The robot captures an image/video of the surroundings of the robot by means of at least one camera installed on the interior or exterior of the robot (**S1902**) and transmits the captured image/video to the XR device (**S1903**). The XR device displays the captured image/video (**S1904**) and transmits a command for controlling the robot to the robot (**S1905**). The command may be input manually by a user of the XR device or automatically generated by AI without departing from the scope of the disclosure.

[0403] The robot executes a function corresponding to the command received in step **S1905** (**S1906**) and transmits a result value to the XR device (**S1907**). The result value may be a general indicator indicating whether data has been successfully processed or not, a current captured image, or specific data in which the XR device is considered. The specific data is designed to change, for example, according to the state of the XR device. If a display of the XR device is in an off state, a command for turning on the display of the XR device is included in the result value in step **S1907**. Therefore, when an emergency situation occurs around the robot, even though the display of the remote XR device is turned off, a notification message may be transmitted.

[0404] AR/VR content is displayed according to the result value received in step **S1907** (**S1908**).

[0405] According to another embodiment of the present disclosure, the XR device may display position information about the robot by using a GPS module attached to the robot.

[0406] The XR device **1300** described with reference to FIG. 13 may be connected to a vehicle that provides a self-driving service in a manner that allows wired/wireless

communication, or may be mounted on the vehicle that provides the self-driving service. Accordingly, various services including AR/VR may be provided even in the vehicle that provides the self-driving service.

[0407] FIG. 20 illustrates a vehicle that provides a self-driving service.

[0408] According to embodiments of the present disclosure, a vehicle **2010** may include a car, a train, and a motor bike as transportation means traveling on a road or a railway. According to embodiments of the present disclosure, the vehicle **2010** may include all of an internal combustion engine vehicle provided with an engine as a power source, a hybrid vehicle provided with an engine and an electric motor as a power source, and an electric vehicle provided with an electric motor as a power source.

[0409] According to embodiments of the present disclosure, the vehicle **2010** may include the following components in order to control operations of the vehicle **2010**: a user interface device, an object detection device, a communication device, a driving maneuver device, a main electronic control unit (ECU), a drive control device, a self-driving device, a sensing unit, and a position data generation device.

[0410] Each of the user interface device, the object detection device, the communication device, the driving maneuver device, the main ECU, the drive control device, the self-driving device, the sensing unit, and the position data generation device may generate an electric signal, and be implemented as an electronic device that exchanges electric signals.

[0411] The user interface device may receive a user input and provide information generated from the vehicle **2010** to a user in the form of a UI or UX. The user interface device may include an input/output (I/O) device and a user monitoring device. The object detection device may detect the presence or absence of an object outside of the vehicle **2010**, and generate information about the object. The object detection device may include at least one of, for example, a camera, a LiDAR, an IR sensor, or an ultrasonic sensor. The camera may generate information about an object outside of the vehicle **2010**. The camera may include one or more lenses, one or more image sensors, and one or more processors for generating object information. The camera may acquire information about the position, distance, or relative speed of an object by various image processing algorithms. Further, the camera may be mounted at a position where the camera may secure an FoV in the vehicle **2010**, to capture an image of the surroundings of the vehicle **1020**, and may be used to provide an AR/VR-based service. The LiDAR may generate information about an object outside of the vehicle **2010**. The LiDAR may include a light transmitter, a light receiver, and at least one processor which is electrically coupled to the light transmitter and the light receiver, processes a received signal, and generates data about an object based on the processed signal.

[0412] The communication device may exchange signals with a device (e.g., infrastructure such as a server or a broadcasting station), another vehicle, or a terminal) outside of the vehicle **2010**. The driving maneuver device is a device that receives a user input for driving. In manual mode, the vehicle **2010** may travel based on a signal provided by the driving maneuver device. The driving maneuver device may include a steering input device (e.g., a steering wheel), an

acceleration input device (e.g., an accelerator pedal), and a brake input device (e.g., a brake pedal).

[0413] The sensing unit may sense a state of the vehicle 2010 and generate state information. The position data generation device may generate position data of the vehicle 2010. The position data generation device may include at least one of a GPS or a differential global positioning system (DGPS). The position data generation device may generate position data of the vehicle 2010 based on a signal generated from at least one of the GPS or the DGPS. The main ECU may provide overall control to at least one electronic device provided in the vehicle 2010, and the drive control device may electrically control a vehicle drive device in the vehicle 2010.

[0414] The self-driving device may generate a path for the self-driving service based on data acquired from the object detection device, the sensing unit, the position data generation device, and so on. The self-driving device may generate a driving plan for driving along the generated path, and generate a signal for controlling movement of the vehicle according to the driving plan. The signal generated from the self-driving device is transmitted to the drive control device, and thus the drive control device may control the vehicle drive device in the vehicle 2010.

[0415] As illustrated in FIG. 20, the vehicle 2010 that provides the self-driving service is connected to an XR device 2000 in a manner that allows wired/wireless communication. The XR device 2000 may include a processor 2001 and a memory 2002. While not shown, the XR device 2000 of FIG. 20 may further include the components of the XR device 1300 described before with reference to FIG. 13.

[0416] If the XR device 2000 is connected to the vehicle 2010 in a manner that allows wired/wireless communication. The XR device 2000 may receive/process AR/VR service-related content data that may be provided along with the self-driving service, and transmit the received/processed AR/VR service-related content data to the vehicle 2010. Further, when the XR device 2000 is mounted on the vehicle 2010, the XR device 2000 may receive/process AR/VR service-related content data according to a user input signal received through the user interface device and provide the received/processed AR/VR service-related content data to the user. In this case, the processor 2001 may receive/process the AR/VR service-related content data based on data acquired from the object detection device, the sensing unit, the position data generation device, the self-driving device, and so on. According to embodiments of the present disclosure, the AR/VR service-related content data may include entertainment content, weather information, and so on which are not related to the self-driving service as well as information related to the self-driving service such as driving information, path information for the self-driving service, driving maneuver information, vehicle state information, and object information.

[0417] FIG. 21 illustrates a process of providing an AR/VR service during a self-driving service.

[0418] According to embodiments of the present disclosure, a vehicle or a user interface device may receive a user input signal (S2110). According to embodiments of the present disclosure, the user input signal may include a signal indicating a self-driving service. According to embodiments of the present disclosure, the self-driving service may include a full self-driving service and a general self-driving service. The full self-driving service refers to perfect self-

driving of a vehicle to a destination without a user's manual driving, whereas the general self-driving service refers to driving a vehicle to a destination through a user's manual driving and self-driving in combination.

[0419] It may be determined whether the user input signal according to embodiments of the present disclosure corresponds to the full self-driving service (S2120). When it is determined that the user input signal corresponds to the full self-driving service, the vehicle according to embodiments of the present disclosure may provide the full self-driving service (S2130). Because the full self-driving service does not need the user's manipulation, the vehicle according to embodiments of the present disclosure may provide VR service-related content to the user through a window of the vehicle, a side mirror of the vehicle, an HMD, or a smartphone (S2130). The VR service-related content according to embodiments of the present disclosure may be content related to full self-driving (e.g., navigation information, driving information, and external object information), and may also be content which is not related to full self-driving according to user selection (e.g., weather information, a distance image, a nature image, and a voice call image).

[0420] If it is determined that the user input signal does not correspond to the full self-driving service, the vehicle according to embodiments of the present disclosure may provide the general self-driving service (S2140). Because the FoV of the user should be secured for the user's manual driving in the general self-driving service, the vehicle according to embodiments of the present disclosure may provide AR service-related content to the user through a window of the vehicle, a side mirror of the vehicle, an HMD, or a smartphone (S2140).

[0421] The AR service-related content according to embodiments of the present disclosure may be content related to full self-driving (e.g., navigation information, driving information, and external object information), and may also be content which is not related to self-driving according to user selection (e.g., weather information, a distance image, a nature image, and a voice call image).

[0422] FIG. 22 is a conceptual diagram illustrating an exemplary method for implementing the XR device using an HMD type according to an embodiment of the present disclosure. The above-mentioned embodiments may also be implemented in HMD types shown in FIG. 22.

[0423] The HMD-type XR device 2200a shown in FIG. 22 may include a communication unit 2210, a control unit 2220, a memory unit 2230, an input/output (I/O) unit 2240a, a sensor unit 2240b, a power-supply unit 2240c, etc. Specifically, the communication unit 2210 embedded in the XR device 2200a may communicate with a mobile terminal 2200b by wire or wirelessly. The mobile terminal may be a smart phone or a tablet personal computer (PC).

[0424] FIG. 23 is a conceptual diagram illustrating an exemplary method for implementing an XR device using AR glasses according to an embodiment of the present disclosure. The above-mentioned embodiments may also be implemented in AR glass types shown in FIG. 23.

[0425] Referring to FIG. 23, the AR glasses may include a frame, a control unit 2300, and an optical display unit 2330.

[0426] Although the frame may be formed in a shape of glasses worn on the face of the user 2320 as shown in FIG. 23, the scope of the present disclosure is not limited thereto,

and it should be noted that the frame may also be formed in a shape of goggles worn in close contact with the face of the user **2320**.

[0427] The frame may include a front frame **2310** and first and second side frames.

[0428] The front frame **2310** may include at least one opening, and may extend in a first horizontal direction (i.e., an X-axis direction). The first and second side frames may extend in the second horizontal direction (i.e., a Y-axis direction) perpendicular to the front frame **2310**, and may extend in parallel to each other.

[0429] The control unit **2300** may generate an image to be viewed by the user **2320** or may generate the resultant image formed by successive images. The control unit **2300** may include an image source configured to create and generate images, a plurality of lenses configured to diffuse and converge light generated from the image source, and the like. The images generated by the control unit **2300** may be transferred to the optical display unit **300** through a guide lens **P2300** disposed between the control unit **2300** and the optical display unit **2330**.

[0430] The control unit **2300** may be fixed to any one of the first and second side frames. For example, the control unit **2300** may be fixed to the inside or outside of any one of the side frames, or may be embedded in and integrated with any one of the side frames.

[0431] The optical display unit **2330** may be formed of a translucent material, so that the optical display unit **2330** can display images created by the control unit **2300** for recognition of the user **2320** and can allow the user to view the external environment through the opening.

[0432] The optical display unit **2330** may be inserted into and fixed to the opening contained in the front frame **2310**, or may be located at the rear surface (interposed between the opening and the user **2320**) of the opening so that the optical display unit **2330** may be fixed to the front frame **2310**. For example, the optical display unit **2330** may be located at the rear surface of the opening, and may be fixed to the front frame **2310** as an example.

[0433] Referring to the XR device shown in FIG. **23**, when image light are incident upon an incident region **S1** of the optical display unit **2330** by the control unit **2300**, image light may be transmitted to an emission region **S2** of the optical display unit **2330** through the optical display unit **2330**, images created by the control unit **2300** can be displayed for recognition of the user **2320**.

[0434] Accordingly, the user **2320** may view the external environment through the opening of the frame, and at the same time may view the images created by the control unit **2300**.

[0435] FIG. **24** illustrates an XR device implemented as a mobile terminal in accordance with the present disclosure. The aforementioned various embodiments may be implemented by a mobile terminal type shown in FIG. **24**. The mobile terminal may be a cellular phone, a tablet PC, etc.

[0436] In an example of FIG. **24**, virtual objects **2401** such as timer, thermometer, and pot indicator are displayed to be overlapped on at least one real object of a kitchen space displayed on an XR device **2400** implemented as a mobile terminal. In the present disclosure, the real object will be referred to as a smart device.

[0437] In one embodiment of the present disclosure, the XR device of FIGS. **22** to **24** executes AR based assistant (hereinafter, AR assistant) application (or AR assistant app),

displays a state of a first real object of a real space displayed on a display module by being overlapped on at least one virtual object, and controls the state of the first real object through one or more second real objects connected with each other by a wire/wireless mode.

[0438] In one embodiment of the present disclosure, the first real object and one or more second real objects controlling the state of the first real object are previously connected with each other by a wire/wireless mode.

[0439] In one embodiment of the present disclosure, when the state of the first real object is abnormal, the first real object is controlled to be a normal state through one or more second real objects.

[0440] In one embodiment of the present disclosure, when the state of the first real object is abnormal, the first real object is guided using at least one virtual object to be controlled to be a normal state through one or more second real objects.

[0441] In one embodiment of the present disclosure, the real space is a space acquired by illuminating a camera of the XR device. The real space may be a kitchen, a living room, a bedroom, a bathroom, etc. at home, or may be a space not home, such as office.

[0442] In the present disclosure, the first real object and one or more second real objects are objects actually existing in the real space, and the virtual object is an object that does not exist in the real space.

[0443] In order that one or more second real objects control the state of the first real object, at least one of the aforementioned 5G communication technology field, the robot technology field, the autonomous driving technology field and the AI technology field may be applied to the present disclosure.

[0444] FIG. **25** is a schematic block view illustrating an XR device for controlling a state of a first real object using one or more second real objects in accordance with one embodiment of the present disclosure.

[0445] The XR device **2400** of FIG. **25** may include a controller **2410**, a power supply module **2420**, a display module **2430**, a camera module **2440**, an input module **2450**, a memory **2460**, a communication module **2470**, a sensing module **2480**, an output module **2485**, a learning processor **2490**, and an AR assistant module **2495**. Some elements may be deleted from, modified from and added to the XR device of FIG. **25** in accordance with the need of the person skilled in the art within the scope of the present disclosure.

[0446] Description of the blocks in FIG. **25**, which are the same as those of FIG. **13** or **16**, will be replaced with the description of FIG. **13** or **16**.

[0447] The controller **2410** controls the overall operation of the corresponding XR device.

[0448] The power supply module **2420** includes a battery, and the battery may be built in the XR device **2400**, or may detachably be configured outside the XR device **2400**. The power supply module **2420** supplies a power required for each element of the XR device.

[0449] The power supply module **2420** of the XR device may be connected with a charger by a cable and then charged through a charging port (not shown), or may be connected with a charger by a wireless mode and then charged.

[0450] The controller **2410** uses the memory **2460** for execution and storage of an application program and storage of an image which is captured. That is, the controller **2410** may provide a user with suitable information or function by

processing signal, data and information, which are input or output, or may provide a user with suitable information or function by driving the application program stored in the memory **2460**. In one embodiment, an AR assistant application program according to the present disclosure is stored in the memory **2460** by downloading of the user when or after the XR device is released. In the present disclosure, for convenience of description, the AR assistant application program is also referred to as an AR assistant application or an AR assistant app.

[0451] Also, if the user executes the AR assistant application, the controller **2410** may control the operation of one or more second real objects for controlling a first real object.

[0452] At least some of the respective elements of the XR device may be operated in cooperation with each other to implement the operation, control or control method according to various embodiments which will be described below. Also, the operation, control or control method of the XR device may be implemented on the XR device by driving of at least one application program stored in the memory **2460**.

[0453] The display module **2430** may be formed in a mutual layer structure or one body with a touch sensor, whereby a touch screen may be implemented.

[0454] The display module **2430** may display an image of a real space, which is captured using one or more cameras.

[0455] In one embodiment, the display module **2430** displays a state of the first real object by overlaying one or more virtual objects **2401** in a specific position in a real space under the control of the controller **2410** or the AR assistant module **2495**.

[0456] The camera module **2440** may be comprised of one or more cameras to capture an image of the real space, and the image which is captured may be at least one of a still image and a moving image. The image captured by the camera module **2440** may be displayed on the display module **2430** in accordance with a purpose of use for capturing the image or a user command, may be stored in the memory **2460**, or may be transmitted to an external server through the communication module **2470**. Each camera of the camera module **2440** may have a viewing angle. At this time, the viewing angle means an area where a real view (or real object) located near the camera module **2440**. The camera module **2440** may detect only a real object located within the viewing angle.

[0457] The input module **2450** may include a microphone, a touch input means, etc. to receive a touch input or voice input of the user. As an example, the touch input means may be a virtual key, soft key or visual key displayed on the touch screen through software processing, or may be a touch key arranged in a portion other than the touch screen. Meanwhile, the virtual key or the visual key may be displayed on the touch screen while having various shapes, and for example, may be configured by graphic, text, icon, video or their combination.

[0458] In one embodiment, a touch input or voice input, which is input through the input module **2450**, is analyzed by the controller **2410** and then processed by a control command of a user. The input module **2450** may include a microphone, a touch key, a mechanical key, etc.

[0459] The memory **2460** may be comprised of a volatile and/or non-volatile memory, and may store a command or data for supporting various functions of the XR device. That is, the memory **2460** may store a plurality of application programs or applications driven by the XR device, data for

the operation of the XR device, and command languages. At least some of the application programs may be downloaded from the external server through wireless communication in the communication module **2470**. Also, the memory **2460** may store the image captured through the camera module **2440**. Also, the memory **2460** may store data for supporting various functions of the XR device. For example, the memory **2460** may store user experiences such as input data, learning data, learning model, learning history, etc. acquired by the input module **2450**.

[0460] The AR assistant application program according to the present disclosure may be built in the XR device **2400** from the time when the XR device **2400** is released, or may be downloaded by a request of a user after the XR device **2400** is released, and then may be installed in the XR device **2400**.

[0461] The communication module **2470** transmits and receives data to and from the external server and Internet for the present disclosure through short-range wireless communication or remote-range wireless communication. Examples of communication technologies used in the communication module **2470** include Global System for Mobile (GSM) communication, Code Division Multi Access (CDMA), Long Term Evolution (LTE), Wireless LAN (WLAN), Wireless-Fidelity (Wi-Fi), Bluetooth™, Radio Frequency Identification (RFID), Infrared Data Association (IrDA), ZigBee, and Near Field Communication (NFC). Particularly, the aforementioned 5G technology described in FIGS. **1** to **9** may be applied to the communication technology used in the communication module **2470**.

[0462] The sensing module **2480** may include one or more sensors for sensing at least one of information in the XR device **2400**, peripheral environment information surrounding the XR device **2400** and user information. For example, the sensing module **2480** may include at least one of a proximity sensor, an illumination sensor, a touch sensor, an acceleration sensor, a magnetic sensor, a G-sensor, a gyroscope sensor, a motion sensor, an RGB sensor, an infrared (IR) sensor, a finger scan sensor, an ultrasonic sensor, an optical sensor, a battery gauge, an environment sensor (for example, barometer, hygrometer, thermometer, radioactivity sensor, heat detector, gas sensor, etc.) and a chemical sensor (for example, electronic nose, healthcare sensor, biometric sensor, etc.). Meanwhile, the XR device disclosed in this specification may use information sensed by at least two or more of the sensors in combination. Particularly, the sensing module **2480** may acquire a state of a first real object of the real space displayed on the display module **2430** by using the various sensors.

[0463] The output module **2485** is intended to generate the output related to auditory or tactile sense, and may include at least one of a sound output module, a haptic module, and an optical output module. Also, the output module **2485** may output a guide for controlling the state of the first real object according to the present disclosure under the control of the controller **2410** or the AR assistant module **2495** as audio.

[0464] The learning processor **2490** records and learns user experiences. The learning processor **2490** may perform AI processing together with a learning processor of an AI server. In the present disclosure, examples of the user experience may include a first real object with high frequency selected by a user, a first real object which is selected most recently, etc. Details of recording and learning of the

user experiences in the learning processor **2490** will be understood with reference to the description of FIGS. **10** to **12**.

[**0465**] The AR assistant module **2495** controls related elements to allow one or more second real objects to control the state of the first real object of the real space displayed on the display module **2430** if the user executes the AR assistant app according to the present disclosure. In the present disclosure, the role of the AR assistant module **2495** may be performed by the controller **2410**. In one embodiment of the present disclosure, the AR assistant module **2495** may perform its role.

[**0466**] Each element of FIG. **25** for controlling the state of the real object of the real space according to the present disclosure may mean software or hardware such as field-programmable gate array (FPGA) or application-specific integrated circuit (ASIC). However, each element is not limited to software or hardware, and may be configured in a storage medium capable of being addressed by each element, or may be configured to be executed by one or more processors. A function provided in the elements may be implemented by more segmented elements, or may be implemented by one element for performing a specific function in combination with a plurality of elements.

[**0467**] FIG. **26** illustrates one embodiment for controlling a state of a pot by using one or more second real objects such as an induction range and a fan provided in a hood when a first real object according to the present disclosure is a pot. In more exact, a cooking state in the pot rather than the state of the pot by controlling a temperature of an induction range or a speed of a fan of a hood. However, for convenience of description in the present disclosure, the control will be referred to as the control of the state of the pot. In other words, adjustment (or control) of the state of the pot means controlling the cooking state in the pot.

[**0468**] In FIG. **26**, a user may display additional information of a first real object of a real space displayed in the XR device implemented as a smart phone or smart glasses as one or more virtual objects. In this case, the virtual objects may be graphic images or text types.

[**0469**] For example, when supposing that cooking is performed on the induction range by using two pots, additional information such as a current temperature and a timer per pot may be displayed as the virtual object. At this time, in one embodiment, the AR assistant module **2495** detects pots which are cooking, based on the image acquired from the camera module **2440**, and detects a current temperature of each pot based on the sensing information (e.g., sensing information of the infrared sensor) of the sensing module **2480**. In one embodiment, a timer or stopwatch added to each pot is directly input by the user. Since a cooking time may be varied even for the same food depending on a user, material type, material amount, etc., in one embodiment, a timer or stopwatch for indicating cooking time of each food is set by an input of a user. The timer or stopwatch may be input through the input module in the form of text, or may be input through a user voice, etc.

[**0470**] FIGS. **26** and **27** illustrate that additional information of one or more real objects of a real space displayed on an XR device is displayed as text type virtual objects.

[**0471**] In FIGS. **26** and **27**, in one embodiment, if a temperature of a pot, which is detected by the XR device **2400**, exceeds a preset normal range, the AR assistant module **2495** controls the temperature of the pot to be within

a normal range by increasing a speed of a fan of a hood connected by a wire or wireless mode or lowering a temperature of an induction range. In this case, the speed of the fan may manually be controlled but is automatically controlled by the AR assistant module **2495** in one embodiment of the present disclosure. Also, the temperature of the induction range may manually be controlled but is automatically controlled by the AR assistant module **2495** in one embodiment of the present disclosure. At this time, the pot will be referred to as a first real object, and the fan or induction range used to lower the temperature of the pot will be referred to as a second real object. In this case, the second real object such as the fan provided in the hood and the induction range may previously set by a user, or the second real object which may control the first real object at the current state may be set by the user through the input module **2450** in accordance with a guide of the XR device **2400**. In one embodiment, the second real object such as the fan and the induction range is remotely operated through the communication module **2470**.

[**0472**] Also, an abnormal state of the pot on the induction range may be sensed through smoke or smell sensed by the sensing module **2480**.

[**0473**] In one embodiment of the present disclosure, if the temperature of the pot exceeds 100° C., the pot is regarded as an abnormal state, and the induction range and/or the fan of the hood is controlled to lower the temperature of the corresponding pot.

[**0474**] In FIG. **26**, since the current temperature of a first pot **2610** of two pots is 102° C., in one embodiment, the temperature of the corresponding induction range is lowered to lower the temperature of the first pot **2610**. In addition, the speed of the fan provided in the hood may be increased to lower the temperature of the first pot **2610**. If the speed of the fan provided in the hood is increased, the temperature of the second pot **2620** is lowered. In FIG. **27**, since the current temperature of a first pot **2710** of two pots is 104° C., in one embodiment, the temperature of the corresponding induction range is lowered to lower the temperature of the first pot **2710**. In addition, the speed of the fan provided in the hood may be increased to lower the temperature of the first pot **2710**. If the speed of the fan provided in the hood is increased, the temperature of the second pot **2720** is lowered.

[**0475**] As shown in FIGS. **26** and **27**, the example of controlling the temperature of the pot on the induction range is applicable to one or more pots. Particularly, when two types of foods are simultaneously cooked using two or more pots, since a user's attention is limited to a specific portion, the user may miss a cooking state of a specific pot even though a timer or stopwatch is set. Therefore, the AR assistant app of the present disclosure is more effective when two or more kinds of foods are cooked. In this case, in one embodiment, each pot may be checked by the sensing module **2480** of the XR device using an object detection function, and the XR device provides object detection information to the AR assistant module **2495**. In one embodiment, if the pots have the same shape, the object detection information includes relative position information (e.g., left, right, and upper) of each pot.

[**0476**] FIG. **28** is a flow chart illustrating one embodiment of an AR assistant method when cooking is performed using a pot on an induction range as shown in FIGS. **26** and **27**.

[0477] If a user executes an AR assistant app from the XR device 2400, a real space acquired by the camera module 2440 is displayed on the display module 2430 (S2811). At this time, if the user powers on the induction range on which the first real object, that is, the pot is arranged for cooking (S2812), the induction range recognizes the pot through the XR device 2400 (S2813). Afterwards, the user may set a timer for cooking of the corresponding pot in the XR device 2400 before cooking or in the middle of cooking. In this case, the AR assistant module 2495 displays the timer by overlapping the timer with a format of a virtual object on a specific position of the corresponding pot (S2814). Also, the AR assistant module 2495 senses a temperature of the pot through the sensing module 2480, and displays the sensed temperature of the pot by overlapping the temperature of the pot with a format of a virtual object on the specific position of the corresponding pot. In this case, the timer and the temperature of the pot are displayed so as not to be overlapped with each other.

[0478] The AR assistant module 2495 continues to monitor the temperature of the pot through the sensing module 2480 (S2815).

[0479] If the temperature of the pot exceeds a normal range, for example, if the temperature of the pot reaches 101° C. or more, the AR assistant module 2495 determines that the pot is an abnormal state, and transmits a command for lowering the temperature of the induction range and a command for enhancing the speed of the fan provided in the hood to the induction range and/or the fan through the communication module 2470.

[0480] For example, the AR assistant module 2495 displays a guide message such as 'lower the temperature of the induction range and increase the speed of the fan' through the display module 2430 to allow a user to recognize the abnormal state of the pot and also allow the user to recognize that the temperature of the induction range is lowered and the speed of the fan is increased to lower the temperature of the pot (S2816). At this time, the guide message may be displayed in the form of pop-up, or may be guided as a voice through the output module 2485. Also, in one embodiment, if a basic value of the guide message is set to 'yes' and a user does not input any selection or command, the temperature of the induction range is lowered automatically after a specific time (for example, 2 seconds). That is, if the user selects 'yes' (S2817) or 2 seconds pass without selection of the user, the temperature of the induction range is automatically lowered.

[0481] In another embodiment of the present disclosure, when a guide message such as 'lower the temperature of the induction range and increase the speed of the fan' is displayed, if the user selects 'no', no operation for lowering the temperature of the induction range and increasing the speed of the fan is performed. Also, in the present disclosure, the AR assistant module 2495 may allow the user to select one of the temperature of the induction range and the speed of the fan.

[0482] In FIG. 28, it is assumed that the user has selected 'yes'. In this case, the AR assistant module 2495 lowers the temperature of the induction range and increases the speed of the fan provided in the hood through the communication module 2470 (S2818). Then, if the temperature of the pot reaches a normal state (for example, 100° C.), each of the temperature of the induction range and the back fan of the hood are restored to a preset initial state (S2819).

[0483] FIG. 29 illustrates one embodiment for handling a diaper by using one or more second real objects such as robot and air cleaner when the first real object according to the present disclosure is a diaper worn by a specific person (for example, baby).

[0484] That is, if poop is found from the diaper 2910 worn by a baby, the AR assistant module 2495 in which the AR assistant application is being executed may control the operation of the robot 2920 to bring baby supplies, and may control the operation of the air cleaner 2930 to clean the air near the baby. The baby supplies may be wet tissue, clean diaper, etc. In this case, a poop state of the baby may directly be checked by a user through the XR device 240, or may directly be checked by a poop smell or the baby's reaction. Alternatively, if a sensor capable of checking a poop is included in the diaper, the poop state may automatically be checked by the AR assistant module 2495. Although one embodiment of the present disclosure is described based on the poop, one embodiment may be described based on a pee.

[0485] For example, if the poop is checked from the diaper 2910 worn by the baby, the AR assistant module 2495 transfers a current position to the robot 2920 of the real space and transfers a command to bring baby supplies to the current position. In this case, in one embodiment, the command to bring the current position and baby supplies is transmitted to the robot 2920 through the communication module 2470. For another example, the command to bring the current position and baby supplies may be transferred to the robot 2920 of a remote place through a user voice. In the embodiment of FIG. 29, the robot 2920 is in a room 2 and the baby is in a living room. In this case, the current position or destination is a living room, and the robot 2920 moves to the living room together with baby supplies.

[0486] Also, the AR assistant module 2495 may clean the air near the baby by controlling the operation of the air cleaner 2930. For example, the AR assistant module 2495 may power on an air cleaning function of the air cleaner 2930. Also, the AR assistant module 2495 may weakly spray some air freshener through the user's checking. In this case, an interface for receiving a user command is provided through text or voice.

[0487] In addition, as shown in FIG. 30, a command to fill water in a baby bathtub 2940 may be transferred. FIG. 30 illustrates that the baby bathtub 2940 is in a bathroom as one embodiment but is only exemplary, and the baby bathtub 2940 may be in another place. In one embodiment, the command to fill water in the bathtub 2940 includes a desired water temperature and a water height. In one embodiment of the present disclosure, the water temperature is 37° C., and the water height is 60%. In this case, since the water height and the water temperature may be varied depending on a concerned party who desires to use the water, the present disclosure is not limited to the aforementioned embodiment.

[0488] In one embodiment, in FIG. 30, after the bathtub 2940 is filled with the water to reach 60%, the water temperature is maintained at 37° C.

[0489] In FIGS. 29 and 30, each of the robot 2920, the air cleaner 2930, and the baby bathtub 2930 will be referred to as a smart device.

[0490] Although one embodiment of FIGS. 29 and 30 is described based on a diaper worn by a baby, the diaper may be worn by an adult due to dementia, or may be worn by a pet such as a dog.

[0491] In this way, the user may be concentrated on only handling of the diaper containing a poop.

[0492] FIG. 31 illustrates one embodiment for handling broken glass pieces in a living room using one or more second real objects such as robot and robot cleaner when a first real object according to the present disclosure is the living room where the broken glass pieces exist.

[0493] That is, if it is checked that there are broken glass pieces such as glass bottle or cup in the living room, the AR assistant module 2495 in which the AR assistant application is being executed may control the operation of the robot 3120 to bring cleaning tools, or may control the operation of the robot cleaner 3130 to remove the glass pieces. In this case, the cleaning tools may be a broom, a wet tissue, etc.

[0494] For example, if it is checked that there are broken glass pieces 3110 such as glass bottle or cup in the living room, the AR assistant module 2495 transfers the current position to the robot 3120 of the real space and transfers a command to bring cleaning tools to the current position. In this case, in one embodiment, the command to bring the current position and the cleaning tools is transmitted to the robot 3120 through the communication module 2470. In another embodiment, the command to bring the current position and the cleaning tools may be transferred to the robot 3120 of the remote place through the user voice. In the embodiment of FIG. 31, the robot 3120 is in the kitchen, and the current position, that is, a destination to which the robot will move is the living room.

[0495] Also, the AR assistant module 2495 may control the operation of the robot cleaner 3130 to allow the robot cleaner 3130 to clean the broken glass pieces. Even at the time, in one embodiment, the AR assistant module 2495 transmits the current position and the cleaning command to the robot cleaner 3130 through the communication module 2470.

[0496] In another embodiment, the AR assistant module 2495 may transfer the current position and the cleaning command to the robot cleaner 3130 of the remote place through the user voice. In the embodiment of FIG. 31, the robot cleaner 3130 is on standby for cleaning, and moves to a corresponding position of the living room where the broken glass pieces exist, so as to clean the corresponding position.

[0497] In FIG. 31, each of the robot 3120 and the robot cleaner 3130 will be referred to as a smart device.

[0498] Although one embodiment of FIG. 31 is described based on broken glass pieces, one embodiment of FIG. 31 may be described based on other objects, which need to be cleaned, for example, paper pieces. Also, the real space may be any place of the living room, the room, and the kitchen.

[0499] Also, states of real objects which are not described in the present disclosure may be controlled or handled using another real object by applying the aforementioned procedures. Therefore, the present disclosure is not limited to the aforementioned embodiments.

[0500] Although the embodiments of the present disclosure have been described in the present specification with reference to the accompanying drawings, it will be apparent to those skilled in the art that the present disclosure can be embodied in other specific forms without departing from the spirit and essential characteristics of the disclosure. The scope of the present disclosure should be determined by reasonable interpretation of the appended claims and all modifications which come within the equivalent scope of the

disclosure are included in the scope according to claims of the present disclosure. Also, the modified embodiments are therefore to be construed in all aspects as illustrative and not restrictive.

What is claimed is:

1. A method of controlling an extended reality (XR) device, the method comprising:

executing an augmented reality (AR) assistant application in the XR device by a user;

displaying a real space, which includes a first real object, on a screen of the XR device;

detecting a state of the first real object;

displaying at least one virtual object for identifying the state of the first real object on the real space of the screen by overlapping the at least one virtual object on the real space; and

controlling the state of the first real object by using one or more second real objects of the real space.

2. The method of claim 1, further comprising displaying at least one virtual object on the real space of the screen by overlapping the at least one virtual object on the real space, so as to provide a guide for controlling the state of the first real object.

3. The method of claim 1, wherein, if the first real object is a pot which is cooking, the one or more second real objects include at least one of an induction range of the pot and a fan provided in a hood.

4. The method of claim 3, wherein the controlling the first real object includes controlling a temperature of the pot by using at least one of a temperature control of the induction range and a speed control of the fan.

5. The method of claim 3, wherein, if the temperature of the pot exceeds 100° C., the temperature of the pot is controlled by lowering a temperature of the induction range or increasing a speed of the fan.

6. The method of claim 1, wherein, if the first real object is a diaper containing a poop, the one or more second real objects include at least one of a robot and an air cleaner.

7. The method of claim 6, wherein the controlling the first real object includes transmitting a current position of a real space where the diaper containing the poop exists and a command to bring poop disposable goods to the current position to the robot, and transmitting a command to power on an air cleaning function to the air cleaner.

8. The method of claim 6, wherein the one or more second real objects further include a bathtub, and wherein the controlling the first real object includes transmitting a command to fill water in the bathtub, the command including a temperature of the water to be filled in the bathtub and height information of the water.

9. The method of claim 1, wherein, if the first real object corresponds to broken glass pieces existing in a specific position of a real space, the one or more second real objects include at least one of a robot and a robot cleaner.

10. The method of claim 9, wherein the controlling the first real object includes transmitting a current position of a real space where the broken glass pieces exists and a command to bring cleaning tools to the current position to the robot, and transmitting a command to clean the broken glass pieces to the robot cleaner.

11. An extended reality (XR) device comprising:

an AR assistant module executing an augmented reality (AR) assistant application if the AR assistant application is selected by a user;

a camera module acquiring a real space that includes a first real object; and  
a display module displaying the real space that includes the first real object,

wherein the AR assistant module detects a state of the first real object, displays at least one virtual object for identifying the state of the first real object on the real space of the display module by overlapping the at least one virtual object on the real space, and controls the state of the first real object by using one or more second real objects of the real space.

**12.** The XR device of claim **11**, wherein the AR assistant module displays at least one virtual object on the real space of the display module by overlapping the at least one virtual object on the real space, so as to provide a guide for controlling the state of the first real object.

**13.** The XR device of claim **11**, wherein, if the first real object is a pot which is cooking, the one or more second real objects include at least one of an induction range of the pot and a fan provided in a hood.

**14.** The XR device of claim **13**, wherein the AR assistant module controls a temperature of the pot by using at least one of a temperature control of the induction range and a speed control of the fan.

**15.** The XR device of claim **13**, wherein, if the temperature of the pot exceeds 100° C., the AR assistant module controls the temperature of the pot by lowering a temperature of the induction range or increasing a speed of the fan.

**16.** The XR device of claim **11**, wherein, if the first real object is a diaper containing a poop, the one or more second real objects include at least one of a robot and an air cleaner.

**17.** The XR device of claim **16**, wherein the AR assistant module transmits a current position of a real space where the diaper containing the poop exists and a command to bring poop disposable goods to the current position to the robot, and transmits a command to power on an air cleaning function to the air cleaner.

**18.** The XR device of claim **16**, wherein the one or more second real objects further include a bathtub, and wherein the AR assistant module transmits a command to fill water in the bathtub, the command including a temperature of the water to be filled in the bathtub and height information of the water.

**19.** The XR device of claim **11**, wherein, if the first real object corresponds to broken glass pieces existing in a specific position of a real space, the one or more second real objects include at least one of a robot and a robot cleaner.

**20.** The XR device of claim **19**, wherein the AR assistant module transmits a current position of a real space where the broken glass pieces exists and a command to bring cleaning tools to the current position to the robot, and transmits a command to clean the broken glass pieces to the robot cleaner.

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